

Wokwi code to gather data from DHT22 sensor

```
#include <WiFi.h> //library for wifi
#include <PubSubClient.h> //library for MQTT
#include "DHT.h" // Library for dht11
#include <Stepper.h>
#define DHTPIN 15 // what pin we're connected to
#define DHTTYPE DHT22 // define type of sensor DHT 11

#define DIRPIN 4
#define STEPPIN 5
#define DELAY_US 2000

DHT dht (DHTPIN, DHTTYPE); // creating the instance by passing pin and typr of
dht connected

void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength);

//-----credentials of IBM Accounts-----

#define ORG "k1o3f1" //IBM ORGANITION ID
#define DEVICE_TYPE "abcd" //Device type mentioned in ibm watson IOT Platform
#define DEVICE_ID "1234" //Device ID mentioned in ibm watson IOT Platform
#define TOKEN "12345678" //Token
String data3;
float h, t ,s;
;

//----- Customise the above values -----
char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; // Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json"; // topic name and type of
event perform and format in which data to be send
char subscribetopic[] = "iot-2/cmd/command/fmt/String"; // cmd REPRESENT
command type AND COMMAND IS TEST OF FORMAT STRING
char authMethod[] = "use-token-auth"; // authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID; //client id

//-----
WiFiClient wifiClient; // creating the instance for wificlient
PubSubClient client(server, 1883 ,wifiClient); //calling the predefined client
id by passing parameter like server id,portand wificredential

void setup() // configureing the ESP32
```

```

{
    Serial.begin(115200);
    dht.begin();

    pinMode(DIRPIN, OUTPUT);
    pinMode(STEPPIN, OUTPUT);
    delay(1000);

    Serial.println();
    wificonnect();
    client.setCallback(callback);

    mqttconnect();
    client.setCallback(callback);
}

void loop()// Recursive Function
{

    h = dht.readHumidity();
    t = dht.readTemperature();
    s=0;
    Serial.print("temp:");
    Serial.println(t);
    Serial.print("Humid:");
    Serial.println(h);

    PublishData(t, h,s);
    delay(1000);
    if (!client.loop()) {
        mqttconnect();
    }
}

/*.....retrieving to
Cloud.....*/

void PublishData(float temp, float humid,float status) {
    mqttconnect();//function call for connecting to ibm
    /*
        creating the String in in form JSon to update the data to ibm cloud
    */
    if (temp>50 && humid>60){
        status=1;
    }
    String payload = "{\"temp\":";
    payload += temp;

```

```

payload += "," "\"Humid\":";
payload += humid;
payload += "," "\"Status\":";
payload += status;
payload += "}";

Serial.print("Sending payload: ");
Serial.println(payload);

if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish ok");// if it sucessfully upload data on the cloud
    then it will print publish ok in Serial monitor or else it will print publish
    failed
} else {
    Serial.println("Publish failed");
}

}

void mqttconnect() {
    if (!client.connected()) {
        Serial.print("Reconnecting client to ");
        Serial.println(server);
        client.setCallback(callback);
        while (!client.connect(clientId, authMethod, token)) {
            Serial.print(".");
            delay(500);
        }
    }
    initManagedDevice();
    client.subscribe("cmnd/command/motoron");
    // client.subscribe("cmnd/GarageDoor/POWER2");
    Serial.println();
}

void wificonnect() //function defination for wificonnect
{
    Serial.println();
    Serial.print("Connecting to ");

    WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish
    the connection
    while (WiFi.status() != WL_CONNECTED) {
        delay(500);
        Serial.print(".");
    }
}

```

```

    Serial.println("");
    Serial.println("WiFi connected");
    Serial.println("IP address: ");
    Serial.println(WiFi.localIP());
}

void initManagedDevice() {
    if (client.subscribe(subscribetopic)) {
        Serial.print(client.subscribe(subscribetopic));
        callback(subscribetopic,0,1);
        Serial.println("subscribe to cmd OK");
    } else {
        Serial.println("subscribe to cmd FAILED");
    }
}

void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{
    Serial.print("callback invoked for topic: ");
    Serial.println(subscribetopic);
    for (int i = 0; i < payloadLength; i++) {
        //Serial.print((char)payload[i]);
        data3 += (char)payload[i];
    }
    data3 = "motoron";
    Serial.println("data: "+ data3);
    if(data3=="motoron")
    {
        Serial.println(data3);
        Serial.print("Motor running");
        digitalWrite(DIRPIN, HIGH);
        for (int i = 0; i < 200; i++) {

            digitalWrite(STEPPIN, HIGH);
            delayMicroseconds(DELAY_US);
            digitalWrite(STEPPIN, LOW);
            delayMicroseconds(DELAY_US);
        }
    }
    else
    {
        Serial.println(data3);
        digitalWrite(DIRPIN, LOW);
    }
    data3="";
}

```