## ASSIGNMENT-4 DISTANCE DETECTION USING ULTRASONIC SENSOR

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Maximum Marks	2 Marks

## Question1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

## CODE:

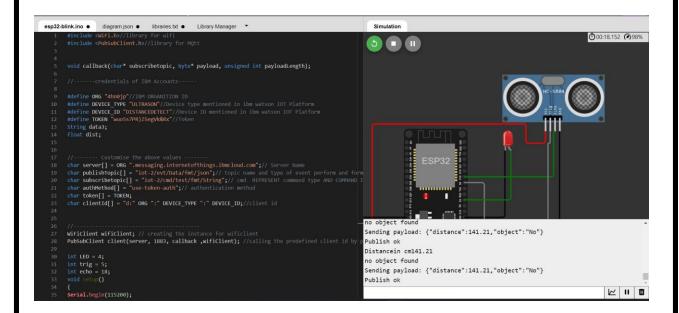
```
#include a minclude sinclude sinclude
```

```
esp32-blink.ino
                  diagram.json •
                                   libraries.txt ●
                                                  Library Manager *
       pinMode(trig,OUTPUT);
       pinMode(echo,INPUT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void loop()// Recursive Function
        digitalWrite(trig,LOW);
         digitalWrite(trig,HIGH);
         delayMicroseconds(10);
         digitalWrite(trig,LOW);
         float dur = pulseIn(echo,HIGH);
         float dist = (dur * 0.0343)/2;
         Serial.print ("Distancein cm");
         Serial.println(dist);
         PublishData(dist);
         delay(1000);
         if (!client.loop()) {
         mqttconnect();
       void PublishData(float dist) {
         mqttconnect();//function call for connecting to ibm
```

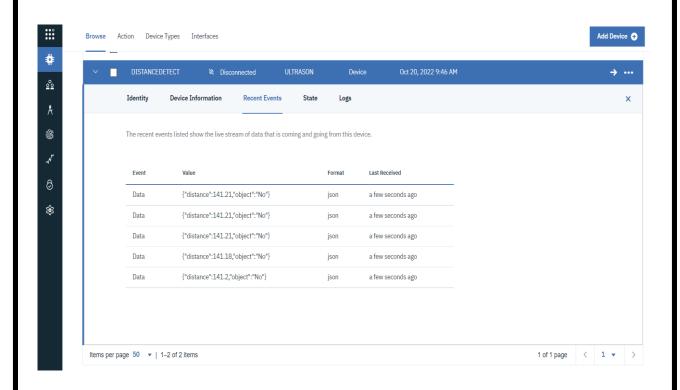
```
| creating the String in in form JSon to update the data to ibm cloud
| "/
| String object;
| if (dist cloe) {
| digitalWrite(LED,HIGH);
| Serial.println("object is near");
| object = "Near";
| }
| else {
| digitalWrite(LED,LOM);
| Serial.println("no object found");
| object = "No";
| }
| String payload = "{\"distance\":";
| payload += dist;
| payload += dist;
| payload += "," "\"object\":\"";
| payload += object;
| payload += "\")";
| Serial.println("Sending payload: ");
| Serial.println(payload);
```

```
esp32-blink.ino •
                   diagram.json •
                                   libraries.txt ●
                                                  Library Manager
         WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
         while (WiFi.status() != WL_CONNECTED) {
           delay(500);
           Serial.print(".");
         Serial.println("");
         Serial.println("WiFi connected");
         Serial.println("IP address: ");
         Serial.println(WiFi.localIP());
       void initManagedDevice() {
         if (client.subscribe(subscribetopic)) {
           Serial.println((subscribetopic));
           Serial.println("subscribe to cmd OK");
           Serial.println("subscribe to cmd FAILED");
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
         Serial.print("callback invoked for topic: ");
 148
         Serial.println(subscribetopic);
         for (int i = 0; i < payloadLength; i++) {</pre>
           data3 += (char)payload[i];
```

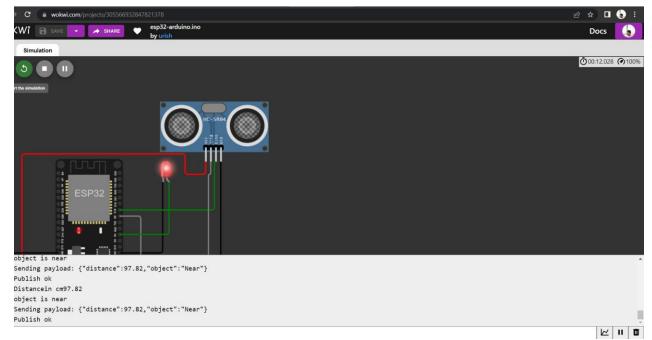
## **OUTPUT:**



Data send to the IBM cloud device when the object is far



when object is near to the ultrasonic sensor



Data sent to the IBM Cloud Device when the object is near

