ASSIGNMENT-4 DISTANCE DETECTION USING ULTRASONIC SENSOR

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Maximum Marks	2 Marks

Question1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

```
#include #i
```

CODE:

```
esp32-blink.ino
                 diagram.json •
                                 libraries.txt ●
                                               Library Manager
       pinMode(trig,OUTPUT);
       pinMode(echo,INPUT);
       pinMode(LED, OUTPUT);
       delay(10);
      wificonnect();
       mqttconnect();
       void loop()// Recursive Function
        digitalWrite(trig,LOW);
        digitalWrite(trig,HIGH);
        delayMicroseconds(10);
        digitalWrite(trig,LOW);
        float dur = pulseIn(echo,HIGH);
        float dist = (dur * 0.0343)/2;
        Serial.print ("Distancein cm");
        Serial.println(dist);
        PublishData(dist);
        delay(1000);
        if (!client.loop()) {
          mqttconnect();
        }
       /*....retrieving to Cloud......
       void PublishData(float dist) {
        mqttconnect();//function call for connecting to ibm
```

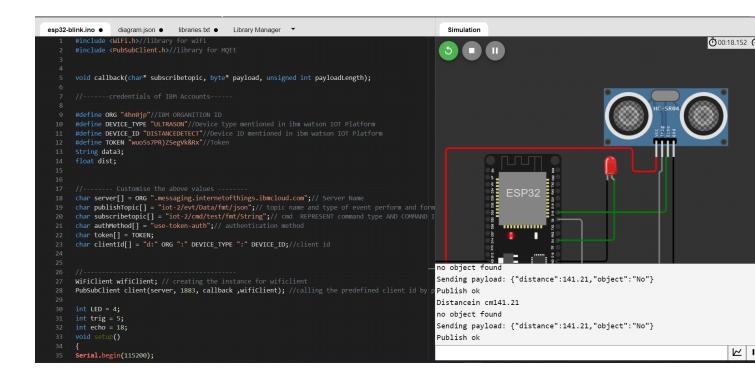
creating the String in in form JSon to update the data to ibm cloud

```
Library Manager ▼
esp32-blink.ino •
                     diagram.json ●
                                        libraries.txt ●
           if (client.publish(publishTopic, (char*) payload.c_str())) {
             Serial.println("Publish ok");// if it successfully upload data on the cloud then it will print publish ok in Serial monitor or else it will print publish fai
             Serial.println("Publish failed");
         void mqttconnect() {
          if (!client.connected()) {
             Serial.print("Reconnecting client to ");
Serial.println(server);
             while (!!!client.connect(clientId, authMethod, token)) {
                delay(500);
              initManagedDevice();
               Serial.println();
        void wificonnect() //function defination for wificonnect
           Serial.print("Connecting to ");
           WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
while (WiFi.status() != WL_CONNECTED) {
             delay(500);
Serial.print(".");
           Serial.println("");
Serial.println("WiFi connected");
Serial.println("IP address: ");
Serial.println(WiFi.localIP());
```

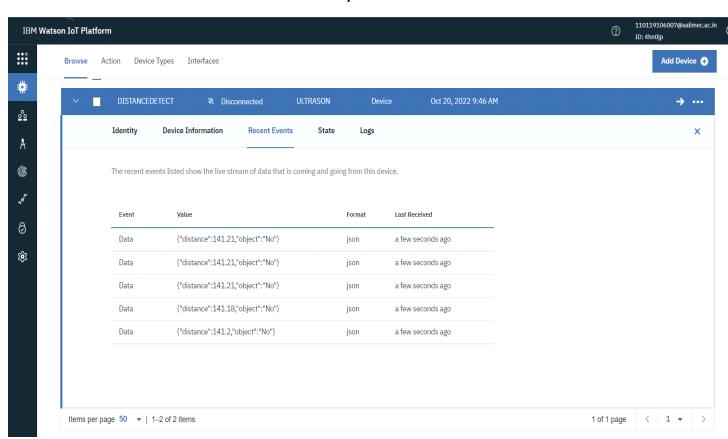
```
esp32-blink.ino •
                   diagram.json •
                                    libraries.txt ●
                                                   Library Manager
         WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
         while (WiFi.status() != WL_CONNECTED) {
            delay(500);
 126
            Serial.print(".");
 128
         Serial.println("");
         Serial.println("WiFi connected");
         Serial.println("IP address: ");
         Serial.println(WiFi.localIP());
       void initManagedDevice() {
         if (client.subscribe(subscribetopic)) {
           Serial.println((subscribetopic));
 138
            Serial.println("subscribe to cmd OK");
         } else {
            Serial.println("subscribe to cmd FAILED");
 144
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
         Serial.print("callback invoked for topic: ");
         Serial.println(subscribetopic);
 148
         for (int i = 0; i < payloadLength; i++) {</pre>
           data3 += (char)payload[i];
```

```
esp32-blink.ino •
                    diagram.json •
                                     libraries.txt ●
                                                     Library Manager
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
          Serial.print("callback invoked for topic: ");
 148
          Serial.println(subscribetopic);
          for (int i = 0; i < payloadLength; i++) {</pre>
            data3 += (char)payload[i];
          }
       data3="";
 170
```

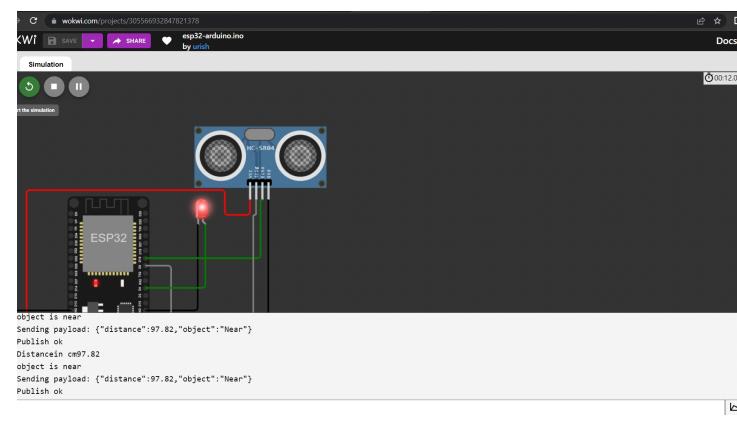
OUTPUT:



Data send to the IBM cloud device when the object is far



when object is near to the ultrasonic sensor



Data sent to the IBM Cloud Device when the object is near

