#### **ASSIGNMENT-4**

Assignment Date	16, November 2022
Student name	Arunkumar
Student Roll no	41181910612
Maximum marks	2 marks

# **QUESTION:**

Write Code and connections in wokwi for ultrasonic sensor. whatever distance is less than 100 cms send "Alert" to ibm cloud aand display in device recent events

# **CODING:**

```
//Pins
const int TRIG_PIN = 7;
const int ECHO_PIN = 8;

//Anything over 400 cm (23200 us pulse) is "out of range"
const unsigned int MAX_DIST = 23200;

void setup() {
```

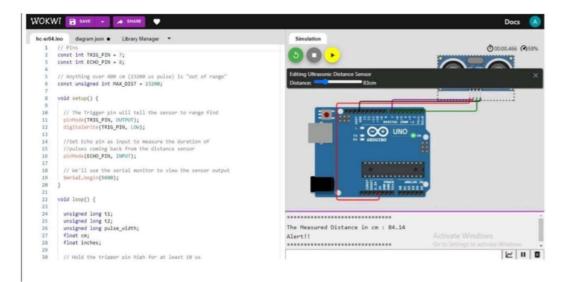
```
// The Trigger pin will tell the sensor to range find
Pin Mode(TRIG_PIN, OUTPUT);
digital Write(TRIG PIN, LOW);
//Set Echo pin as input to measure the duration of
//pulses coming back from the distance sensor
pinMode(ECHO_PIN, INPUT );
// We'll use the serial monitor to view the sensor output
Serial.begin(9600);
}
void loop() {
unsigned long t1;
unsigned long t2;
unsigned long pulse width;
float cm;
float inches;
// Hold the trigger pin high for at least 10 us
```

```
digitalWrite(TRIG PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG PIN, LOW);
// Wait for pulse on echo pin
while (digitalRead(ECHO PIN)==0);
// Measure how long the echo pin was held high (pulse width)
// Note: the micros() counter will overflow after-70 min
t1 = micros();
 while (digitalRead(ECHO PIN) == 1);
 t2 = micros();
 pulse width = t2-t1;
// Calculate distance in centimeters and inches. The constants
//are found in the datasheet, and calculated from the assumed speed
// of sound in air at sea level (- 340m/s)
cm=pulse Width / 58;
inches = pulse width/148.0;
// Print out results
```

```
if (pulse_width >MAX _ DIST ){
Serial.println("Out of range");
} else {
Serial.println("*********************************);
Serial.print("The Measured Distance in cm: ");
Serial.println(cm);
if( cm < 100 ){
   //while(true){
    Serial.println("Alert!!");
   //}
Serial.print("**********************************);
}
//wait at least 1000ms before next measurement
Delay(1000);
```

### **OUTPUT:**

#### 1.If the distance is less than 100 cms, it alerts.



Activate Windows

### 2.If the distance is more than 100 cms, it won't alert

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         const int ECHO_PIN = 8;
         // Anything over 400 cm (23200 us pulse) is "out of range"
         const unsigned int MAX_DIST = 23200;
           // The Trigger pin will tell the sensor to range find
           pinMode(TRIG_PIN, OUTPUT);
digitalWrite(TRIG_PIN, LOW);
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           //Set Echo pin as input to measure the duration of 
//pulses coming back from the distance sensor
           pinFlode(ECHO_PIN, INPUT);
            // We'll use the serial monitor to view the sensor output
           Serial.begin(9600);
    20
21
                                                                                                                       iii.iii .....
         void loop() {
    23
24
            unsigned long t1;
            unsigned long t2;
                                                                                           The Measured Distance in cm : 227.10
            unsigned long pulse_width; float cm;
                                                                                                                                               Activate Windows
            float inches;
```

### 3.Simulation and code execution

