ASSIGNMENT-4
DISTANCE DETECTION USING ULTRASONIC SENSOR

Date	20 October 2022
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Maximum Marks	2 Marks

Question1 :

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

WOKWI LINK :

https://wokwi.com/projects/305566932847821378

CODE :

```
1   #include <WiFi.h>//library for wifi
2   #include <PubSubClient.h>//library for MQtt
3
4
5   void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);
6
7   //-------credentials of IBM Accounts------
8
9   #define ORG "4hn0jp"//IBM ORGANITION ID
10  #define DEVICE_TYPE "ULTRASON"//Device type mentioned in ibm watson IOT Platform
11  #define DEVICE_ID "DISTANCEDETECT"//Device ID mentioned in ibm watson IOT Platform
12  #define TOKEN "wuo5s7PR)ZSegVk&Rx"//Token
13  String data3;
14  float dist;
15
16
17  //-------- Customise the above values --------
18  char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name
19  char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of event perform and format in which data to be send
20  char subscribetopic[] = "iot-2/cmd/test/fmt/String";// cmd  REPRESENT command type AND COMMAND IS TEST OF FORMAT STRING
21  char authMethod[] = "use-token-auth";// authentication method
22  char token[] = TOKEN;
23  char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;//client id
24
25
26  //----------------------------------------
27  WiFiClient wifiClient; // creating the instance for wificlient
28  PubSubClient client(server, 1883, callback ,wifiClient); //calling the predefined client id by passing parameter like server id,portand wificredential
29
30  int LED = 4;
31  int trig = 5;
32  int echo = 18;
33  void setup()
34  {
35  Serial.begin(115200);
```

```
36    pinMode(trig,OUTPUT);
37    pinMode(echo,INPUT);
38    pinMode(LED, OUTPUT);
39    delay(10);
40    wificonnect();
41    mqttconnect();
42    }
43    void loop()// Recursive Function
44    {
45
46     digitalWrite(trig,LOW);
47      digitalWrite(trig,HIGH);
48      delayMicroseconds(10);
49      digitalWrite(trig,LOW);
50      float dur = pulseIn(echo,HIGH);
51      float dist = (dur * 0.0343)/2;
52      Serial.print ("Distancein cm");
53      Serial.println(dist);
54
55
56      PublishData(dist);
57      delay(1000);
58      if (!client.loop()) {
59        mqttconnect();
60      }
61    }
62
63
64
65    /*................................retrieving to Cloud............................*/
66
67    void PublishData(float dist) {
68      mqttconnect();//function call for connecting to ibm
69      /*
70        creating the String in in form JSon to update the data to ibm cloud
```

```
        |  creating the String in in form JSon to update the data to ibm cloud
        */
        String object;
        if (dist <100)
        {
            digitalWrite(LED,HIGH);
            Serial.println("object is near");
            object = "Near";
        }
        else
        {
            digitalWrite(LED,LOW);
            Serial.println("no object found");
            object = "No";
        }

        String payload = "{\"distance\":";
        payload += dist;
        payload += "," "\"object\":\"";
        payload += object;
        payload += "\"}";


        Serial.print("Sending payload: ");
        Serial.println(payload);



