REAL-TIME COMMUNICATION SYSTEM POWERED BY AI FOR SPECIALLY ABLED

A PROJECT REPORT

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Submitted by

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Source Code

GitHub & Project Demo Link

TITLE	REAL-TIME COMMUNICATION
	SYSTEM POWERED BY AI FOR
	SPECIALLY ABLED
	DVTI2022TV VD 440.72
TEAMID	PNT2022TMID44952
WEAR EAD	TY2.6.4
TEAMLEAD	UMA
TEAMMEMBERS	RAKESH
	IV MEDIT
	GOWTHAMAN
	SNEKA

INTRODUCTION

1.1 Project Overview

In our society, we have people with disabilities. The technology is developing day by day but no significant developments are undertaken for the betterment of these people .Communications between deaf-mute and a normal person has always been a challenging task. It is very difficult for mute people to convey their message to normal people. Since normal people are not trained on hand sign language. In emergency times conveying their message is very difficult. The human hand has remained a popular choice to convey information insituations where other forms like speech cannot be used. Conversion System with Hand Gesture Recognition and translation will be very useful to have a proper conversation between a normal person and an impaired person in any language.

The project aims to develop a system that converts the sign language into a human hearing voice in the desired language to convey a message to normal people, as well asconvertspeechintounderstandablesignlanguageforthedeafanddumb. Wearemaking

use of a convolution neural network to create a model that is trained on different hand gestures. An app is built which uses this model. This app enables deafand dumb people to convey the irinformation using signs which get converted to human-understand able language and image is given as output.

1.2 PURPOSE

People get to know one another by sharing their ideas, thoughts, and experiences with those around them. There are numerous ways to accomplish this, one of which is the gift of images. Everyone can very convincing lytrans fertheir thoughts and understand each other through images. It will be unjust if we overlook those who are denied this priceless gift :the deaf and dumb. In such cases, the human hand has remained the preferred method of communication. The project's purpose is to create a system that translates sign language in to a human understandable languages that ordinary people may understand it.

LITERATURESURVEY

2.1 EXISTINGPROBLEM

Some of the existing solutions for solving this problem are :

[1] A Novel Communication System for Deaf and Dump People Using gesture

Human Beings know each other and contact with themselves through thoughts and ideas. The best way to present our idea is through speech. Some people don't have the power of speech; the only way they communicate with others is through sign language.

[2] Design of Communication interpreter for Deaf and Dump person

In this paper, we describe gesture based device for deaf and dumb person as communication for a person, who cannot hear is visual, not auditory. Generally dumb people use sign language for communication, but they find difficulty in communicating with others who don't understand sign language.

[3] AN Assisitive Device for Deaf and Dump People

This system describes a speech enabled hand glove system which aims at translation of sign language to analyze text input and voice. A system is designed that translates the hand finger motion to corresponding letters, using HC -SR04 ultrasonicsensors and an arduino mega board.

[4] Hand Sign recognition for depth images With Multi_scale density features of Deaf mute persons

Among many of the fastest growing research fields, sign language recognition is one of the top. Deaf and dumb community uses sign language to express their ideas or views. Sign Language is a methodical coded language where meanings are assigned to every gestures.

2.2 References

1.Pritesh Ambavane, Rahul Karjavkar, Hemant Pathare3, Shubham Relekar4,

Bhavana Alte and Neeraj Kumar Sharmar,2020,A Novel Communication System For Deaf And Dumb People using gesture.

- 2.Pallavi Verma , Shimi S.L. , Richa Priyadarshani ,(2013),Design of Communication Interpreter for Deaf and Dumb Person
- 3.Gowriswari S.Roshan J, Aadhithyan M, Venkatesh R, (2020), An Assistive Device For Deaf And Dumb People.
- 4.Taniya Sahanaa , Soumi Paulb, Subhadip Basub ,Ayatullah Faruk Mollaha,(2020),Hand sign recognition from depth images with multi-scale density features for deaf mute persons

2.3 Problem Statement Definition

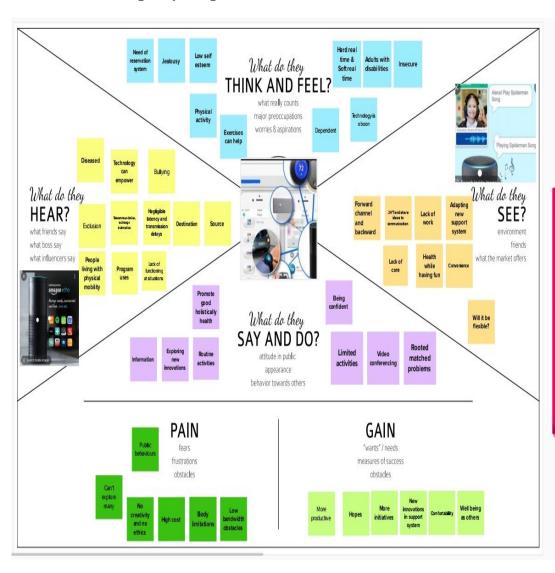
Real time communication system powered by AI for specially abled



