# ASSIGNMENT-4 DISTANCE DETECTION USING ULTRASONIC SENSOR

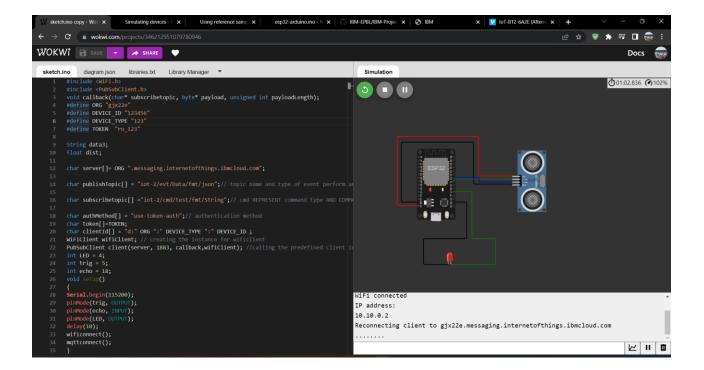
Date	22 October 2022
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Maximum Marks	2 Marks

#### Question1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 Cm send "alert" to IBM cloud and display in device recent events.

### **WOKWI LINK:**

https://wokwi.com/projects/346212951079780946



#### CODE:

```
#include <WiFi.h>
#include <PubSubClient.h>
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);
#define ORG "gjx22e"
#define DEVICE ID "123456"
#define DEVICE TYPE "123"
#define TOKEN "ro 123"
String data3;
float dist;
char server[]= ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of event
perform and Format in which data to be send
char subscribetopic[] ="iot-2/cmd/test/fmt/String";// cmd REPRESENT command type
AND COMMAND IS TEST OF FORMAT STRING
char authMethod[] = "use-token-auth";// authentication method
char token[]=TOKEN;
char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID ;
WiFiClient wifiClient; // creating the instance for wificlient
PubSubClient client(server, 1883, callback,wifiClient); //calling the predefined
client id by passing parameter like server
int LED = 4;
int trig = 5;
int echo = 18;
void setup()
Serial.begin(115200);
pinMode(trig, OUTPUT);
pinMode(echo, INPUT);
pinMode(LED, OUTPUT);
delay(10);
wificonnect();
mqttconnect();
void loop()// Recursive Function
  digitalWrite(trig, LOW);
 digitalWrite(trig, HIGH);
 delayMicroseconds(10);
  digitalWrite(trig, LOW);
 float dur=pulseIn(echo, HIGH);
 float dist = (dur * 0.0343)/2;
  Serial.print ("Distancein cm");
 Serial.println(dist);
```

```
PublishData(dist);
 delay(1000);
 if (!client.loop())
   mqttconnect();
void PublishData(float dist) {
 mqttconnect();
 String object;
 if (dist <100)
   digitalWrite(LED, HIGH);
   Serial.println("object is near");
   object = "Near";
 else
   digitalWrite(LED, LOW);
   Serial.println("no object found");
   object = "No";
  String payload = "{\"distance\":";
  payload += dist;
  payload += "," "\"object\":\"";
 payload += object;
 payload += "\"}";
 Serial.print("Sending payload: ");
 Serial.println(payload);
 if (client.publish(publishTopic, (char*) payload.c_str()))
   Serial.println("Publish ok");// if it sucessfully upload data on the cloud the
 } else {
   Serial.println("Publish failed");
void mqttconnect() {
 if (!client.connected()) {
   Serial.print("Reconnecting client to ");
   Serial.println(server);
   while (!!!client.connect(clientId, authMethod, token)) {
     Serial.print(".");
     delay(500);
     initManagedDevice();
     Serial.println();
```

```
void wificonnect()
  Serial.println();
 Serial.print("Connecting to ");
 WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the
 while (WiFi.status() != WL_CONNECTED) {
   delay(500);
    Serial.print(".");
 Serial.println("");
  Serial.println("WiFi connected");
 Serial.println("IP address: ");
  Serial.println(WiFi.localIP());
void initManagedDevice() {
 if (client.subscribe (subscribetopic)) {
   Serial.println((subscribetopic));
    Serial.println("subscribe to cmd OK");
} else {
 Serial.println("subscribe to cmd FAILED");
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength) {
Serial.print("callback invoked for topic: ");
Serial.println(subscribetopic);
for (int i = 0; i < payloadLength; i++) {</pre>
   data3 += (char)payload[i];
data3="";
```

## **OUTPUT**

