# ASSIGNMENT-4 DISTANCE DETECTION USING ULTRASONIC SENSOR

Date	20 October 2022
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Maximum Marks	2 Marks

### Question1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

### WOKWI LINK:

https://wokwi.com/projects/346577411886809683

#### CODE:

```
pinMode(trig,OUTPUT);
pinMode(echo,INPUT);
pinMode(LED, OUTPUT);
delay(10);
wificonnect();
mqttconnect();
void loop()// Recursive Function
 digitalWrite(trig,LOW);
  digitalWrite(trig,HIGH);
  delayMicroseconds(10);
  digitalWrite(trig,LOW);
  float dur = pulseIn(echo,HIGH);
  float dist = (dur * 0.0343)/2;
Serial.print ("Distancein cm");
  Serial.println(dist);
  PublishData(dist);
  delay(1000);
  if (!client.loop()) {
    mqttconnect();
void PublishData(float dist) {
  mqttconnect();//function call for connecting to ibm
```

```
WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
        while (WiFi.status() != WL CONNECTED) {
          delay(500);
          Serial.print(".");
        Serial.println("");
        Serial.println("WiFi connected");
        Serial.println("IP address: ");
        Serial.println(WiFi.localIP());
      void initManagedDevice() {
       if (client.subscribe(subscribetopic)) {
          Serial.println((subscribetopic));
          Serial.println("subscribe to cmd OK");
          Serial.println("subscribe to cmd FAILED");
      void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
        Serial.print("callback invoked for topic: ");
        Serial.println(subscribetopic);
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        for (int i = 0; i < payloadLength; i++) {</pre>
          data3 += (char)payload[i];
```

```
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)

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serial.println(callback invoked for topic: ");

serial.println(subscribetopic);

for (int i = 0; i < payloadLength; i++) {
    //serial.print((char)payload[i]);
    data3 += (char)payload[i];
}

// Serial.println("data: "+ data3);

// if(data3=="Near")

// // serial.println(data3);

// digitalWrite(LED,HIGH);

// else
// |
// serial.println(data3);
// digitalWrite(LED,LOW);

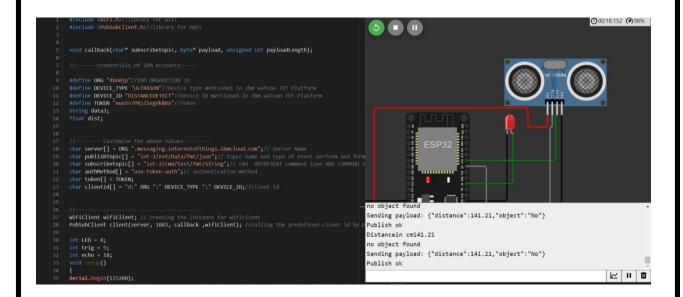
// data3=="";

// data3="";

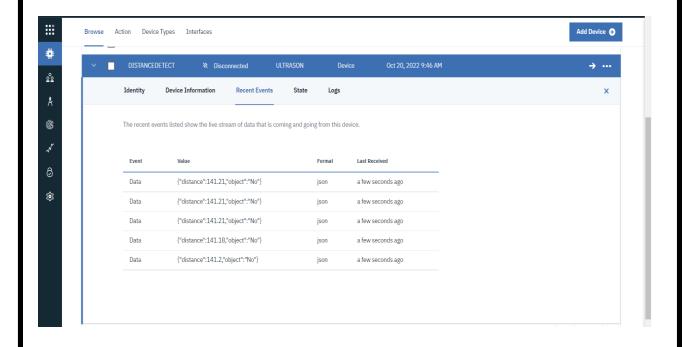
// data3=""/*

/
```

## **OUTPUT:**

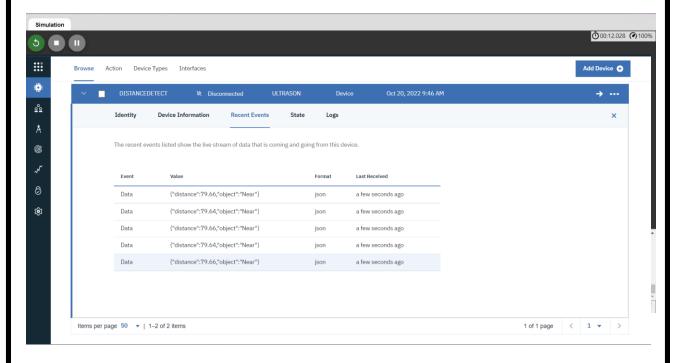


Data send to the IBM cloud device when the object is far



when object is near to the ultrasonic sensor

Data sent to the IBM Cloud Device when the object is near



https://wokwi.com/projects/346577411886809683