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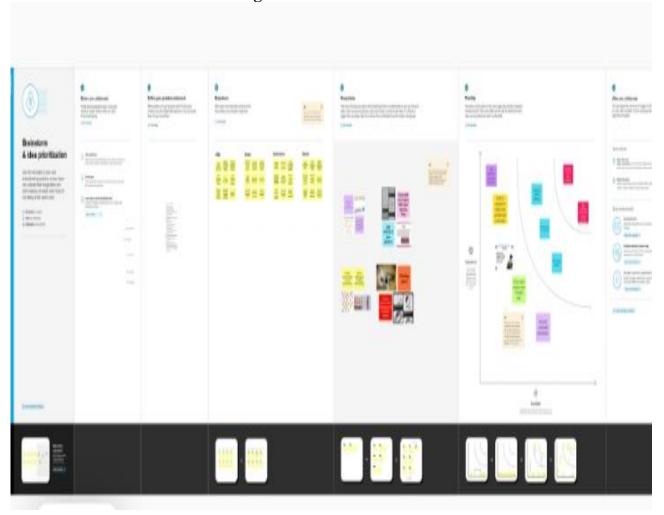
IDEATION & PROPOSED SOLUTION

3.1 Empathy Map Canvas



Share your feedback

3.2 Ideation & Brainstorming

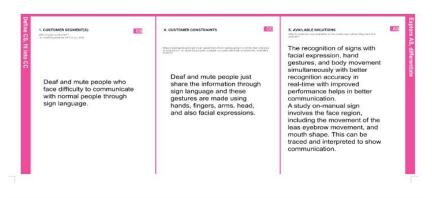


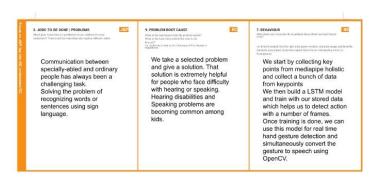
P	
3.ProposedSolution	

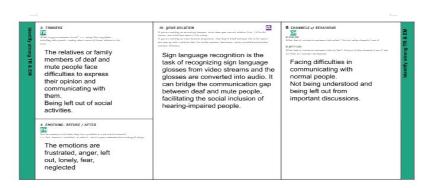
S. No.	Parameter	Description
•	Problem Statement (Problem to be solved)	how to easily communicate understand sign language for dump and deaf people What is the learn hand gestures Why read facial expression and lip movement for necessary in deaf and dump people Have a new technology for dump and deaf people Why interpret their hand gestures to other from make a hand held device
	ldea / Solation description	1. sign language INGLT HTK super vector 2. Sign language each country has one or sometimes more sign language 3. Hand gestures system used help with deaf and dump people and input is mapped to determined 4. Memories the finger spelling hand sign and LCD display system 5. Use knowledge of subject feature extraction and key point making
•	Novelty / Uniqueness	FLEX SENSOR: Flex sensors are attached to the gloves . These flex sensors contains the continues flow of current voltages. These sensors when bend creates a drop in voltage which in turn is recorded in microcontroller. ACCELEROMETER SENSOR:

		Accelerameter sensor measure the dynamic accelaration. When we attach accelerameter then we get a access which can be used for every finger direction.					
	Social Impact / Gustomer Satis factio n	Accelerameter is a device that measures acceleration across three axes (x, g, z) to determine orientation i. e. hand gestures shown in Figl (b). The output of the accelerameter is obtained in terms of angle i.e. orientation in x, g, z directions obtained in the form of analog readings. By the particular gesture of the flex sensor the message will display that we have saved in the Android Application database will display on LCD as well as the Android Phone and sound signal will also produce. effective communication between the deaf/dumb & traditional individuals.					
•	Business Model (Revenue Model)	Deaf and dumb Literate deaf and dumb Graduate deaf and dumb Employed deaf and dumb					
3	Scalability of the Solution	Smart Gloves is proposed to bridge the barrier of communication between disabled person and normal person. Sign language is the only medium for deaf and dumb persons to share their feeling or thoughts with other but their communication is restricted to other disabled person as normal cannot understand what they wants to say. Hand gesture recognition is a challenging problem in designing real life applications for deaf mate community. In this paper, we have presented an of ficient method to recognize hand gestures approach the Kineet VI.					

