ASSIGNMENT-4 DISTANCE DETECTION USING ULTRASONIC SENSOR

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Maximum Marks	2 Marks

Ouestion1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

WOKWI LINK:

https://wokwi.com/projects/305566932847821378

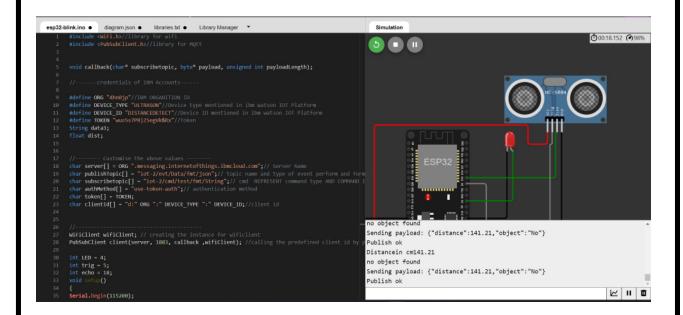
CODE:

```
#include #i
```

```
esp32-blink.ino •
                   diagram.json •
                                    libraries.txt •
                                                   Library Manager
       pinMode(trig,OUTPUT);
       pinMode(echo,INPUT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void loop()// Recursive Function
        digitalWrite(trig,LOW);
         digitalWrite(trig,HIGH);
         delayMicroseconds(10);
         digitalWrite(trig,LOW);
         float dur = pulseIn(echo,HIGH);
         float dist = (dur * 0.0343)/2;
         Serial.print ("Distancein cm");
         Serial.println(dist);
         PublishData(dist);
         delay(1000);
         if (!client.loop()) {
           mqttconnect();
       void PublishData(float dist) {
         mqttconnect();//function call for connecting to ibm
```

```
esp32-blink.ino •
                    diagram.json •
                                                      Library Manager
                                      libraries.txt •
          WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
          while (WiFi.status() != WL CONNECTED) {
            delay(500);
            Serial.print(".");
          Serial.println("");
Serial.println("WiFi connected");
Serial.println("IP address: ");
          Serial.println(WiFi.localIP());
        void initManagedDevice() {
          if (client.subscribe(subscribetopic)) {
            Serial.println((subscribetopic));
             Serial.println("subscribe to cmd OK");
          } else {
            Serial.println("subscribe to cmd FAILED");
          }
        void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
          Serial.print("callback invoked for topic: ");
          Serial.println(subscribetopic);
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          for (int i = 0; i < payloadLength; i++) {</pre>
            data3 += (char)payload[i];
```

OUTPUT:



Data send to the IBM cloud device when the object is far

