

SPRINT4 PY CODE.py - C:/Users/devadharshini/Desktop/New folder (2)/SPRINT4 PY CODE.py (3.9.6)

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```
import serial
import time
import csv
import numpy as np
import matplotlib.pyplot as plt
ser = serial.Serial('/COM6',9600)
ser_bytes = ser.readline(10)
print (ser_bytes)
ser.flushInput()
while True:
    try:
        ser_bytes = ser.readline()
        decoded_bytes = float(ser_bytes[0:len(ser_bytes)-2].decode("utf-8"))
        print(decoded_bytes)
        temp = float(decoded_bytes(1:3))
        turb = float(decoded_bytes(4:6))
        pH = float(decoded_bytes(6:8))
        with open("test_data.csv","a") as f:
            writer = csv.writer(f,delimiter=",")
            writer.writerow([time.time(),decoded_bytes])
    except:
        print("Keyboard Interrupt")
        ser.close()
        break()
t = np.arange(0.0, 2.0, 0.01)
s = 1 + np.sin(2*np.pi*t)
plt.plot(t, s)
plt.xlabel('time (s)')
plt.ylabel('Celsiusus (C)')
plt.title('Temperature')
plt.grid(True)
plt.savefig("Temperature.png")
plt.show()
Serial.begin(9600);
sensors.begin();
int sensorValue = analogRead(A1);
voltage = sensorValue * (5.0 / 1024.0);
}
void loop(void)
{
    sensors.requestTemperatures();
    Celcius=sensors.getTempCByIndex(0);
    Fahrenheit=sensors.toFahrenheit(Celcius);
    for(int i=0;i<10;i++)
    {
        buf[i]=analogRead(analogInPin);
        delay(10);
    }
    for(int i=0;i<9;i++)
    {
```

```

{
    for(int j=i+1;j<10;j++)
    {
        if(buf[i]>buf[j])
        {
            temp=buf[i];
            buf[i]=buf[j];
            buf[j]=temp;
        }
    }
n = 256
X = np.linspace(-np.pi, np.pi, 256, endpoint=True)
C,S = np.cos(X), np.sin(X)
plt.plot(X, C)
plt.plot(X, S)
plt.show()
print ("Visualization of real time sensor Data.")
print("/n")
while True:
    try:
        ser_bytes = ser.readline()
        decoded_bytes = float(ser_bytes[0:len(ser_bytes)-2].decode("utf-8"))
        print(decoded_bytes)
    temp = float(decoded_bytes(1:3))
    turb = float(decoded_bytes(4:6))
    pH = float(decoded_bytes(6:8))
    with open("test_data.csv","a") as f:
        writer = csv.writer(f,delimiter=",")
        writer.writerow([time.time(),decoded_bytes])
    except:
        print("Keyboard Interrupt")
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        break()
t = np.arange(0.0, 2.0, 0.01)
s = 1 + np.sin(2*np.pi*t)
plt.plot(t, s)

```