3.3 Problem Solution fit







REQUIREMENTANALYSIS

4.1 Functional requirements

FR No.	Functional Requirement (Epic)	Sub Requirement (Story / Sub-Task)
FR-1	User Registration	Registration through Form Registration through Gmail Registration through Linked IN
FR-2	User Confirmation	Confirmation via Email Confirmation via OTP
FR-3	User Verification	The user should receive a verification e-mail which they have to confirm to complete the registration.
FR-4	Compliance to rules or laws	Terms and conditions. Privacy policy. End user licensing agreement.
FR- 5	Authorization levels	There are two levels of authorization namely standard access level and advanced access level.
FR-6	Legal Requirements	Medical Certificate is produced

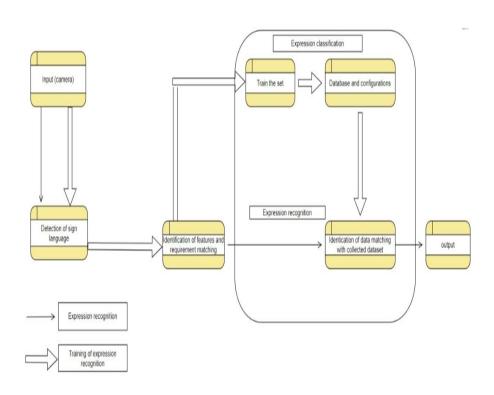
Non Functional Requirements

0 , 1 , 1 1

FR No.	Non-Functional Requirement	Description
NFR-1	Usability	The designed system is easy to use for specially abled persons as it is portable and platform independent.
NFR-2	Security	Converted information using signs into speech is accessed only by the user.
NFR-3	Reliability	System is tested with large number of data and Provides insight into issues.
NFR-4	Performance	Quick Launch time of application and faster in converting signs into speech
NFR-5	Availability	Provides automatic recovery and User access.
NFR-6	Scalability	Standard network condition the device should convert information within second.

PROJECT DESIGN

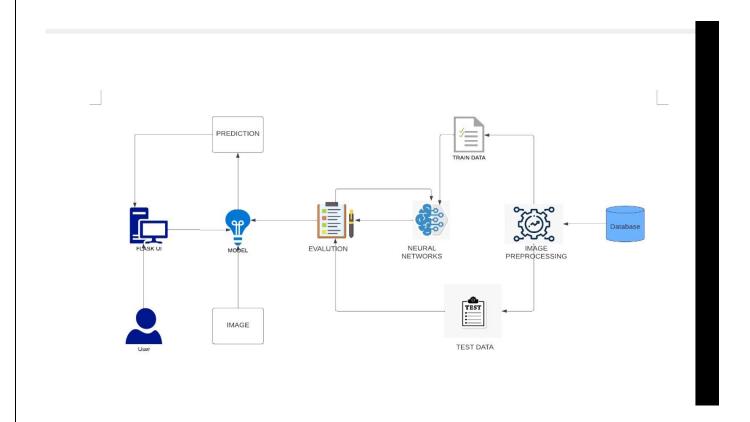
5.1 Data Flow Diagrams



Solution Architecture:

The Deliverable shall include the architectural diagram.

Example-Solution Architecture Diagram:



5.2 User Stories

User Stories

Use the below template to list all the user stories for the product.

User Type	Functional Requirement (Epic)	User Story Number	User Story / Task	Acceptance oriteria	Priority	Release
Gustomer (Mobile user)	Registration	USN-1	As a user. I can register for the application by entering my email. password. and confirming my password.	I can access my account / dashboard	High	Sprint-1
		USN-2	As a user. I can register for the application through Gmail	l can access my account / dashboard	High	Sprint-1
	Confirmation	USN-3	As a user. I will receive confirmation email once I have registered for the application	I can receive confirmation email & click confirm	High	Sprint-1
	Login	USN-4	As a user. I can log into the application by entering email & password	I can enter into the login by id and password	High	Sprint-1
	Data input	USN-5	User will be giving the input, the camera as speech or signs	I can give the input to the system	High	Sprint-1
		USN-6	The system will take the input for the testing will the given data base	The will accept the input for the testing	High	Sprint-2
	Data verification	USN-7	It will verify with the data base that will match with the input	Configuration of the input	High	Sprint-2
		USN-8	Identification of the input and convert into the text if the input is signs or as signs	Identification of the input and creating output	High	Sprint-3
	Output Display	USN-9	Display the output on the screen for the user	Display of the output	High	Sprint-4

PROJECT PLANNING AND SCHEDULING

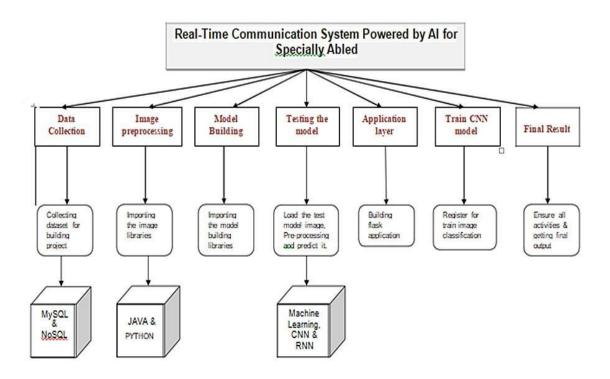
6.1 Sprint Planning And Estimation

Milestone Activity Plan.

