ASSIGNMENT-4 DISTANCE DETECTION USING ULTRASONICSENSOR

Date	30 October 2022
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Maximum Marks	2 Marks

Question1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

WOKWI LINK:

https://wokwi.com/projects/305566932847821378

CODE:

```
esp32-blink.ino
                   diagram.json •
                                    libraries.txt ●
                                                   Library Manager
       pinMode(trig,OUTPUT);
       pinMode(echo,INPUT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void loop()// Recursive Function
        digitalWrite(trig,LOW);
         digitalWrite(trig,HIGH);
         delayMicroseconds(10);
         digitalWrite(trig,LOW);
         float dur = pulseIn(echo,HIGH);
         float dist = (dur * 0.0343)/2;
         Serial.print ("Distancein cm");
         Serial.println(dist);
         PublishData(dist);
         delay(1000);
         if (!client.loop()) {
           mqttconnect();
         }
       void PublishData(float dist) {
         mqttconnect();//function call for connecting to ibm
```

```
creating the String in in form JSon to update the data to ibm cloud

"/
String object;
if (dist <100)

{
digitalWrite(LED,HIGH);
Serial.println("object is near");
object = "Near";

}
else
{
digitalWrite(LED,LOW);
Serial.println("no object found");
object = "No";
}

String payload = "{\"distance\":";
payload += object;
payload += object;
payload += "\"";

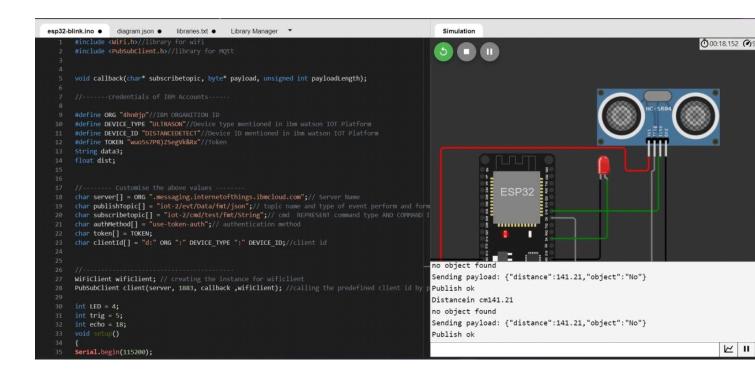
serial.println("sending payload: ");
Serial.println(payload);
```

```
libraries.txt ● Library Manager ▼
esp32-blink.ino
                      diagram.json ●
            if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish ok");// if it successfully upload data on the cloud then it will print publish ok in Serial monitor or else it will print publish failed
              Serial.println("Publish failed");
         void mqttconnect() {
           if (!client.connected()) {
    Serial.print("Reconnecting client to ");
    Serial.println(server);
              while (!!!client.connect(clientId, authMethod, token)) {
                 delay(500);
                initManagedDevice();
                Serial.println();
         void wificonnect() //function defination for wificonnect
            Serial.print("Connecting to ");
           WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
while (WiFi.status() != WL_CONNECTED) {
             delay(500);
Serial.print(".");
           Serial.println("");
Serial.println("WiFi connected");
Serial.println("IP address: ");
            Serial.println(WiFi.localIP());
```

