

Sprint 04

Signs with Smart Connectivity for Better Road Safety

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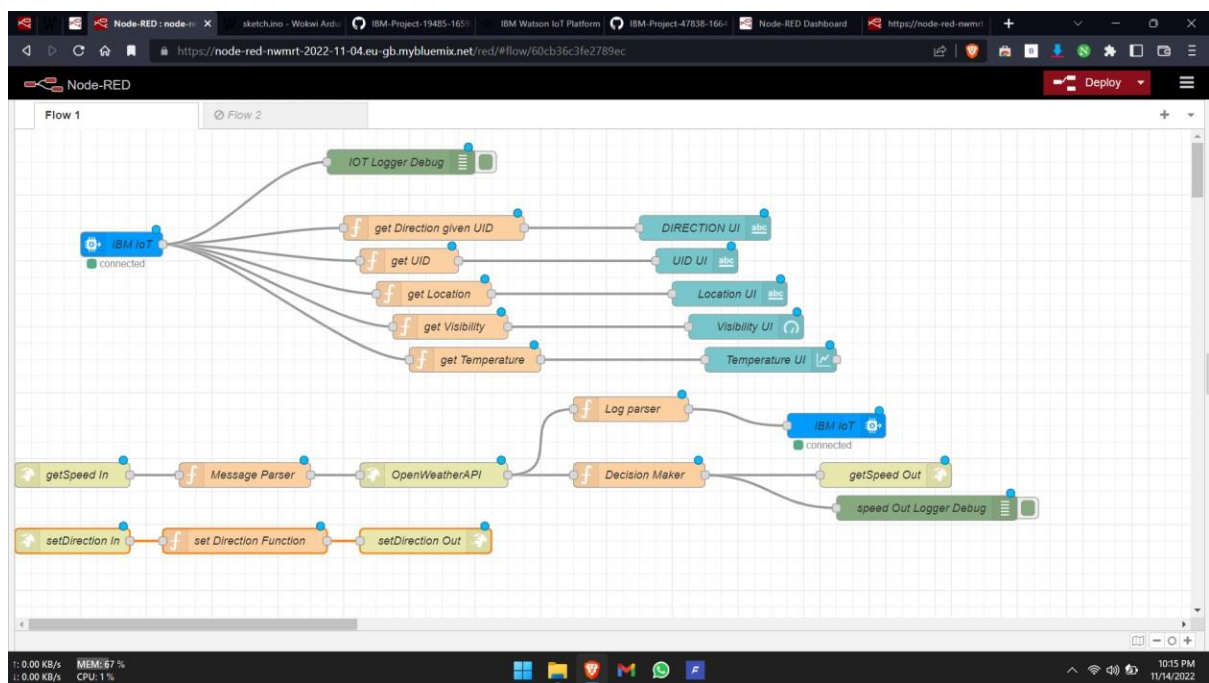
Sprint Goals :

Hardware & Cloud integration

UI/UX Optimization

Node RED :

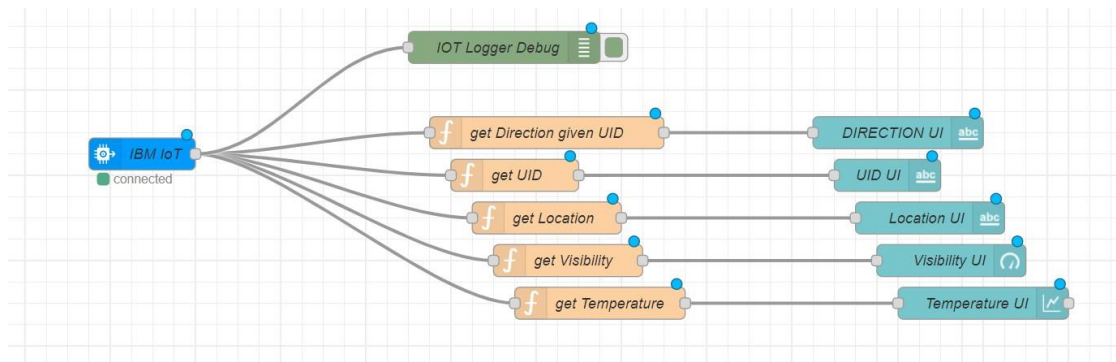
Node RED flow :