Use the below template to create product backleg and sprint schedule

Milostone Punolton(Epto)		Milostono Story Number	Story/Task
Milestone-I	Data Golloction	М	we're collecting data set for hailding our project and creating two folders, one for training and a not her one for teeting
Milestone-2	lmago proprocessing	M2	Importing image data generator libraries and applying image data generator functionality to train the test set.
Milestone-3	Model Pus ldsng	мэ	Importing the model huilding libraries. Initialising the model. Adding Convolution layers. Adding the Pooling layers. Adding the Flatten layers. Adding Dense layers. Compiling the model Fit and Save the model
Milestone-4	Tosting the model	M4	Import the packages first. Then we save the model and Load the test image, p reprocess it and product it.
Milestone-5	Application layer	M5	Build the flack application and the HTML pages.
Milestone-6	Train CNN model	M6	Register for IBM Cloud and train image Classification Model

MILESTONE ACTIVITY PLAN



SPRINT PLANING

Sprint	Functional	User Story Number	User Story/Task	Story	Priority	Team Members
	Requirement(Epic)			Points		
Sprint-1	Data Collection	นร ท- 1	Collect Data set.	9	High	UMA
Sprint-1	lmage processing	USN-2	lmage p reprocessing	8	Medium	RAKESH GOWTHAM
Sprint-2	Model Building	USN-3	Import the required libraries, add the necessary layers and compile the model	10	High	UMA RAKESH

						GOWTHAM Sneka
Sprint-2	CNNMODEL	USN-4	Training the image classification model using CNN	7	Medlum	UMA RAKESH GOWTHAM
Sprint-3	Training and Testing	USN-5	Training the model and testing the model's performance	9	High	UMA SNEKA
Sprint-4	Implementation of the application	USN-6	Converting the input sign language image sin to English alphabets	8	Medium	UMA RAKESH SNEKA

6.2 Sprint Delivery Schedule

Project Tracker, Velocity & Burn down Chart: (4Marks)

Sprint	Total Story Points	Duration	Sprint Start Date	Sprint End Date(Planned)	Story Points Completed(abson Planned End Date)	Sprint Release Date(Actual)
Sprint-1	10	6Days	240ct 2022	290et 2022	8	290ct 2022
Sprint-2	10	6Days	310et 2022	04Nov2022	5	04Nev2022
Sprint-3	10	6Days	07Nov2022	11Nov2022	Z	11Nov2022
Sprint-4	10	6Days	14Nov2022	18Nov2022	5	18Nov2022

Velocity:

Velocity

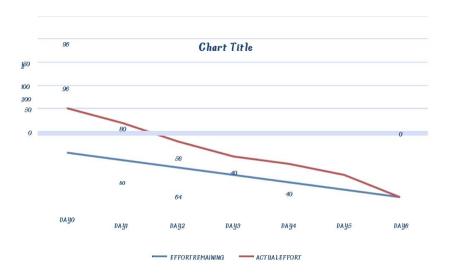
Average Velocity= Velocity

Sprint Duration

- Average Velocity →AV
- Velocity →Points per sprint
- Sprint Duration →Number of days per sprint

AV = 6/10 = 0.6

6.3 Report From Jira



BURNDOWNCHART

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CODING AND EXECUTION

7.1 Feature1

The proposed system consists of two features front end and backend. The frontendisdesignedusingHTMLandCSS. The first feature is a webpage whenever a user wants tot ranslate the sign language to English, they can go to the webpage it has start button. On pressing the start button, it will turn on the camera for live translation. Once the camera is turne don, we can start translating.

Coding:

```
<!DOCTYPEhtml>
<html>
<head>
<title>RealTimeCommunication</title>
<style>body
{
background-image:linear-
gradient(tobottomright,blue,black);background-repeat: no-
repeat;
background-attachment:fixed;
h1,h2,a,p\{co
lor:white;
}
</style>
</head>
```

```
<body>
<divclass="title">
<h1><center>
REAL-
TIMECOMMUNICATIONSYSTEMPOWEREDBYAIFORSPE
CIALLYABLED</center></h1>
</div>
<center><imgsrc="../static/img/img.png"width="300"height="300"></center>
<div>
<center><h2>ShowtheseGesturestoget the Alphabet</h2></center>
</div>
<div>
<center><ahref="{{url_for('predict')}}">CLICKHERETO
SHOWYOURGESTURES</a></center>
</div>
<div>
```

<center>In our society, we have people with disabilities. The technology isdeveloping dayby daybutnosignificantdevelopments are undertakenforthebetterment of these people. Communications between deaf-mute and a normal person has always been a challenging task. It is very difficult for mute people to convey their message tonormal people. Since normal people are not trained on hand sign language. In emergencytimes conveying their message is very difficult.

