

# FINAL PYTHON CODE

TEAM ID: PNT2022TMID21463

```
import time
import sys
import ibmiotf.application
import ibmiotf.device
import random

#Provide your IBM Watson Device Credentials
organization = "vr8RSt"
deviceType = "PNT2022TMID21463"
deviceId = "PNT2022TMID21463DEVICEID"
authMethod = "token"
authToken = "0weRRNRVrkaSEGJHug!"

# Initialize GPIO

def myCommandCallback(cmd):
    print("Command received: %s" % cmd.data['command'])
    status=cmd.data['command']
    if status=="alarmon":
        print ("Alarm is on")
    elif (status == "alarmoff") :
        print ("Alarm is off")
    elif status == "sprinkleron":
        print("Sprinkler is OFF")
    elif status == "sprinkleron":
        print("Sprinkler is ON")
    #print(cmd)
try:
    deviceOptions = {"org": organization, "type": deviceType, "id": deviceId, "auth-method": authMethod,
"auth-token": authToken}
    deviceCli = ibmiotf.device.Client(deviceOptions)
    #.....
```

```
except Exception as e:
```

```
    print("Caught exception connecting device: %s" % str(e))
```

```
    sys.exit()
```

```
# Connect and send a datapoint "hello" with value "world" into the cloud as an event of type "greeting" 10 times
```

```
deviceCli.connect()
```

```
while True:
```

```
    #Get Sensor Data from DHT11
```

```
    temp=random.randint(0,100)
```

```
    Humid=random.randint(0,100)
```

```
    gas=random.randint(0,100)
```

```
    data = { 'temp' : temp, 'Humid': Humid, 'gas' : gas }
```

```
    #print data
```

```
    def myOnPublishCallback():
```

```
        print ("Published Temperature = %s C" % temp, "Humidity = %s %" % Humid, "Gas_Level = %s %" %  
%gas, "to IBM Watson")
```

```
    success = deviceCli.publishEvent("IoTSensor", "json", data, qos=0, on_publish=myOnPublishCallback)
```

```
    if not success:
```

```
        print("Not connected to IoT")
```

```
    time.sleep(1)
```

```
    deviceCli.commandCallback = myCommandCallback
```

```
# Disconnect the device and application from the cloud
```

```
deviceCli.disconnect()
```