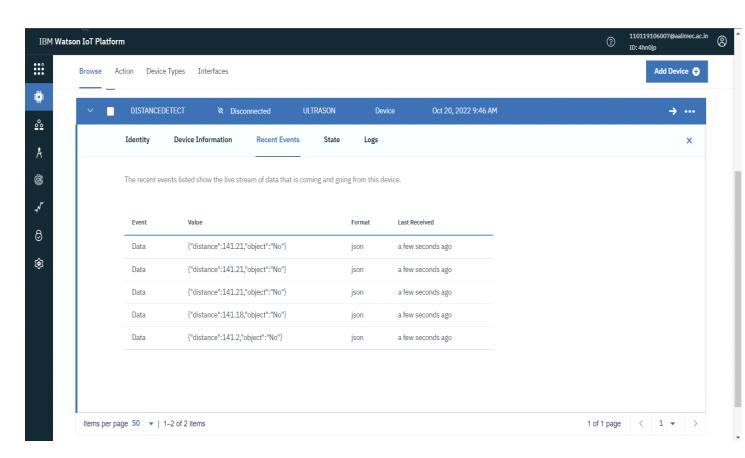
```
esp32-blink.ino •
                   diagram.json •
                                    libraries.txt •
                                                   Library Manager
         WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
         while (WiFi.status() != WL CONNECTED) {
           delay(500);
           Serial.print(".");
         Serial.println("");
         Serial.println("WiFi connected");
         Serial.println("IP address: ");
         Serial.println(WiFi.localIP());
       void initManagedDevice() {
         if (client.subscribe(subscribetopic)) {
           Serial.println((subscribetopic));
           Serial.println("subscribe to cmd OK");
          } else {
           Serial.println("subscribe to cmd FAILED");
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
         Serial.print("callback invoked for topic: ");
         Serial.println(subscribetopic);
 148
         for (int i = 0; i < payloadLength; i++) {</pre>
           //Serial.print((char)payload[i]);
           data3 += (char)payload[i];
```

```
esp32-blink.ino •
                    diagram.json •
                                     libraries.txt •
                                                     Library Manager
        void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
          Serial.print("callback invoked for topic: ");
          Serial.println(subscribetopic);
 148
          for (int i = 0; i < payloadLength; i++) {</pre>
            data3 += (char)payload[i];
          }
       data3="";
```

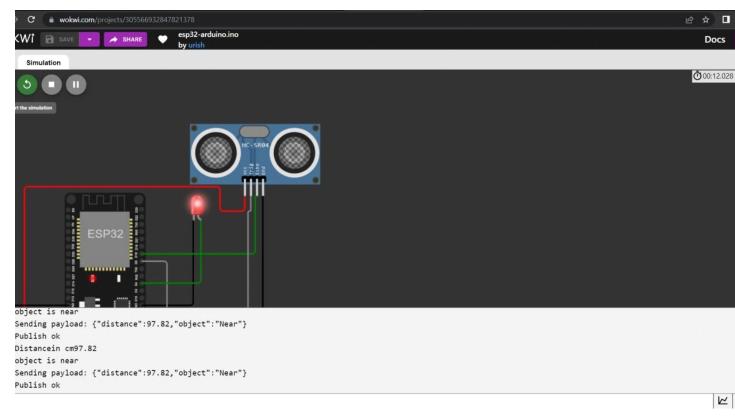
OUTPUT:



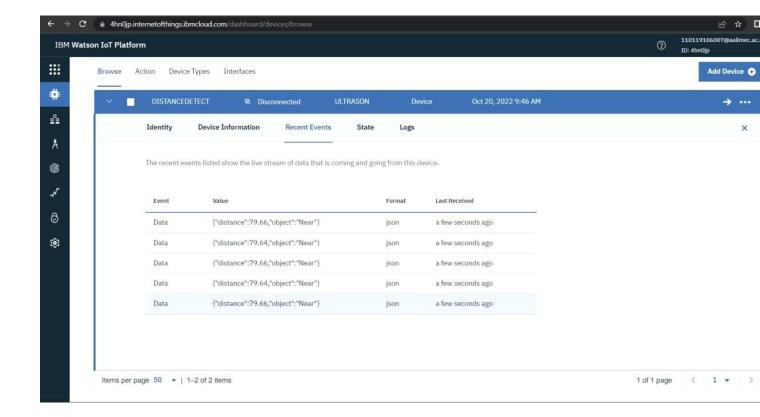
Data send to the IBM cloud device when the object is far



when object is near to the ultrasonic sensor



Data sent to the IBM Cloud Device when the object is near



https://wokwi.com/projects/305566932847821378