# ASSIGNMENT-4 DISTANCE DETECTION USING ULTRASONIC SENSOR

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Maximum Marks	2 Marks

## Question1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

## WOKWI LINK:

https://wokwi.com/projects/305566932847821378

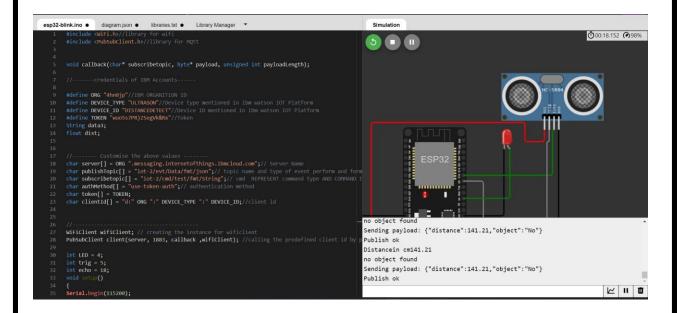
#### CODE:

```
esp32-blink.ino •
                  diagram.json •
                                   libraries.txt ●
                                                  Library Manager
       pinMode(trig,OUTPUT);
       pinMode(echo,INPUT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void loop()// Recursive Function
        digitalWrite(trig,LOW);
         digitalWrite(trig,HIGH);
         delayMicroseconds(10);
         digitalWrite(trig,LOW);
         float dur = pulseIn(echo,HIGH);
         float dist = (dur * 0.0343)/2;
         Serial.print ("Distancein cm");
         Serial.println(dist);
         PublishData(dist);
         delay(1000);
         if (!client.loop()) {
         mqttconnect();
       void PublishData(float dist) {
         mqttconnect();//function call for connecting to ibm
```

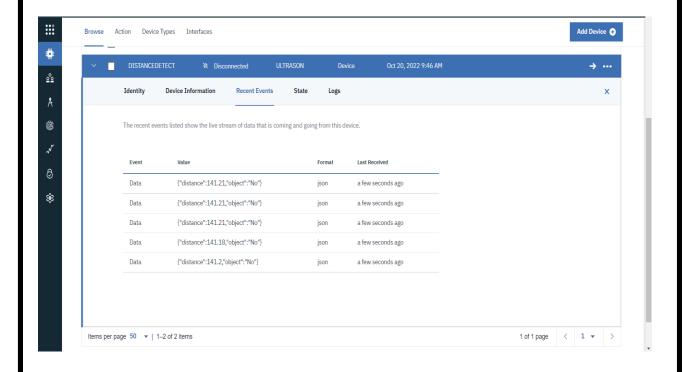
```
esp32-blink.ino •
                   diagram.json •
                                   libraries.txt ●
                                                  Library Manager
         WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
         while (WiFi.status() != WL_CONNECTED) {
           delay(500);
           Serial.print(".");
         Serial.println("");
         Serial.println("WiFi connected");
         Serial.println("IP address: ");
         Serial.println(WiFi.localIP());
       void initManagedDevice() {
         if (client.subscribe(subscribetopic)) {
           Serial.println((subscribetopic));
           Serial.println("subscribe to cmd OK");
           Serial.println("subscribe to cmd FAILED");
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
         Serial.print("callback invoked for topic: ");
 148
         Serial.println(subscribetopic);
         for (int i = 0; i < payloadLength; i++) {</pre>
           data3 += (char)payload[i];
```

## **OUTPUT:**

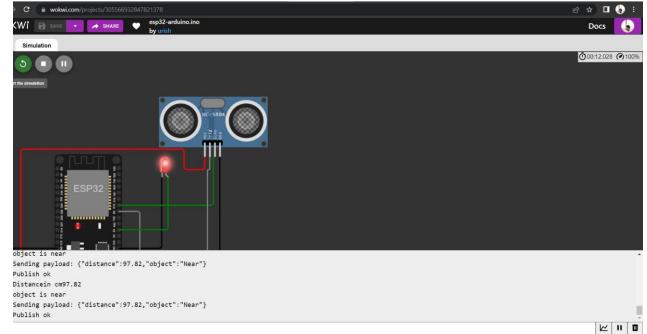
When the object is far from ultrasonic sensor



Data send to the IBM cloud device when the object is far



# when object is near to the ultrasonic sensor



# Data sent to the IBM Cloud Device when the object is near