The project aims to develop a system that converts the sign language into a alphabet inthe desired language to convey a message to normal people. We are making use of aconvolution neural network to create a model that is trained on different hand gestures. Anappis builtwhichusesthismodel. This appenables deaf and dumbpeopleto conveytheir information using signs which get converted to human-understandable language is given as output.

```
</center>
</div>
</body>
</html>
```

7.2 Feature 2

The second feature of the proposed system is backend. The backend is designed using python with the packages of python like flask, tensorflow, opency-python, keras, numpy, pandas, virtualeny, pillow and Machine learning technology and trained with datasets. Once the camera is turned on the system detects and identify the sign language and translate it to English by matching the live action with the trained dataset. **Coding:** from flask import Flask ,render_template,request import cv2

```
From keras.model sim port load_
model import numpy as np from gtts
import TTSimportos

From keras. Preprocessing import
image from sk image.transform import
resize from play sound import play
sound app

=
Flask(_name_)model=load_model("
aslpng1.h5")vals=['A','B','C','D','E','F
','G','H','I']
@app. route('/',methods=['GET'])def
index():
    return render_
template('index.html')@app. route('/index',
```

P	
	1 1 (ICEPTI) 1 (1
	methods=['GET']) def home():

```
return
```

```
render_template('index.html')@app.route('/predict',
methods=['GET','POST'])defpredict():
                 print("[INFO]starting video
                 stream...")vs=cv2.VideoCapture(0)
                (W,H)=(None,
                 None)while True:
        (grabbed, frame)=vs .read()
                        If not grabbed:
                                  break
                        if W is None or His None:
                                  (H, W) = frame.
                         shape[:2]output=frame. copy()
                         # r = cv2.selectROI("Slect",
                       output)#print(r)
                         cv2.rectangle(output,(81,79),(276,274),(0,255,0),2)fra
                         me=frame[81:276,79:274]
                         frame= cv2.cvtColor(frame,cv2.COLOR_RGB2GRAY)
                          _, frame = cv2.threshold(frame, 95,
255,cv2.THRESH_BINARY_INV)
                         frame=cv2.cvtColor(frame,cv2.COLOR_GRAY2RGB)i
                         mg=resize(frame,(64,64,3))
                         img=np.expand_dims(img,axis=0)i
                         f(np.max(img)>1):
```

```
img=img/255.0
                          result=np.argmax(model.predict(img))i
                           ndex=['A','B','C','D','E','F','G','H','I']
                           result=str(index[result])
                    cv2.putText(output,"The
PredictedLetter:{}".format(result),(10,50),cv2.FONT_HERSHEY_PLAIN,
                                                      2,(150,0,150),2)
                           cv2.putText(output,"Pressqtoexit",(10,450),cv
2.FONT_HERSHEY_PLAIN,2,(0,0,255),2)
                     speech = gTTS(text = result, lang = 'en', slow =
                           False)cv2.imshow("Output",output)
                           key = cv2.waitKey(1) &
                           0xFFifkey==ord("q"):
                                    breakprint(
                  "[INFO] cleaning
                  up...") vs.release () cv2.destroy\\
                  AllWindows()
                  return render _template("index.html")if
```

name == '_main_ ':app

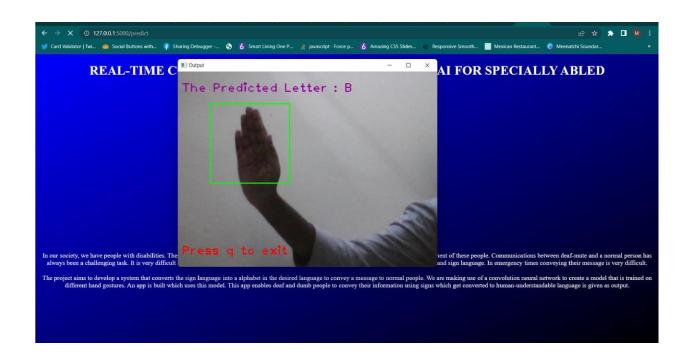
.run(debug=True)

