```
#!/usr/bin/env python
# coding: utf-8

# In[50]:


from keras.models import Sequential
from keras.layers import Convolution2D
from keras.layers import MaxPooling2D
from keras.layers import Flatten
from keras.layers import Dense
from keras.models import model_from_json
import matplotlib.pyplot as plt
import warnings


# In[51]:


warnings.filterwarnings('ignore')
batch_size = 32


# In[52]:


from tensorflow.keras.preprocessing.image import ImageDataGenerator

# All images will be rescaled by 1./255
train_datagen = ImageDataGenerator(rescale=1/255)


# In[53]:


# Flow training images in batches of 128 using train_datagen generator
train_generator = train_datagen.flow_from_directory(
        'G:/CAR_DATASET/Car damage/body/training',    # This is the source directory for training
images
        target_size=(200, 200),    # All images will be resized to 200 x 200
        batch_size=batch_size,
        # Specify the classes explicitly
        classes = ['00-front','01-rear','02-side'],
        # Since we use categorical_crossentropy loss, we need categorical labels
        class_mode='categorical')


# In[54]:


import tensorflow as tf


# In[55]:


#cnn Model
```

```
model = tf.keras.models.Sequential([
    # Note the input shape is the desired size of the image 200x 200 with 3 bytes color
    # The first convolution
    tf.keras.layers.Conv2D(16, (3,3), activation='relu', input_shape=(200, 200, 3)),
    tf.keras.layers.MaxPooling2D(2, 2),
    # The second convolution
    tf.keras.layers.Conv2D(32, (3,3), activation='relu'),
    tf.keras.layers.MaxPooling2D(2,2),
    # The third convolution
    tf.keras.layers.Conv2D(64, (3,3), activation='relu'),
    tf.keras.layers.MaxPooling2D(2,2),
    # The fourth convolution
    tf.keras.layers.Conv2D(64, (3,3), activation='relu'),
    tf.keras.layers.MaxPooling2D(2,2),
    # The fifth convolution
    tf.keras.layers.Conv2D(64, (3,3), activation='relu'),
    tf.keras.layers.MaxPooling2D(2,2),
    # Flatten the results to feed into a dense layer
    tf.keras.layers.Flatten(),
    # 128 neuron in the fully-connected layer
    tf.keras.layers.Dense(128, activation='relu'),
    # 5 output neurons for 5 classes with the softmax activation
    tf.keras.layers.Dense(3, activation='softmax')
])


# In[56]:


model.summary()


# In[57]:


model.compile(loss="categorical_crossentropy",metrics=["accuracy"],optimizer='adam')


# In[58]:


from tensorflow.keras.optimizers import RMSprop


# In[59]:


early = tf.keras.callbacks.EarlyStopping(monitor='val_loss',patience=5)
model.compile(loss='categorical_crossentropy',
              optimizer=RMSprop(lr=0.001),
              metrics=['accuracy'])


# In[60]:


total_sample=train_generator.n
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In[61]:

```
n_epochs = 10
```

In[62]:

```
history = model.fit_generator(
            train_generator,
            steps_per_epoch=int(total_sample/batch_size),
            epochs=n_epochs,
            verbose=1)
```

In[63]:

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model.save('body.h5')
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In[64]:

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acc = history.history['accuracy']
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In[65]:

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loss = history.history['loss']
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In[66]:

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epochs = range(1, len(acc) + 1)
```

In[67]:

```
# Train and validation accuracy
plt.plot(epochs, acc, 'b', label='accurarcy')
```

In[68]:

```
plt.title('   accurarcy')
plt.legend()
```

In[69]:

```
plt.figure()


# In[70]:


# Train and validation loss
plt.plot(epochs, loss, 'b', label='loss')
plt.title('   loss')
plt.legend()
plt.show()


# In[ ]:




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