Assignment-4

Assignment Date	31.10.2022
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Maximum Marks	2 Marks

Question:

Write code and connections in wokwi for ultrasonic sensor.

Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

Solution:

Wokwi Link

https://wokwi.com/projects/346963035247608403

Code:

```
#include <WiFi.h>
#include <PubSubClient.h>

WiFiClient wifiClient;
String data3;

#define ORG "szro21"

#define DEVICE_TYPE "sangeedevicetype"

#define DEVICE_ID "sangeedeviceid"

#define TOKEN "0987654321"

#define speed 0.034

#define led 14

char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
```

```
char topic[] = "iot-2/cmd/command/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();
const int trigpin=4;
const int echopin=19;
String command;
String data="";
long duration;
float dist;
void setup()
{
Serial.begin(115200);
 pinMode(led, OUTPUT);
 pinMode(trigpin, OUTPUT);
 pinMode(echopin, INPUT);
wifiConnect();
 mqttConnect();
}
void loop()
{
 bool isNearby = dist < 100;
```

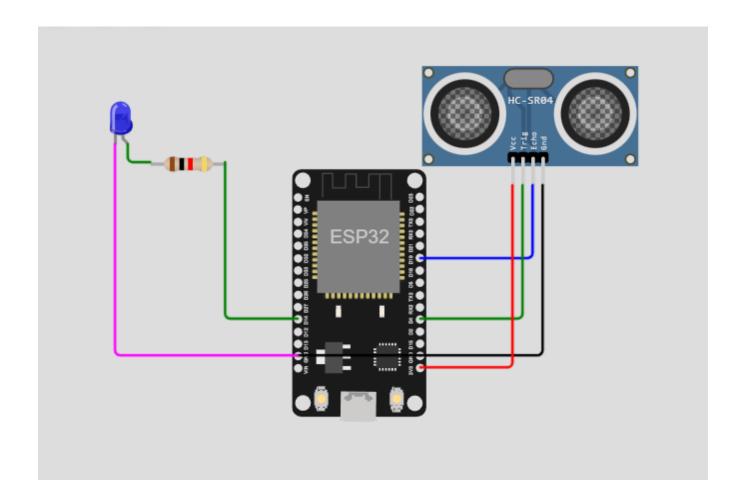
```
digitalWrite(led, isNearby);
 publishData();
 delay(500);
 if (!client.loop())
 {
  mqttConnect();
 }
}
void wifiConnect()
{
 Serial.print("Connecting to ");
 Serial.print("Wifi");
 WiFi.begin("Wokwi-GUEST", "", 6);
 while (WiFi.status() != WL_CONNECTED)
  delay(500);
  Serial.print(".");
 }
 Serial.print("WiFi connected, IP address: ");
 Serial.println(WiFi.localIP());
}
void mqttConnect()
{
 if (!client.connected())
  Serial.print("Reconnecting MQTT client to ");
  Serial.println(server);
```

```
while (!client.connect(clientId, authMethod, token))
  {
   Serial.print(".");
   delay(500);
  }
  initManagedDevice();
  Serial.println();
 }
}
void initManagedDevice()
{
 if (client.subscribe(topic))
  // Serial.println(client.subscribe(topic));
  Serial.println("IBM subscribe to cmd OK");
 }
 else
  {
  Serial.println("subscribe to cmd FAILED");
 }
}
void publishData()
{
 digitalWrite(trigpin,LOW);
 digitalWrite(trigpin,HIGH);
 delayMicroseconds(10);
 digitalWrite(trigpin,LOW);
 duration=pulseIn(echopin,HIGH);
 dist=duration*speed/2;
 if(dist<100)
```

```
{
 String payload = "{\"Alert Distance\":";
 payload += dist;
 payload += "}";
 Serial.print("\n");
 Serial.print("Sending payload: ");
 Serial.println(payload);
 if (client.publish(publishTopic, (char*) payload.c_str()))
 {
  Serial.println("Publish OK");
 }
}
 if(dist>101 && dist<150)
 {
 String payload = "{\"Normal distance\":";
 payload += dist;
 payload += "}";
 Serial.print("\n");
 Serial.print("Sending payload: ");
 Serial.println(payload);
 if(client.publish(publishTopic, (char*) payload.c_str()))
  {
  Serial.println("Warning crosses 110cm -- it automaticaly of the loop");
  digitalWrite(led,HIGH);
 }
 else
 {
  Serial.println("Publish FAILED");
```

```
}
}
}
 void callback(char* subscribeTopic, byte* payload, unsigned int payloadLength){
 Serial.print("callback invoked for topic:");
 Serial.println(subscribeTopic);
 for(int i=0; i<payloadLength; i++)</pre>
 {
  dist += (char)payload[i];
 }
 Serial.println("data:"+ data3);
 if(data3=="lighton")
  Serial.println(data3);
  digitalWrite(led,HIGH);
 }
 data3="";
}
```

Circuit Diagram:



Output:

