

SPRINT 2

TEAM ID PNT2022TMID47006

CODE :

```
#include <WiFi.h> // library for wifi

#include <PubSubClient.h> // library for MQTT

#include <LiquidCrystal_I2C.h>

LiquidCrystal_I2C lcd(0x27, 20, 4);

//----- credentials of IBM Accounts -----

// IBM organisation id

#define DEVICE_TYPE "abcd" // Device type mentioned in ibm watson iot platform

#define DEVICE_ID "1234" // Device ID mentioned in ibm watson iot platform

#define TOKEN "12345678" // Token

//----- customise above values -----

char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; // server name

char publishTopic[] = "iot-2/evt/data/fmt/json"; // topic name and type of event
perform and format in

which data to be send

char topic[] = "iot-2/cmd/led/fmt/String"; // cmd Represent type and command is test
format of

strings

char authMethod[] = "use-token-auth"; // authentication method

char token[] = TOKEN;

char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID; //Client id

//-----

WiFiClient wifiClient; // creating instance for wificlient
```



```
PubSubClient client(server, 1883, wifiClient);

#define ECHO_PIN 12

#define TRIG_PIN 13

float dist;

void setup()

{

  Serial.begin(115200);

  pinMode(LED_BUILTIN, OUTPUT);

  pinMode(TRIG_PIN, OUTPUT);

  pinMode(ECHO_PIN, INPUT);

  //pir pin

  #define ORG "wjmfdn"

  pinMode(34, INPUT);

  //ledpins

  pinMode(23, OUTPUT);

  pinMode(2, OUTPUT);

  pinMode(4, OUTPUT);

  pinMode(15, OUTPUT);

  lcd.init();

  lcd.backlight();

  lcd.setCursor(1, 0);

  lcd.print("");

  wifiConnect();

  mqttConnect();

}

float readcmCM()

{
```



```

digitalWrite(TRIG_PIN, LOW);

delayMicroseconds(2);

digitalWrite(TRIG_PIN, HIGH);

delayMicroseconds(10);

digitalWrite(TRIG_PIN, LOW);

int duration = pulseIn(ECHO_PIN, HIGH);

return duration * 0.034 / 2;

}

void loop()

{

  lcd.clear();

  publishData();

  delay(500);

  if (!client.loop())

  {

    mqttConnect(); // function call to connect to IBM

  }

}

/* -----retrieving to cloud-----*/

void wifiConnect()

{

  Serial.print("Connecting to ");

  Serial.print("Wifi");

  WiFi.begin("Wokwi-GUEST", "", 6);

  while (WiFi.status() != WL_CONNECTED)

  {

    delay(500);

```



```

Serial.print(".");
}

Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
}

void mqttConnect()
{
  if (!client.connected())
  {
    Serial.print("Reconnecting MQTT client to ");
    Serial.println(server);
    while (!client.connect(clientId, authMethod, token))
    {
      Serial.print(".");
      delay(500);
    }
    initManagedDevice();
    Serial.println();
  }
}

void initManagedDevice()
{
  if (client.subscribe(topic))
  {
    Serial.println("IBM subscribe to cmd OK");
  }
  else

```



```

{
  Serial.println("subscribe to cmd FAILED");
}
}

void publishData()
{
  float cm = readcmCM();
  if(digitalRead(34)) //pir motion detection
  {
    Serial.println("Motion Detected");
    Serial.println("Lid Opened");
    digitalWrite(15, HIGH);
    if(digitalRead(34)== true)
    {
      if(cm <= 60) //Bin level detection
      {
        digitalWrite(2, HIGH);
        Serial.println("High Alert!!!,Trash bin is about to be full");
        Serial.println("Lid Closed");
        lcd.print("Full! Don't use");
        delay(2000);
        lcd.clear();
        digitalWrite(4, LOW);
        digitalWrite(23, LOW);
      }
      else if(cm > 60 && cm < 120)
      {

```



```
digitalWrite(4, HIGH);  
  
Serial.println("Warning!!,Trash is about to cross 50% of bin level");  
  
digitalWrite(2, LOW);  
  
digitalWrite(23, LOW);  
  
}  
  
else if(cm > 120)  
{  
  
digitalWrite(23, HIGH);  
  
Serial.println("Bin is available");  
  
digitalWrite(2,LOW);  
  
digitalWrite(4, LOW);  
  
}  
  
delay(10000);  
  
Serial.println("Lid Closed");  
  
}  
  
else  
{  
  
Serial.println("No motion detected");  
  
digitalWrite(2, LOW);  
  
digitalWrite(15, LOW);  
  
digitalWrite(4, LOW);  
  
digitalWrite(23, LOW);  
  
}  
  
}  
  
else  
{  
  
digitalWrite(15, LOW);
```



```

}

if(cm <= 60)
{
digitalWrite(21,HIGH);

String payload = "{\"High_Alert\":\"";

payload += cm;

payload += " }";

Serial.print("\n");

Serial.print("Sending payload: ");

Serial.println(payload);

if (client.publish(publishTopic, (char*) payload.c_str())) // if data is uploaded to cloud
successfully,prints publish ok

else prints publish failed

{

Serial.println("Publish OK");

}

}

else if(cm <= 120)
{

digitalWrite(22,HIGH);

String payload = "{\"Warning\":\"";

payload += cm ;

payload += " }";

Serial.print("\n");

Serial.print("Sending payload: ");

Serial.println(payload);

if(client.publish(publishTopic, (char*) payload.c_str()))

{

```



```
Serial.println("Publish OK");  
}  
else  
{  
Serial.println("Publish FAILED");  
}  
}  
else  
{  
Serial.println();  
}  
float inches = (cm / 2.54); //print on lcd  
lcd.setCursor(0,0);  
lcd.print("Inches");  
lcd.setCursor(4,0);  
lcd.setCursor(12,0);  
lcd.print("cm");  
lcd.setCursor(1,1);  
lcd.print(inches, 1);  
lcd.setCursor(11,1);  
lcd.print(cm, 1);  
lcd.setCursor(14,1);  
delay(1000);  
lcd.clear();  
}
```



CIRCUIT

