ASSIGNMENT-4

Hazardous Area Monitoring For Industrial Plant Powered By IOT

Date	20October2022
TeamID	PNT2022TMID10955
Name	HARISH K
StudentRollNumber	811519106051
MaximumMarks	2Marks

Question1:

Write code and connections in wokwiforul trasonic sensor. Whenever distance is less than 100 cmss end "alert" to ibmcloud and display indevice recent events.

CODE:

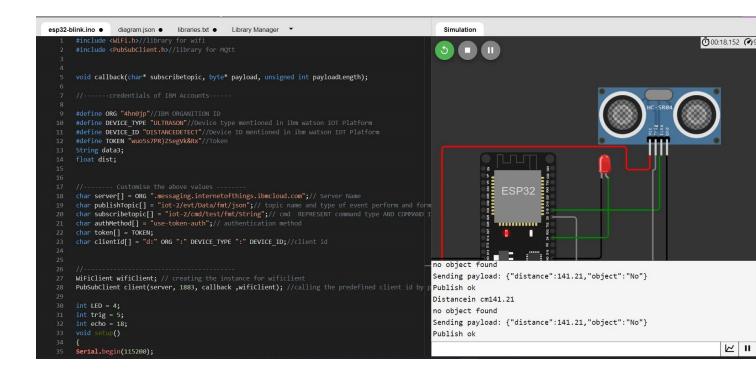
```
esp32-blink.ino
                   diagram.json •
                                                  Library Manager
                                   libraries.txt •
       pinMode(trig,OUTPUT);
       pinMode(echo,INPUT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void loop()// Recursive Function
       {
        digitalWrite(trig,LOW);
         digitalWrite(trig,HIGH);
         delayMicroseconds(10);
         digitalWrite(trig,LOW);
         float dur = pulseIn(echo,HIGH);
         float dist = (dur * 0.0343)/2;
         Serial.print ("Distancein cm");
         Serial.println(dist);
         PublishData(dist);
         delay(1000);
         if (!client.loop()) {
           mqttconnect();
         }
       void PublishData(float dist) {
         mqttconnect();//function call for connecting to ibm
         creating the String in in form JSon to update the data to ibm cloud
  70
```

```
esp32-blink.ino ● diagram.json ●
                                      libraries.txt ●
                                                      Library Manager ▼
          if (client.publish(publishTopic, (char*) payload.c_str())) {
           Serial.println("Publish ok");// if it sucessfully upload data on the cloud then it will print publish ok in Serial monitor or else it will print publish failed
            Serial.println("Publish failed");
        void mqttconnect() {
         if (!client.connected()) {
            Serial.print("Reconnecting client to ");
Serial.println(server);
            while (!!!client.connect(clientId, authMethod, token)) {
               delay(500);
             initManagedDevice();
             Serial.println();
       void wificonnect() //function defination for wificonnect
          Serial.print("Connecting to ");
          WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
while (WiFi.status() != WL_CONNECTED) {
            delay(500);
          Serial.println("");
          Serial.println("WiFi connected");
          Serial.println("IP address: ");
Serial.println(WiFi.localIP());
```

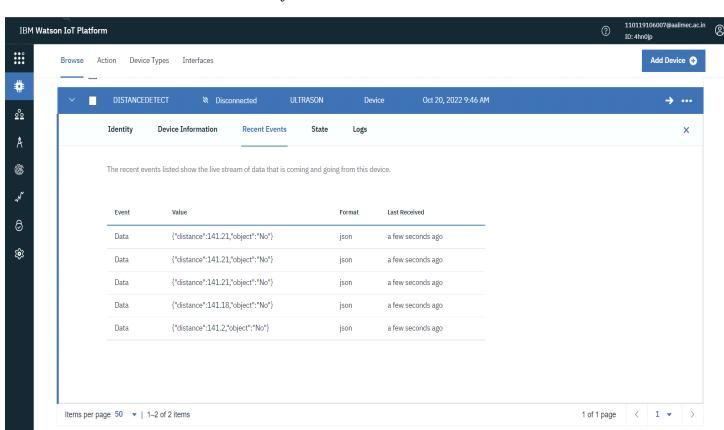
```
esp32-blink.ino •
                   diagram.json •
                                    libraries.txt •
                                                   Library Manager
         WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
         while (WiFi.status() != WL CONNECTED) {
 126
           delay(500);
           Serial.print(".");
 128
         Serial.println("");
         Serial.println("WiFi connected");
         Serial.println("IP address: ");
         Serial.println(WiFi.localIP());
       void initManagedDevice() {
 136
         if (client.subscribe(subscribetopic)) {
           Serial.println((subscribetopic));
           Serial.println("subscribe to cmd OK");
         } else {
           Serial.println("subscribe to cmd FAILED");
         }
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
         Serial.print("callback invoked for topic: ");
         Serial.println(subscribetopic);
 148
         for (int i = 0; i < payloadLength; i++) {</pre>
           data3 += (char)payload[i];
         }
 154
```

```
esp32-blink.ino •
                    diagram.json •
                                     libraries.txt ●
                                                     Library Manager
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
          Serial.print("callback invoked for topic: ");
 148
          Serial.println(subscribetopic);
          for (int i = 0; i < payloadLength; i++) {</pre>
            data3 += (char)payload[i];
       data3="";
 170
       }
```

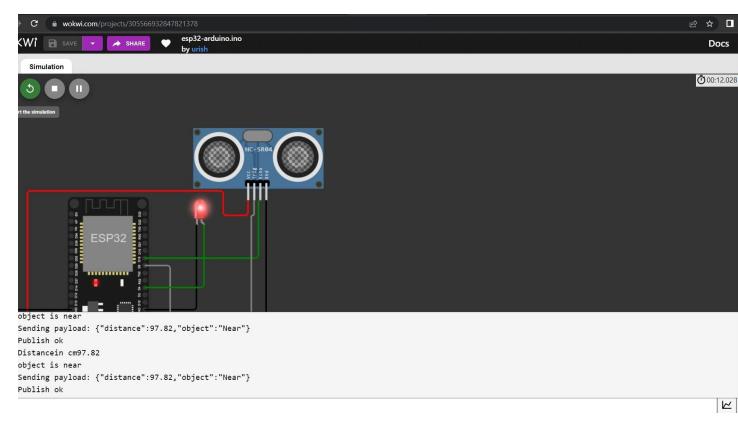
OUTPUT:



DatasendtotheIBMclouddevicewhentheobjectisfar



when object is near to the ultrasonic sensor



Datas ent to the IBM Cloud Device when the object is near