```

esp32-blink.ino ●   diagram.json ●   libraries.txt ●   Library Manager ▾

```
 98
 99    if (client.publish(publishTopic, (char*) payload.c_str())) {
100        Serial.println("Publish ok");// if it sucessfully upload data on the cloud then it will print publish ok in Serial monitor or else it will print publish failed
101    } else {
102        Serial.println("Publish failed");
103    }
104
105 }
106 void mqttconnect() {
107    if (!client.connected()) {
108        Serial.print("Reconnecting client to ");
109        Serial.println(server);
110        while (!!!client.connect(clientId, authMethod, token)) {
111            Serial.print(".");
112            delay(500);
113        }
114
115        initManagedDevice();
116        Serial.println();
117    }
118 }
119 void wificonnect() //function defination for wificonnect
120 {
121    Serial.println();
122    Serial.print("Connecting to ");
123
124    WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
125    while (WiFi.status() != WL_CONNECTED) {
126        delay(500);
127        Serial.print(".");
128    }
129    Serial.println("");
130    Serial.println("WiFi connected");
131    Serial.println("IP address: ");
132    Serial.println(WiFi.localIP());
```

```
123
124      WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
125      while (WiFi.status() != WL_CONNECTED) {
126        delay(500);
127        Serial.print(".");
128      }
129      Serial.println("");
130      Serial.println("WiFi connected");
131      Serial.println("IP address: ");
132      Serial.println(WiFi.localIP());
133    }
134
135    void initManagedDevice() {
136      if (client.subscribe(subscribetopic)) {
137        Serial.println((subscribetopic));
138        Serial.println("subscribe to cmd OK");
139      } else {
140        Serial.println("subscribe to cmd FAILED");
141      }
142    }
143
144    void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
145    {
146
147      Serial.print("callback invoked for topic: ");
148      Serial.println(subscribetopic);
149      for (int i = 0; i < payloadLength; i++) {
150        //Serial.print((char)payload[i]);
151        data3 += (char)payload[i];
152      }
153
154    //   Serial.println("data: "+ data3);
155    //   if(data3=="Near")
156    //   {
157    // Serial.println(data3);
158    // diaitalunite(IFR UICU).
```
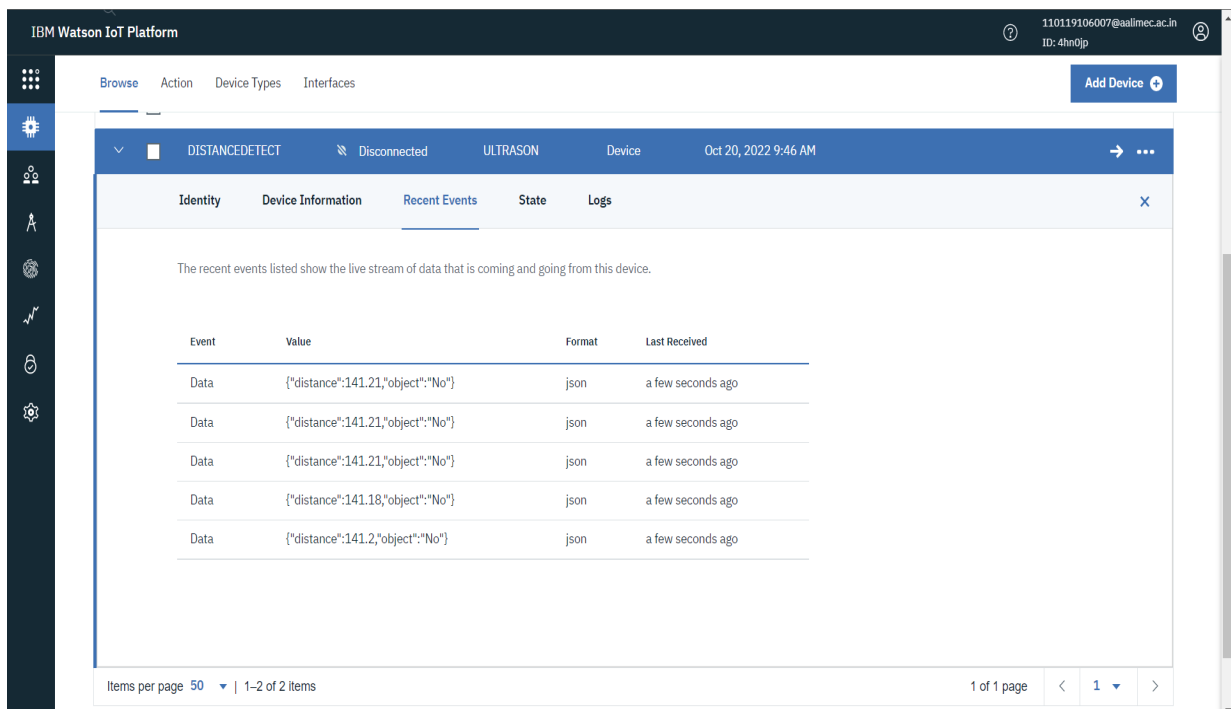
```cpp