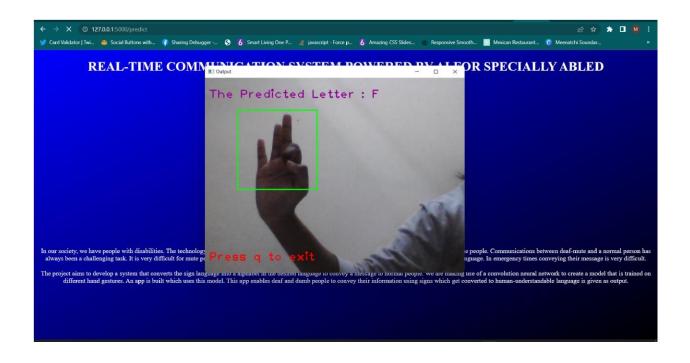
TESTING

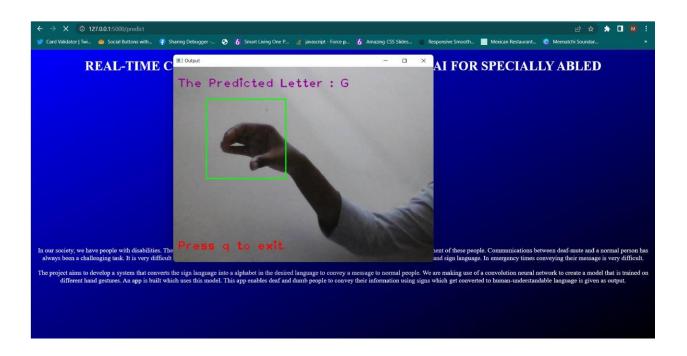
```
# Importing Libarries
from tensor flow. keras. model simport load\_model fr
omtensorflow.keras.preprocessing import image
import numpy as np import cv2 # loading model
model = load_ model('aslpng1.h5') from sk
image. transform import resize def detect(frame):
  img=resize(frame, (64,64,3))
  img= np. expand_ dims(img,
  axis=0)if np .max(img)>1:
    img=img/255.0
  prediction=model.predict(img)p
  rint(prediction)
  return prediction frame = cv2.imread(r"D:\Real-time Communication
System for specially abled\Dataset\test_set\A\16.png") data
=detect(frame)
index=['A','B','C','D','E','F','G','H','I']
index[np.argmax(data)]#ImportingLi
brariesimportcv2
import numpy as np
```

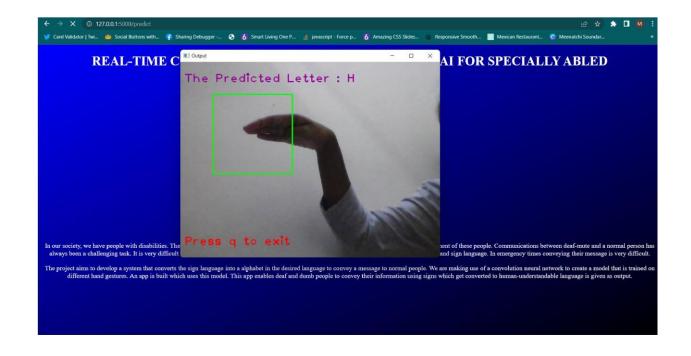
```
fromtensorflow.keras.modelsimportload_modelfromte
nsorflow.keras.preprocessingimportimage
#Loading Model
model=load_model("aslpng1.h5")video
=cv2.VideoCapture(0)
index=['A','B','C','D','E','F','G','H','I']while
True:
  success, frame =
  video.read()cv2.imwrite('frame
  .jpg',frame)
  img=image.load_img('frame.jpg',target_size=(64,64))x=i
  mage.img_to_array(img)
  x=cv2.cvtColor(x,cv2.COLOR_BGR2HSV)a
  = x.array\_to\_img(x)
  cv2.imshow("")
x=np.expand\_dims(x,axis=0)
  pred=np.argmax(model.predict(x),axis=1)
y=pred[0]
  copy=frame.copy()
  cv2.rectangle(copy,(320,100),(620,400),(255,0,0), 5)
  cv2.putText(frame, "The Predicted Alphabet: " + str(index[y]), (100,
100),cv2.FONT_HERSHEY_SIMPLEX,1,(0,0,0),4)
  cv2.imshow('frame',frame)
  ifcv2.waitKey(1)&0xFF==ord('q'):break
```

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	video. release()cv2.destroyAllWindows()		
	RESULT		
	9.1 Performance Metrics		









ADVANTAGES AND

DISADVANTAGES

ADVANTAGE:

- Communication is the key in this societypeoplewithdisabilitytendssufferbuttheproposedsystemprovides as olution to the em.
- Makes the translation of sign language to English easy.
- It can identify and translate the live and moving images.
- The proposed system ensures the easy translation of sign language to English.
- Eventhepeoplewithlackofsignlanguagecanusetheproposedsystemeasily.
- This does not require high-end device to use it.
- Can be used on almost all operating systems and browses.
- Does not require prior programming knowledge tuse the system
- The proposed system is user friendly.
- Makes the life of the person with disability easy.