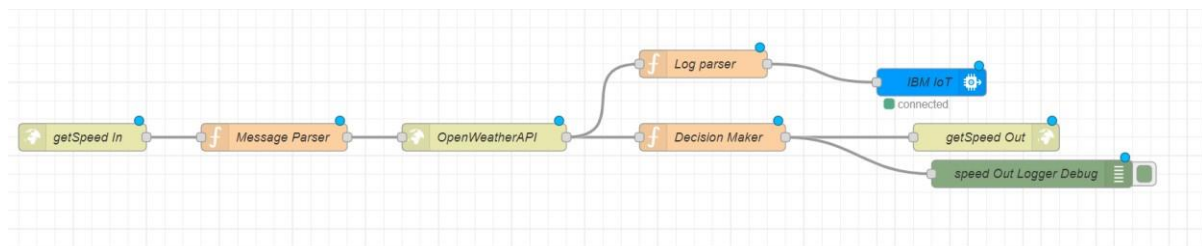
There are 3 flows in the above Node RED flow. They are

- Node RED UI flow
- /getSpeed API flow
- /setDirection API flow

1. Node RED UI flow :



- "IBM IoT" node connects the backend to Node RED UI
- The function nodes such as "get Direction given UID", "get UID", "get Location", "get Visibility" & "get Temperature" extract the respective data out and provides them to the UI nodes "Direction UI", "UID UI", "Location UI", "Visibility UI" & "Temperature UI".
- "IOT Logger Debug" node logs the data at debugger



- "getSpeed In" node is an http end point. It accepts parameters like microcontroller UID, location, school & hospital zones info.
- "Message Parser" node parses the data and passes on only required information to the next node
- "OpenWeatherAPI" node is a http request node which calls the OpenWeather API and send the data to the next node.
- "Log Parser" node extracts specific parameters from the weather data and and sends it to the next node.

```
weatherObj = JSON.parse(JSON.stringify(msg.payload));
```

```
localityObj = global.get("data");
```

```
var suggestedSpeedPercentage = 100;
```

```

var preciseObject = {
  temperature : weatherObj.main.temp - 273.15,
  location : localityObj.location,
  visibility : weatherObj.visibility/100,
  uid : localityObj.uid,
  direction : global.get("direction")
};

```

```

msg.payload = preciseObject;

```

```

return msg;

```

- "IBM IoT" node here (IBM IoT OUT) connects the "IBM IoT" node (IBM IoT IN) mentioned in the Node RED UI flow which enables UI updation and logging.
- "Decision Maker" node processes the weather data and other information from the micro controller to form the string that is to be displayed at the Sign Board

```

weatherObj = JSON.parse(JSON.stringify(msg.payload));

```

```

localityObj = global.get("data");

```

```

var suggestedSpeedPercentage = 100;

```

```

var preciseObject = {
  temperature : weatherObj.main.temp - 273.15,
  weather : weatherObj.weather.map(x=>x.id).filter(code => code<700),
  visibility : weatherObj.visibility/100
};

```

```

if(preciseObject.visibility<=40)
  suggestedSpeedPercentage -=30

```

```

switch(String(preciseObject.weather)[-1]) // https://openweathermap.org/weather-conditions refer
weather codes meaning here

