ASSIGNMENT-4 DISTANCE DETECTION USING ULTRASONIC SENSOR

Ouestion1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

WOKWI LINK:

https://wokwi.com/projects/346668487286981204

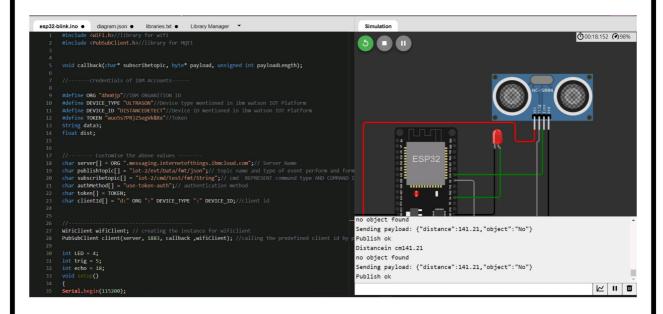
CODE:

```
#include #i
```

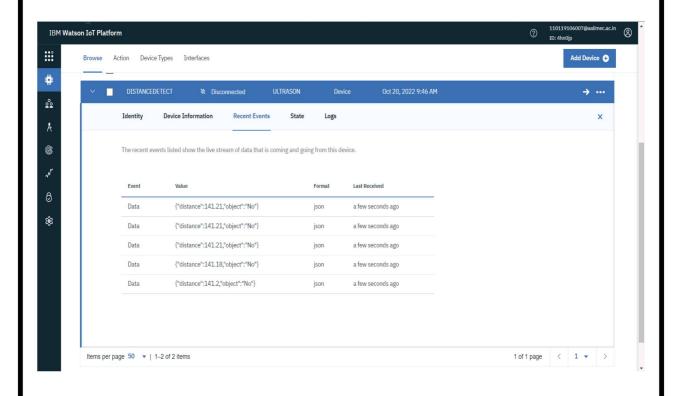
```
esp32-blink.ino •
                  diagram.json •
                                   libraries.txt ●
                                                  Library Manager
       pinMode(trig,OUTPUT);
       pinMode(echo,INPUT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void loop()// Recursive Function
        digitalWrite(trig,LOW);
         digitalWrite(trig,HIGH);
         delayMicroseconds(10);
         digitalWrite(trig,LOW);
         float dur = pulseIn(echo,HIGH);
         float dist = (dur * 0.0343)/2;
         Serial.print ("Distancein cm");
         Serial.println(dist);
         PublishData(dist);
         delay(1000);
         if (!client.loop()) {
         mqttconnect();
       void PublishData(float dist) {
         mqttconnect();//function call for connecting to ibm
```

```
esp32-blink.ino •
                   diagram.ison •
                                     libraries txt
                                                    Library Manager
         WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
          while (WiFi.status() != WL_CONNECTED) {
           delay(500);
         Serial.println("");
Serial.println("WiFi connected");
         Serial.println("IP address: ");
         Serial.println(WiFi.localIP());
        void initManagedDevice() {
         if (client.subscribe(subscribetopic)) {
           Serial.println((subscribetopic));
           Serial.println("subscribe to cmd OK");
         } else {
    Serial.println("subscribe to cmd FAILED");
         }
        void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
         Serial.print("callback invoked for topic: ");
         Serial.println(subscribetopic);
 148
         for (int i = 0; i < payloadLength; i++) {</pre>
            data3 += (char)payload[i];
```

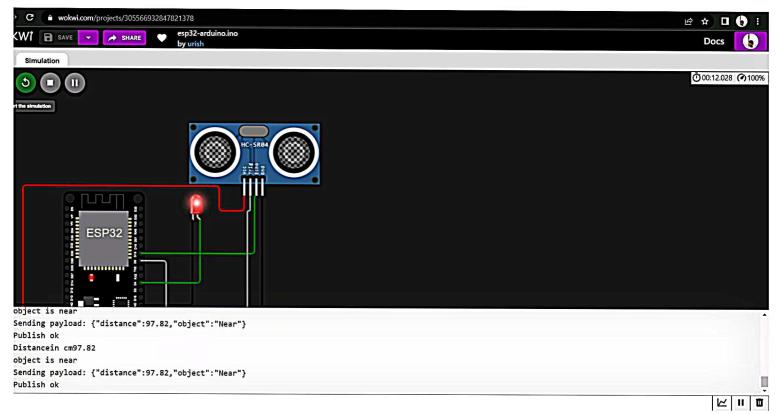
OUTPUT:



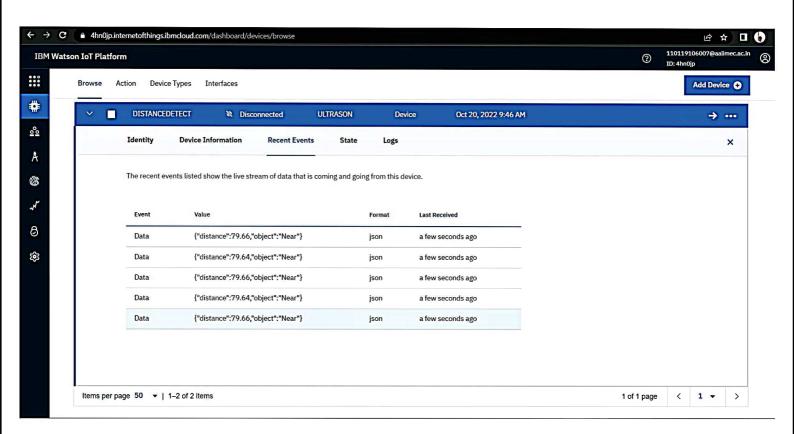
Data send to the IBM cloud device when the object is far



when object is near to the ultrasonic sensor



Data sent to the IBM Cloud Device when the object is near



https://wokwi.com/projects/346668487286981204