DISADVANTAGE:

- The proposed system is not two-way translation system.
- There is chance for wrong translation.
- Sinceitisawebpage-basedsystem, it does require internet connectivity which can be in convenient times.

• It would have been convenient if it is application based.

CONCLUSION

Sign language is a useful tool for facilitating communication between deaf and hearing people. Because it allows for two-way communication, the system aims to bridge the communication gap between deaf people and theres to society. The proposedmethodologytranslateslanguageintoEnglishalphabetsthatareunderstandabletohum ans. This system sends hand gestures to the model, who recognizes them and displays the equivalent Alphabet on the screen. Deaf-mute people can use their hands to perform sign language, which will then be converted into alphabets, thanks to this project.

FUTURE

SCOPE

In the future to take the project to the next level two way communication system such as sign language to english and english to sign language is beign under the planning phase. The application version of the web page for both ios and android is also in planningprocessforthefuturedevelopment.Researchtoimprovetheaccuracyofthesystemisun derprogress.

APPENDIX

```
SOURCECODE:
HTML:
<!DOCTYPEhtml>
<html>
<head>
<title>RealTimeCommunication</title>
<style>body
{
background-image:linear-
gradient(tobottomright,blue,black);background-repeat: no-
repeat;
background-attachment:fixed;
}
h1,h2,a,p\{co
lor:white;
}
</style>
</head>
<body>
<divclass="title">
<h1><center>
```

REAL-TIMECOMMUNICATIONSYSTEMPOWEREDBYAI

FORSPECIALLY ABLED </center> </h1>

```
</div>
<center><imgsrc="../static/img/img.png"width="300"height="300"></center>
<div>
<center><h2>ShowtheseGesturestoget the Alphabet</h2></center>
</div>
<div>
<center><ahref="{{url_for('predict')}}">CLICKHERETO
SHOWYOURGESTURES</a></center>
</div>
<div>
<div></div>
```

<center>In our society, we have people with disabilities. The technology is developing day by day but no significant development sareunder taken for the better men to f these people. Communications between deaf-mute and a normal person has always been a challenging task. It is very difficult for mute people to convey their message to normal people. Since normal people are not trained on hand sign language. In emergency times conveying their message is very difficult.

The project aims to develop a system that converts the sign language into a alphabet in the desired language to convey a message to normal people. We are making use of a convolution neural network to create a model that is trained on different hand gestures. An app is built which uses this model. This app enables deaf and dumb people to convey their information using signs which get converted to human-understandable language is given as output.

</center>
</div>
</body>
</html>

```
PYTHON:
from flask import Flask, render\_template, request import cv
2
from keras. Model sim port load_
model import numpy as np from gtts
import gTT Simportos
fromkeras.preprocessingimportimagefr
om skimage.transform import
resizefromplaysoundimport
playsoundapp
Flask(_name_)model=load_model("
aslpng1.h5")vals=['A','B','C','D','E','F
','G','H','I']
@app.route('/',methods=['GET'])defi
ndex():
         return
render_template('index.html')@app.route('/in
dex', methods=['GET']) defhome():
         return
render_template('index.html')@app.route('/predict',
methods=['GET','POST'])defpredict():
                  print("[INFO]startingvideostream...")v
                  s=cv2.VideoCapture(0)
                 (W,H)=(None,None)w
```