```

```

{
    case "0" : suggestedSpeedPercentage -=10;break;
    case "1" : suggestedSpeedPercentage -=20;break;
    case "2" : suggestedSpeedPercentage -=30;break;
}

msg.payload = preciseObject;

var doNotHonk = 0;

if(localityObj.hospitalZone=="1"||localityObj.schoolZone=="1")
    doNotHonk = 1;

var responseObject = {
    suggestedSpeed : localityObj.usualSpeedLimit*(suggestedSpeedPercentage/100),
    doNotHonk : doNotHonk
}

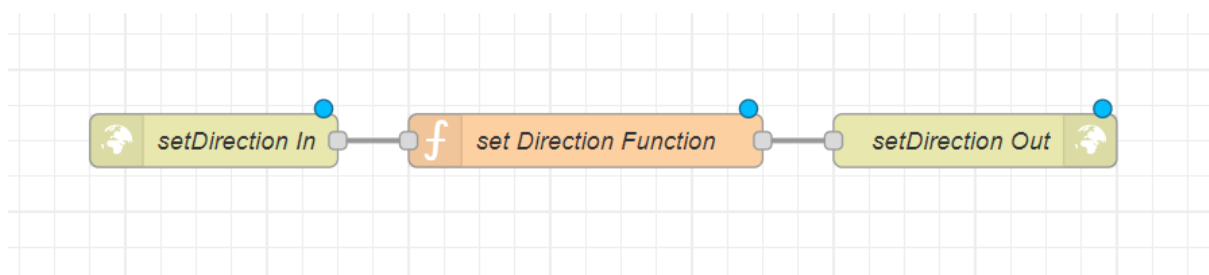
msg.payload = String(responseObject.suggestedSpeed) + " kmph \n\n" +
(returnObject.doNotHonk==1?"Do Not Honk":"" ) + "$" + global.get(String(localityObj.uid));

return msg;

```

- "getSpeed Out" node returns a http response for the request at node "getSpeed In".
- "speed Out Logger Debug" logs the data for debugging.

3/setDirection API flow :



- "setDirection In" node is an http end point. It accepts parameters like microcontroller UID & direction.
- "set Direction Function" node sets the direction for the given UID.
- "setDirection Out" node returns a http response for the request at node "setDirection In".ht

- "Direction can be set by the Authorities" in a separate ui created for them with "MIT APP INVENTOR" and the direction will be displayed in a display in the board connected with "ESP32" at the "Wokwi Simulator" which was connected with "OpenWeatherMap API" through "Node-Red".

Wokwi Circuit :

Code:

```
#include <WiFi.h>
#include <HTTPClient.h>
#include <Adafruit_GFX.h>
#include <Adafruit_ILI9341.h>
#include <string.h>

const char* ssid = "Wokwi-GUEST";
const char* password = "";

#define TFT_DC 2
#define TFT_CS 15
Adafruit_ILI9341 tft = Adafruit_ILI9341(TFT_CS, TFT_DC);

String myLocation = "Chennai,IN";
String usualSpeedLimit = "70"; // kmph

int schoolZone = 32;
int hospitalZone = 26;

int uid = 2504;

String getString(char x)
{
```

```

String s(1, x);

returns;

}

String stringSplitter1(String fullString,char delimiter='$')
{
    String returnString = "";
    for(int i = 0; i<fullString.length();i++) {
        char c = fullString[i];
        if(delimiter==c)
            break;
        returnString+=String(c);
    }
    return(returnString);
}

```

```

String stringSplitter2(String fullString,char delimiter='$')
{
    String returnString = "";
    bool flag = false;
    for(int i = 0; i<fullString.length();i++) {
        char c = fullString[i];
        if(flag)
            returnString+=String(c);
        if(delimiter==c)
            flag = true;
    }
    return(returnString);
}

```

```

void rightArrow()

```

```

{
    int refX = 50;
    int refY = tft.setCursorY() + 40;

    tft.fillRect(refX,refY,100,20,ILI9341_RED);
    tft.fillTriangle(refX+100,refY-30,refX+100,refY+50,refX+40+100,refY+10,ILI9341_RED);
}

```

void leftArrow()

```

{
    int refX = 50;
    int refY = tft.setCursorY() + 40;

    tft.fillRect(refX+40,refY,100,20,ILI9341_RED);
    tft.fillTriangle(refX+40,refY-30,refX+40,refY+50,refX,refY+10,ILI9341_RED);
}

```

void upArrow()

```

{
    int refX = 125;
    int refY = tft.setCursorY() + 30;

    tft.fillTriangle(refX-40,refY+40,refX+40,refY+40,refX,refY,ILI9341_RED);
    tft.fillRect(refX-15,refY+40,30,20,ILI9341_RED);
}

```

String APICall() {

HTTPClient http;

