SPRINT - 2

DATE	03 November 2022
TEAM ID	PNT2022TMID01891
PROJECT NAME	Smart Farmer - IoT Enabled
	Smart Farming Application

FINAL SENSOR CONNECTION WITH ARDUINO PROGRAM FOR OUR PROJECT

Description:

This Smart Irrigation System is used to help farmers in the irrigation process. The System provides data on the parameters which can be used to monitor the condition of the field to maintain and protect the crops. The parameters like temperature, soil moisture, the water level in the field, etc., can be accessed through the system. The sensors in the system monitor the parameters and provide them to the farmer to take the necessary measures.

Program:

```
#include <Adafruit_LiquidCrystal.h> //Includes the library for LCD Display
#include <Wire.h> //Includes the library for connections
#include <Servo.h> //Includes the library for Servo Motor

Servo s; int
```

e = 4; int t
= 5; int r =
12; int b =
11; int g =
10; int sec

= 0;

```
int Sensor = 0;
int soil = 0; int
motorPin = 9;
Adafruit_LiquidCrystal lcd(0);
void
setup()
{
  Wire.begin();
  pinMode(A0, INPUT);
                                   // Temperature Sensor
  pinMode(A1, INPUT);
                                   // Soil Moisture Sensor
  pinMode(t, OUTPUT);
                                   // Ultra sonic Trigger
  pinMode(e, INPUT);
                                   // Ultra sonic Echo
  pinMode(b, OUTPUT);
                                   // GREEN light for LED
  pinMode(g, OUTPUT);
                                   // BLUE light for LED
  pinMode(r, OUTPUT);
                                   // RED light for LED
  pinMode(motorPin, OUTPUT);
                                   // DC motor
  s.attach(3);
                                   // Servo Motor
```

```
delayMicroseconds(10);
  digitalWrite(t,
                    LOW);
                               int
  duration = pulseIn(e, HIGH);
  return duration * 0.034 / 2;
void loop()
  // Soil Moisture:
  Sensor = analogRead(A1);
// Reads data from Soil Moisture
                                  sensor
  soil = map(Sensor, 0, 1023, 0, 117);
// Low analog value indicates HIGH moisture level and High analog value
indicates LOW moisture level
  // data = map(analogValue,fromLOW,fromHIGH,toLOW,toHIGH)
  Serial.print("Soil Moisture value:");
```

Serial.println(soil);

//'data = 0' indicates total wetness and 'data = 100' indicates total dryness

// Temperature:

double a = analogRead(A0); // Reads data from Temperature sensor double t = (((a / 1024) * 5) - 0.5) * 100;

Serial.print("Temperature value:"); //Temperature value in Celsius
Serial.println(t);

// Ultrasonic sensor:

float distance = readDistanceCM(); //Reads data from Ultrasonic sensor
Serial.print("Measured distance: ");

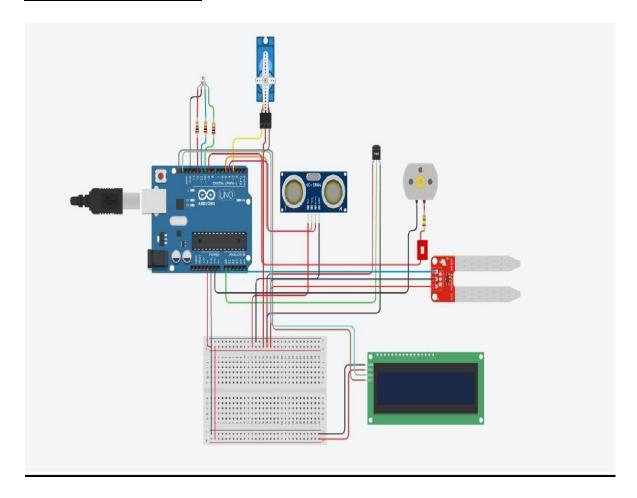
```
Serial.println(readDistanceCM());
  // LCD Display:
  lcd.setBacklight(1); //ON the background light in LCD lcd.clear();
  // Conditions:
  /*If the temperature is Greater than 20 and less than 35 and also the moisture
of soil is less than 60 then the GREEN light will be turned ON indicating the
Normal condition */ if (t \ge 20 \&\& t < 35 \&\& soil
  >=40 \&\& soil < 50
  { digitalWrite(b, 0);
    digitalWrite(g, 1);
    digitalWrite(r, 0); s.write(90);
    digitalWrite(motorPin, HIGH);
    lcd.setCursor(3, 0);
    lcd.print("ON MOTOR");
    delay(1000); lcd.clear();
    Serial.println("Water Partially Flows");
  }
  /*If the temperature is Greater than 35 and less than 45, then the BLUE light
will be turned ON indicating the Intermediate risk condition due to slightly
warm weather */
  else if (t \ge 35 \&\& t < 45)
  { digitalWrite(b, 1);
    digitalWrite(g, 0);
```

```
digitalWrite(r, 0); s.write(90);
    digitalWrite(motorPin, HIGH);
    lcd.setCursor(3, 0);
    lcd.print("ON MOTOR");
    delay(1000); lcd.clear();
    Serial.println("Water Partially Flows");
  }
  /*If the temperature is Greater than 45 or the moisture of soil is less than
30, then the RED light will be turned ON indicating the Critical condition due
to highly warm weather or the low moisture content in soil */ else if (t \ge 45 ||
soil < 30)
  { digitalWrite(b, 0);
    digitalWrite(g, 0);
    digitalWrite(r, 1);
    s.write(180);
    digitalWrite(motorPin, HIGH);
    Serial.println("Water Fully
    Flows''); lcd.setCursor(2, 0);
    lcd.print("ON MOTOR!!!");
    lcd.setCursor(3, 1);
    lcd.print("Low
    Water"); delay(1000);
    lcd.clear();
```

/*If the level of water is MORE in the field it will be indicated by distance sensor for less than 10cm and also the moisture of soil is greater than 80, then the

```
YELLOW light will be turned ON indicating the high water level */ else if
(distance<10 && soil> 80)
  { digitalWrite(b, 0);
    digitalWrite(g, 1);
    digitalWrite(r, 1);
    s.write(0);
    digitalWrite(motorPin,
                                     LOW);
    Serial.println("Water Does Not Flow");
    lcd.clear();
                    lcd.setCursor(3,
                                         0);
                                MOTOR");
    lcd.print("OFF
    delay(1000);
                                 lcd.clear();
    lcd.setCursor(1, 0); lcd.print("DRAIN
    WATER!!!"); delay(1000); lcd.clear();
  }
  else
  { digitalWrite(b, 1);
    digitalWrite(g, 1);
    digitalWrite(r, 0); s.write(0);
    digitalWrite(motorPin, LOW);
    lcd.setCursor(3, 0);
    lcd.print("OFF MOTOR");
    delay(1000); lcd.clear();
    Serial.println("Water Does Not Flow");
  }
  lcd.setCursor(0, 0);
  lcd.print("Temp:");
```

Circuit Diagram:



Component Used:

Name	Quantity	Component
UAU	1	Arduino Uno R3
SERVOMS	1	Positional Micro Servo
DLED	1	LED RGE
RGreen LED Resistor RRed LED Resistor RBlue LED Resistor	3	200 Ω Resistor
SENSMS	1	Soil Moisture Sensor
MSmall 6V DC Motor	1	DC Motor
RMotor Resistor	1	240 Ω Resistor
UTS	1	Temperature Sensor [TMP36]
DISTUltrasonic Distance Sersor	1	Ultrasonic Distance Sensor
U3	1	MCP23008-based, 32 LCD 16 x 2 (I2C)
SWDPST Switch	1	DIP Switch DPST

Link to Project in Tinker cad:

https://www.tinkercad.com/things/dcWbFQCFov5-smart-farmer-irrigation-%20system/editel?sharecode=XGk7187aEkY0Qz-xhQM-ey-K71uyCjmorp8hbDhM3WA