



```
const int TrigPin = 6;
```

```
const int EchoPin = 7;
```

```
const int LedPin = 13;
```

```
const int DISTANCE = 10;
```

```
float duration_us, distance_cm;
```

```
void setup() {
```

```
  Serial.begin(9600);
```

```
  pinMode(TrigPin, OUTPUT);
```

```
  pinMode(EchoPin, INPUT);
```

```
  pinMode(LedPin, OUTPUT);
```

```
}
```

```
void loop() {  
  
    digitalWrite(TrigPin, HIGH);  
    delayMicroseconds(10);  
    digitalWrite(TrigPin, LOW);  
  
    duration_us = pulseIn(EchoPin, HIGH);  
  
    distance_cm = 0.017 * duration_us;  
  
    if(distance_cm < DISTANCE)  
        digitalWrite(LedPin, HIGH);  
    else  
        digitalWrite(LedPin, LOW);  
  
    Serial.print("distance: ");  
    Serial.print(distance_cm);  
    Serial.println(" cm");  
  
    delay(500);  
}
```