String url = "https://node-red-nwmrt-2022-11-04.eu-gb.mybluemix.net/getSpeed?";

url += "location="+myLocation+"&";

```

url += "schoolZone="+(String)digitalRead(schoolZone)+(String) "& ";
url += "hospitalZone="+(String)digitalRead(hospitalZone)+(String) "& ";
url += "usualSpeedLimit="+(String)usualSpeedLimit+(String) "& ";
url += "uid="+(String)uid;
http.begin(url.c_str());

int httpResponseCode = http.GET();

```

```

if (httpResponseCode>0) {
    String payload = http.getString();
    http.end();

    return(payload);
}
else {
    Serial.print("Error code: ");
    Serial.println(httpResponseCode);
}
http.end();
}

```

```

void myPrint(String contents) {
    tft.fillScreen(ILI9341_BLACK);
    tft.setCursor(0, 20);
    tft.setTextSize(4);
    tft.setTextColor(ILI9341_RED);

    //tft.println(contents);

    tft.println(stringSplitter1(contents));
    String c2 = stringSplitter2(contents);
    if(c2=="s") // represents Straight
    {
        upArrow();
    }
}

```



```

    }

    if(c2=="l") // represents left
    {
        leftArrow();
    }

    if(c2=="r") // represents right
    {
        rightArrow();
    }
}

void setup() {
    WiFi.begin(ssid, password, 6);

    tft.begin();
    tft.setRotation(1);

    tft.setTextColor(ILI9341_WHITE);
    tft.setTextSize(2);
    tft.print("Connecting to WiFi");

    while (WiFi.status() != WL_CONNECTED) {
        delay(100);
        tft.print(".");
    }

    tft.print("\nOK! IP=");
    tft.println(WiFi.localIP());
}

void loop() {

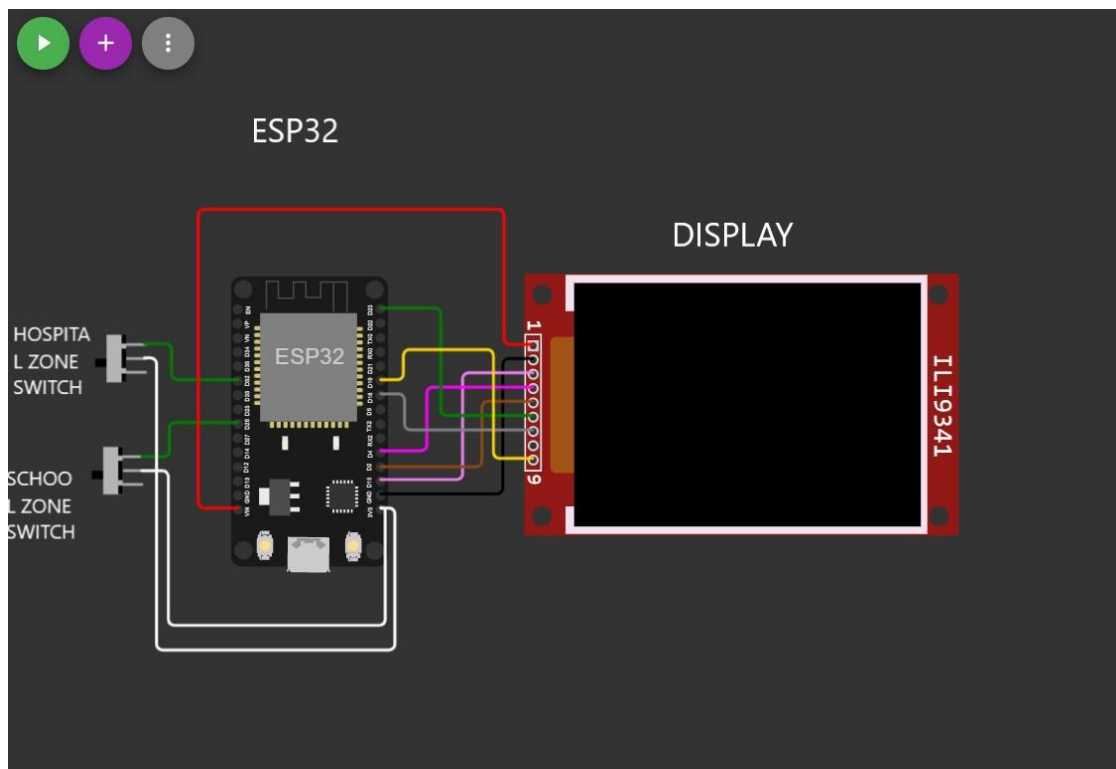
```

```
myPrint(APICall());
```

```
delay(100);
```