P	
	hileTrue:

```
(grabbed,frame)=vs.read()
                         ifnotgrabbed:
                                   break
                         ifWis Noneor HisNone:
                                   (H, W) =
                          frame.shape[:2]output=frame.copy
                          ()
                          \# r = cv2.selectROI("Slect",
                       output)#print(r)
                          cv2.rectangle(output,(81,79),(276,274),(0,255,0),2)fra
                          me=frame[81:276,79:274]
                          frame= cv2.cvtColor(frame,cv2.COLOR_RGB2GRAY)
                          _, frame = cv2.threshold(frame, 95,
255,cv2.THRESH_BINARY_INV)
                          frame=cv2.cvtColor(frame,cv2.COLOR_GRAY2RGB)i
                         mg=resize(frame,(64,64,3))
                          img=np.expand_dims(img,axis=0)i
                          f(np.max(img)>1):
                                   img=img/255.0
                         result=np.argmax(model.predict(img))i
                          ndex=['A','B','C','D','E','F','G','H','I']
                          result=str(index[result])
                   cv2.putText(output,"The
PredictedLetter:{}".format(result),(10,50),cv2.FONT_HERSHEY_PLAIN,
                                                    2,(150,0,150),2)
```

```
cv2.putText(output,"Pressqtoexit",(10,450),cv
2.FONT_HERSHEY_PLAIN,2,(0,0,255),2)
                    speech = gTTS(text = result, lang = 'en', slow =
                          False)cv2.imshow("Output",output)
                          key = cv2.waitKey(1) &
                          0xFFifkey==ord("q"):
                                   breakprint(
                  "[INFO] cleaning
                 up...")vs.release()cv2.destroy
                 AllWindows()
                 returnrender_template("index.html")if
_name_=='_main_':
          app.run(debug=True)TRAI
NNINGCODE:
#ImportingLibraries
from tensor flow. keras. preprocessing. image import Image Data Generator\\
#ImageAugmentation
train_datagen=ImageDataGenerator(rescale=1./255,shear_range=0.2,zoom_ra
nge=
0.2,horizontal_flip=True)test_datagen=Im
ageDataGenerator(rescale=1./255)
#Loadingtrainandtestset
X_train = train_datagen.flow_from_directory(r"D:\Real-time Communication System
forspeciallyabled\Dataset\training_set",target_size=(64,64),batch_size=32,class_mode
='categorical')
```

```
X_{test} = test_{datagen.flow_from_directory(r"D:\Real-time Communication System)}
forspeciallyabled\Dataset\training_set",target_size=(64,64),batch_size=32,class_mode
='categorical')
# checking
indicesX_train.class_i
ndices#
ImportingLibraries
fromtensorflow.keras.modelsimportSequentialfromte
nsorflow.keras.layers importDense
fromtensorflow.keras.layersimportConvolution2D,MaxPooling2D,Flatten#I
nitializingtheModel
model=Sequential()#
AddingConvolutionLayer
model.add(Convolution2D((32),(3,3),input_shape=(64,64,3),activation='relu'))#Add
ingPoolingLayer
model.add(MaxPooling2D(pool_size=(2,2)))#
AddingFlattenLayer
model.add(Flatten())#
AddingHiddenLayer
model.add(Dense(units=512,kernel_initializer='random_uniform',activation='relu'))
# Adding Output Layer model.add(Dense(units = 9, kernel_initializer
='random_uniform', activation = 'softmax')) # Compile the
modelmodel.compile(loss = 'categorical_crossentropy', optimizer = 'adam',
metrics =['accuracy'])#Fiitingthemodel
model.fit_generator(X_train,steps_per_epoch=24, epochs = 10, validation_data
= X_test, validation_steps = 40) # Saving themodelmodel.save('aslpng1.h5')
```

TESTINGCODE: #ImportingLibarries $from tensor flow. keras. model simport load_model from tensor flow. keras. model simport load_model flow. keras. model fl$ nsorflow.keras.preprocessing import image importnumpy as np import cv2 # loading model model =load_model('aslpng1.h5') from skimage.transformimportresizedefdetect(frame): img=resize(frame, (64,64,3)) img=np.expand_dims(img,axis=0)ifn p.max(img)>1: img=img/255.0 prediction=model.predict(img)p rint(prediction) return prediction frame = cv2.imread(r"D:\Real-time Communication System for specially abled\Dataset\test_set\A\16.png") data =detect(frame) index=['A','B','C','D','E','F','G','H','I'] index[np.argmax(data)]#ImportingLi braries import cv2 import numpyasnp $from tensor flow. keras. model simport load_model from tensor flow. keras. model simport load_model flow. keras. model flow.$ nsorflow.keras.preprocessingimportimage # Loading Model model =load_model("aslpng1.h5")video=cv

2. VideoCapture(0)

```
index=['A','B','C','D','E','F','G','H','I']while
True:
  success, frame =
  video.read()cv2.imwrite('frame
  .jpg',frame)
  img=image.load_img('frame.jpg',target_size=(64,64))x=i
  mage.img_to_array(img)
  x=cv2.cvtColor(x,cv2.COLOR_BGR2HSV)a
  = x.array_to_img(x)
  cv2.imshow("")
x=np.expand_dims(x,axis=0)
  pred=np.argmax(model.predict(x),axis=1)
y=pred[0]
  copy=frame.copy()
  cv2.rectangle(copy,(320,100), (620,400), (255,0,0), 5)
  cv2.putText(frame, "The Predicted Alphabet: " + str(index[y]), (100,
100),cv2.FONT_HERSHEY_SIMPLEX,1,(0,0,0),4)
  cv2.imshow('frame',frame)
  ifcv2.waitKey(1)&0xFF==ord('q'):break
video.release()cv2.destroyAllWindows()
```

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	GITHUBLINK:
	https://github.com/IBM-EPBL/IBM-Project-5964-1658821323