142    }
143
144    void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
145    {
146
147      Serial.print("callback invoked for topic: ");
148      Serial.println(subscribetopic);
149      for (int i = 0; i < payloadLength; i++) {
150        //Serial.print((char)payload[i]);
151        data3 += (char)payload[i];
152      }
153
154    //    Serial.println("data: "+ data3);
155    //    if(data3=="Near")
156    //    {
157    // Serial.println(data3);
158    // digitalWrite(LED,HIGH);
159
160    //    }
161
162    //    else
163    //    {
164    // Serial.println(data3);
165    // digitalWrite(LED,LOW);
166
167    //    }
168    data3="";
169
170
171    }
```
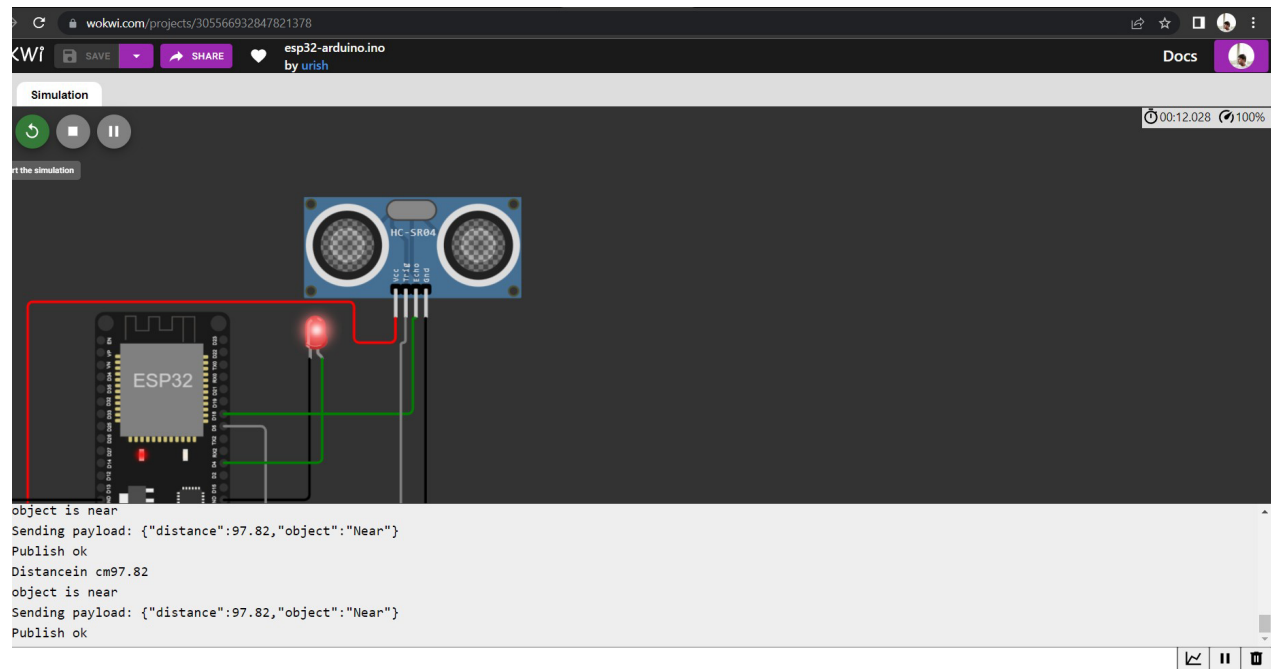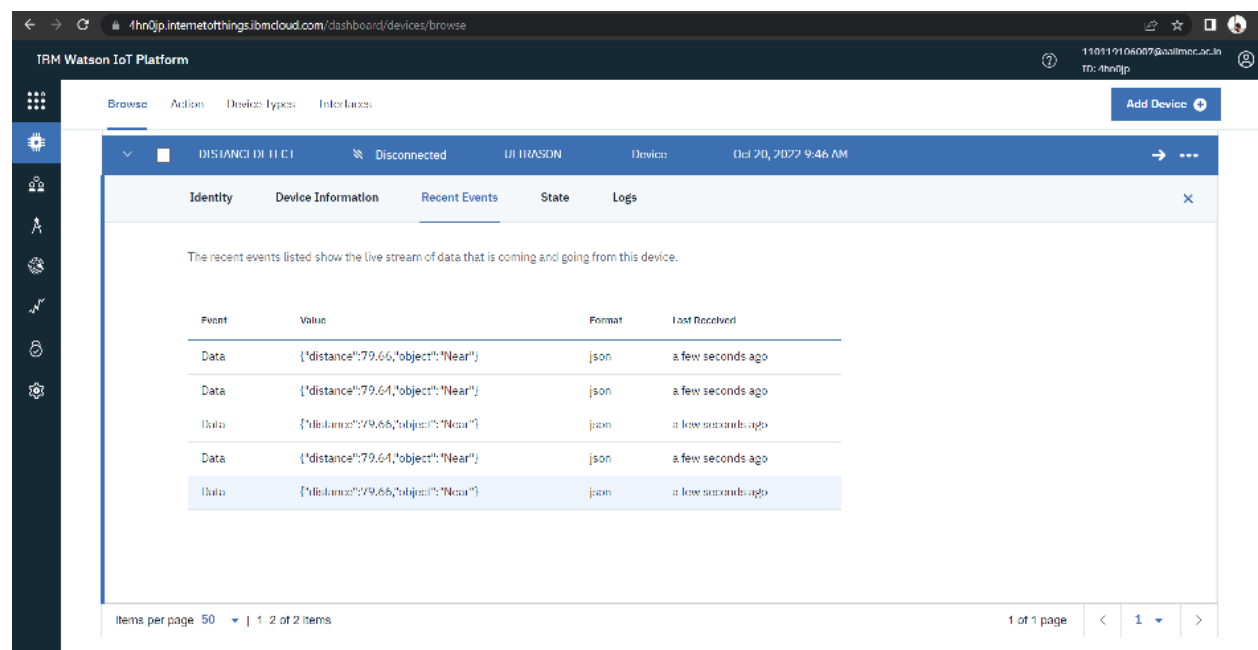
OUTPUT:
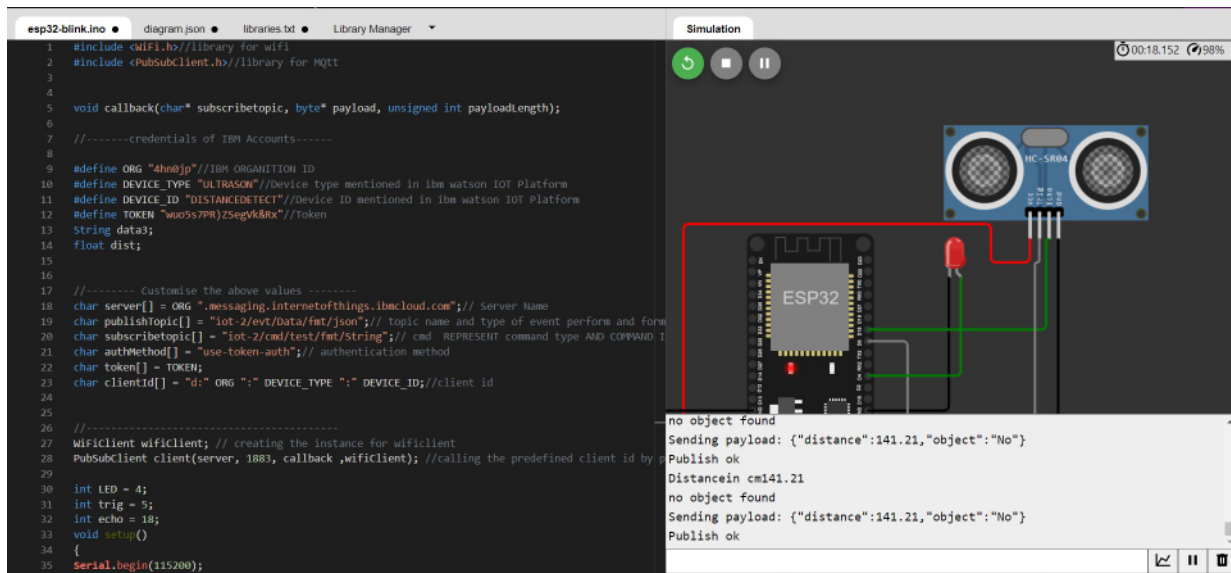
Data send to the IBM cloud device when the object is far

when object is near to the ultrasonic sensor

object is near
Sending payload: {"distance":97.82,"object":"Near"}
Publish ok
Distancein cm97.82
object is near
Sending payload: {"distance":97.82,"object":"Near"}
Publish ok

Data sent to the IBM Cloud Device when the object is near

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