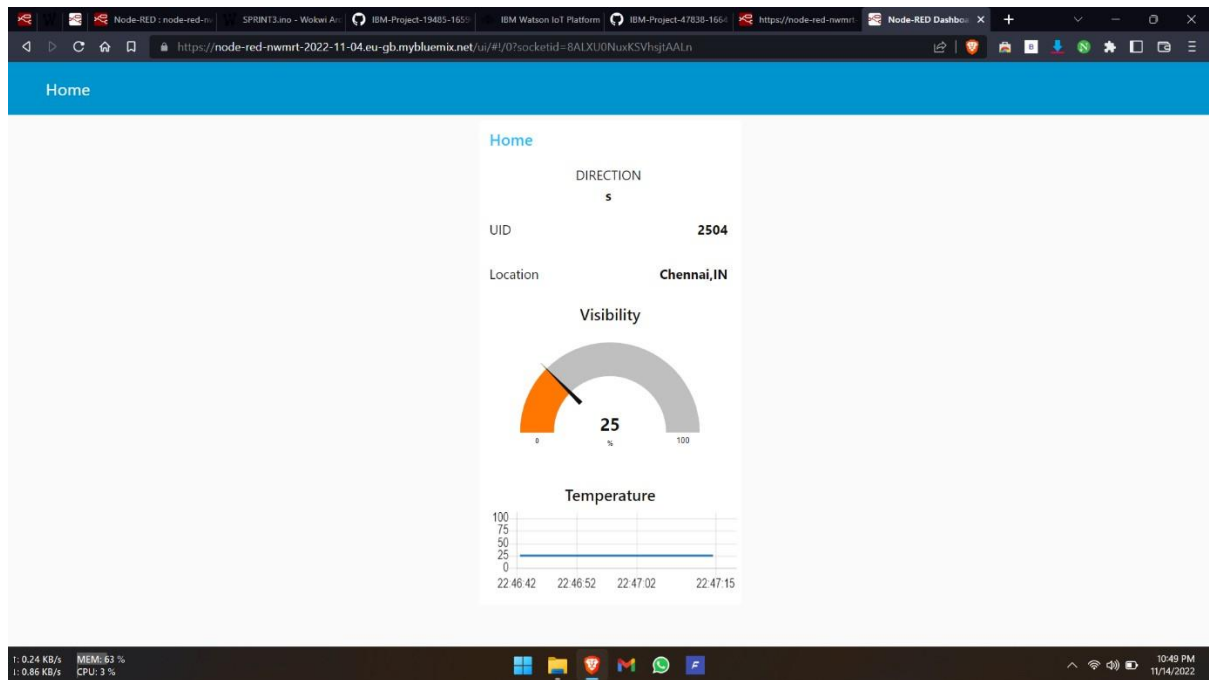
```
}
```

Circuit Diagram :



