ASSIGNMENT-4 REAL-TIME RIVER WATER QUALITY MONITORING AND CONTROL SYSTEM

Date	20 October 2022
Team ID	PNT2022TMID10999
Name	HARINIE S
Student Roll	811519106050
Number	
Maximum Marks	2 Marks

QUESTION 1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

CODE:

```
esp32-blink.ino
                 diagram.json •
                                   libraries.txt •
                                                  Library Manager
       pinMode(trig,OUTPUT);
       pinMode(echo,INPUT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void loop()// Recursive Function
        digitalWrite(trig,LOW);
         digitalWrite(trig,HIGH);
         delayMicroseconds(10);
         digitalWrite(trig,LOW);
         float dur = pulseIn(echo,HIGH);
         float dist = (dur * 0.0343)/2;
         Serial.print ("Distancein cm");
         Serial.println(dist);
         PublishData(dist);
         delay(1000);
         if (!client.loop()) {
           mqttconnect();
       void PublishData(float dist) {
         mqttconnect();//function call for connecting to ibm
```

```
esp32-blink.ino •
                   diagram.json •
                                    libraries.txt ●
                                                    Library Manager
          WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
          while (WiFi.status() != WL CONNECTED) {
            delay(500);
            Serial.print(".");
         Serial.println("");
Serial.println("WiFi connected");
          Serial.println("IP address: ");
         Serial.println(WiFi.localIP());
        void initManagedDevice() {
         if (client.subscribe(subscribetopic)) {
            Serial.println((subscribetopic));
            Serial.println("subscribe to cmd OK");
           Serial.println("subscribe to cmd FAILED");
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
          Serial.print("callback invoked for topic: ");
 148
          Serial.println(subscribetopic);
          for (int i = 0; i < payloadLength; i++) {</pre>
            data3 += (char)payload[i];
```

```
esp32-blink.lno  diagram.json  libranes.bt  Library Manager  void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)

143
144 void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)

145
146
147 Serial.print("callback invoked for topic: ");

148 Serial.println(subscribetopic);

159 | //Serial.println(char)payload[i]);

150 | //Serial.println("data: "+ data3);

151 | // Serial.println("data: "+ data3);

152 | // |
153 | // |
154 | // Serial.println(data3);

155 | // |
156 | // |
157 | // Serial.println(data3);

158 | // digitalbrite(LED,HIGH);

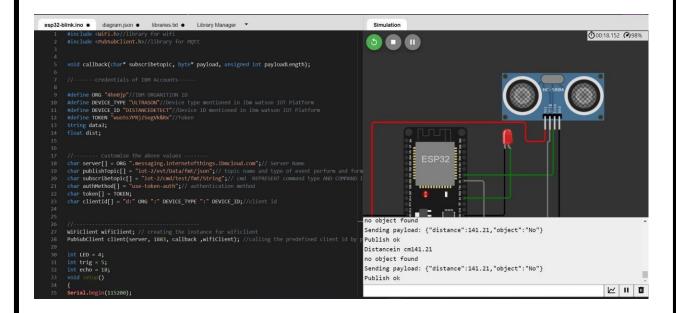
159 |
160 | // |
161 | // Serial.println(data3);

165 | // digitalbrite(LED,LOW);

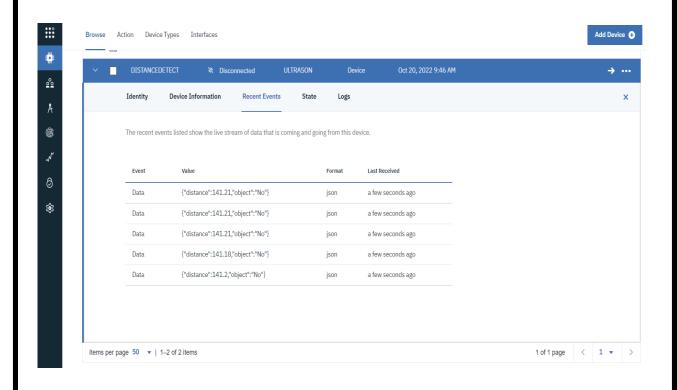
166 | // |
167 | // |
168 | data3="";

169 |
170 | 171 | ]
```

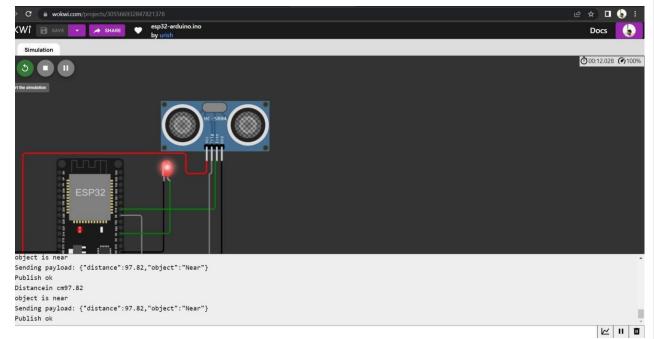
OUTPUT:



Data send to the IBM cloud device when the object is far



when object is near to the ultrasonic sensor



Data sent to the IBM Cloud Device when the object is near

