ASSIGNMENT-4 DISTANCE DETECTION USING ULTRASONIC SENSOR

Date	20 October 2022
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Maximum Marks	2 Marks

Question1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

WOKWI LINK:

https://wokwi.com/projects/305566932847821378

CODE:

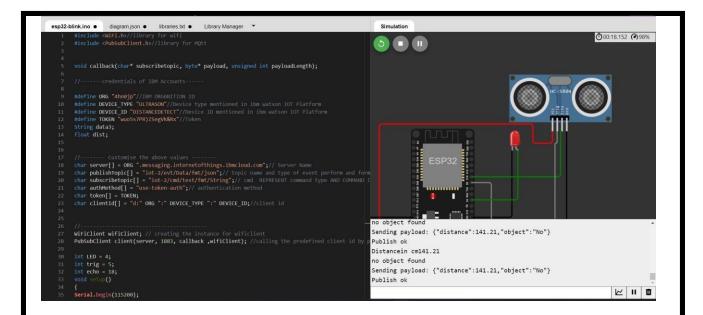
```
esp32-blink.ino
                  diagram.json •
                                   libraries.txt ●
                                                  Library Manager
       pinMode(trig,OUTPUT);
       pinMode(echo,INPUT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void loop()// Recursive Function
        digitalWrite(trig,LOW);
         digitalWrite(trig,HIGH);
         delayMicroseconds(10);
         digitalWrite(trig,LOW);
         float dur = pulseIn(echo,HIGH);
         float dist = (dur * 0.0343)/2;
         Serial.print ("Distancein cm");
         Serial.println(dist);
         PublishData(dist);
         delay(1000);
         if (!client.loop()) {
         mqttconnect();
       void PublishData(float dist) {
         mqttconnect();//function call for connecting to ibm
```

```
| creating the String in in form JSon to update the data to ibm cloud
| "/
| String object; | if (dist <100) |
| {
| digitalWrite(LED,HIGH); |
| Serial.println("object is near"); |
| object = "Near"; |
| }
| else | |
| digitalWrite(LED,LOM); |
| Serial.println("no object found"); |
| object = "No"; |
| }
| String payload = "{\"distance\":"; |
| payload += dist; |
| payload += "," "\"object\":\""; |
| payload += "\""; |
| payload += "\""; |
| payload += "\""; |
| Serial.print("Sending payload: "); |
| Serial.print("Sending payload); |
| Serial.println(payload); |
```

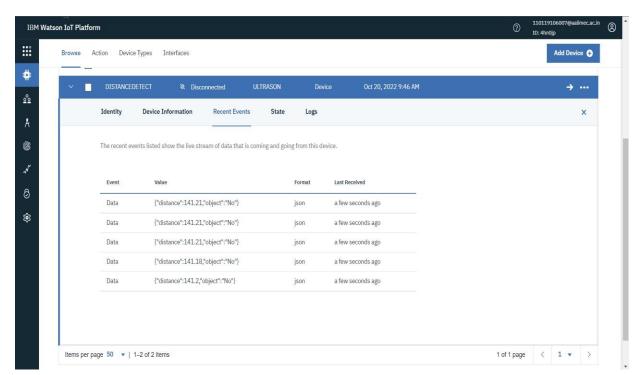
```
esp32-blink.ino
                   diagram.json •
                                    libraries.txt ●
                                                   Library Manager
          WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
          while (WiFi.status() != WL_CONNECTED) {
            delay(500);
            Serial.print(".");
         Serial.println("");
Serial.println("WiFi connected");
         Serial.println("IP address: ");
         Serial.println(WiFi.localIP());
        void initManagedDevice() {
         if (client.subscribe(subscribetopic)) {
            Serial.println((subscribetopic));
            Serial.println("subscribe to cmd OK");
            Serial.println("subscribe to cmd FAILED");
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
          Serial.print("callback invoked for topic: ");
          Serial.println(subscribetopic);
 148
          for (int i = 0; i < payloadLength; i++) {</pre>
            data3 += (char)payload[i];
```

```
esp32-blink.ino
                   diagram.json •
                                    libraries.txt ●
                                                    Library Manager
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
         Serial.print("callback invoked for topic: ");
 148
         Serial.println(subscribetopic);
          for (int i = 0; i < payloadLength; i++) {</pre>
           data3 += (char)payload[i];
       data3="";
```

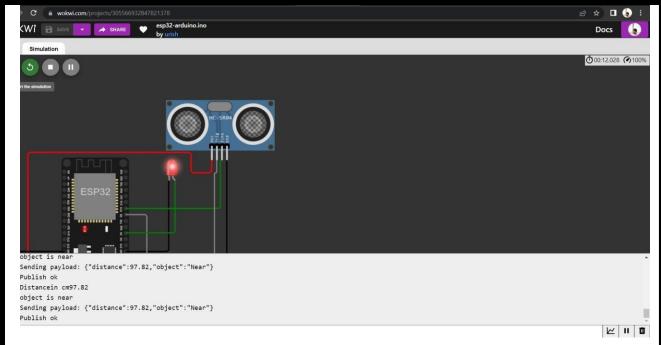
OUTPUT:



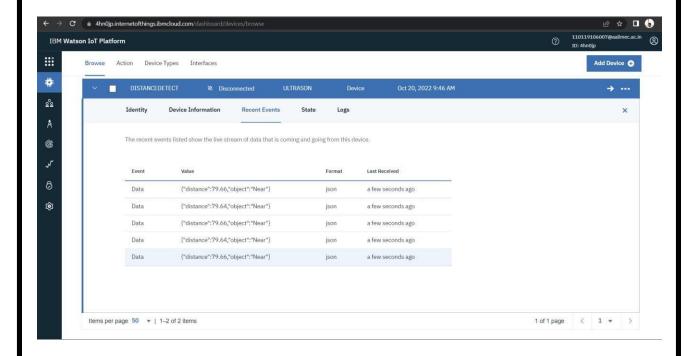
Data send to the IBM cloud device when the object is far



when object is near to the ultrasonic sensor



Data sent to the IBM Cloud Device when the object is near



https://wokwi.com/projects/305566932847821378