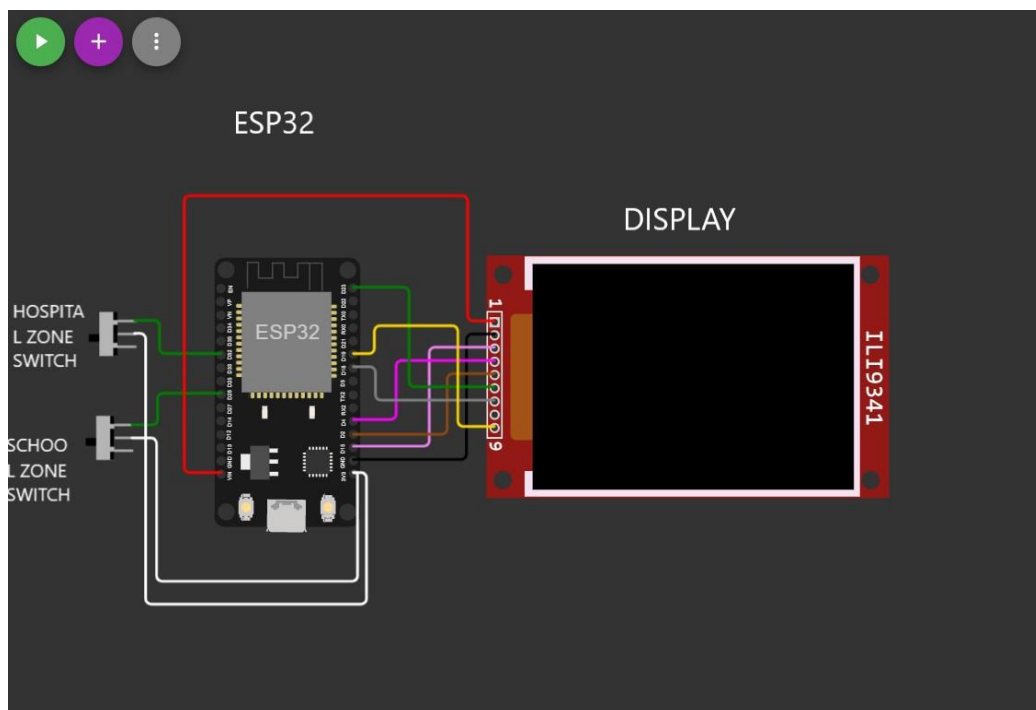
Output :

Node RED Dashboard :

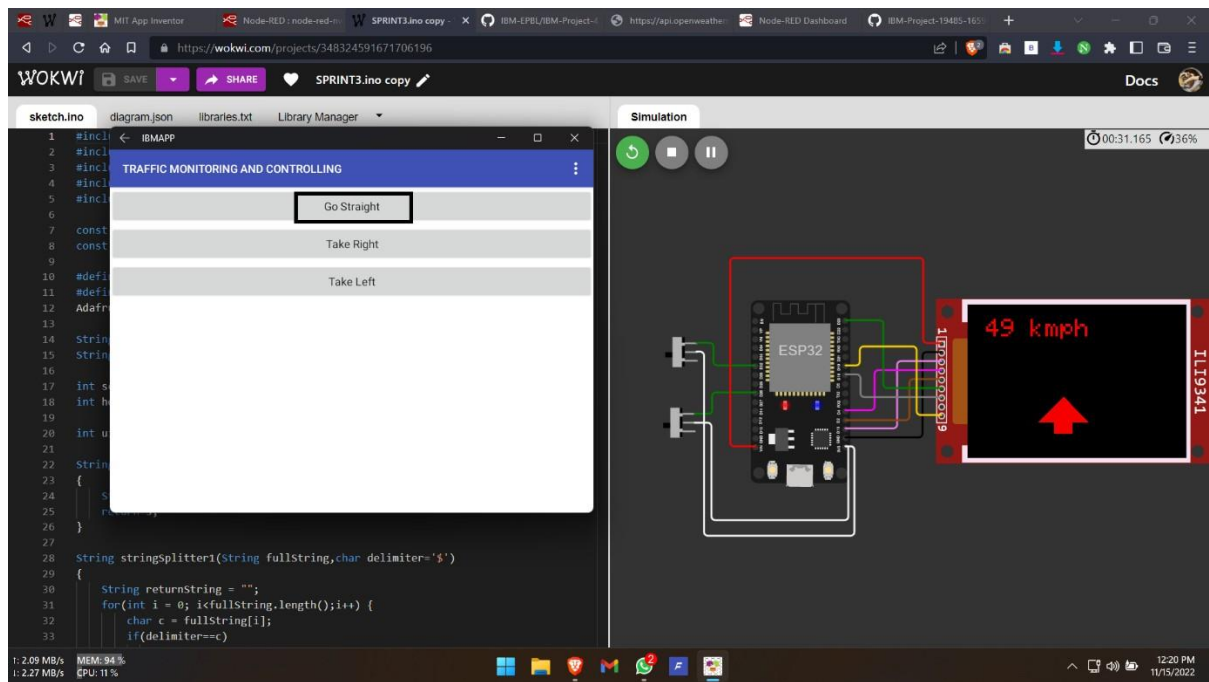


Wokwi Output :

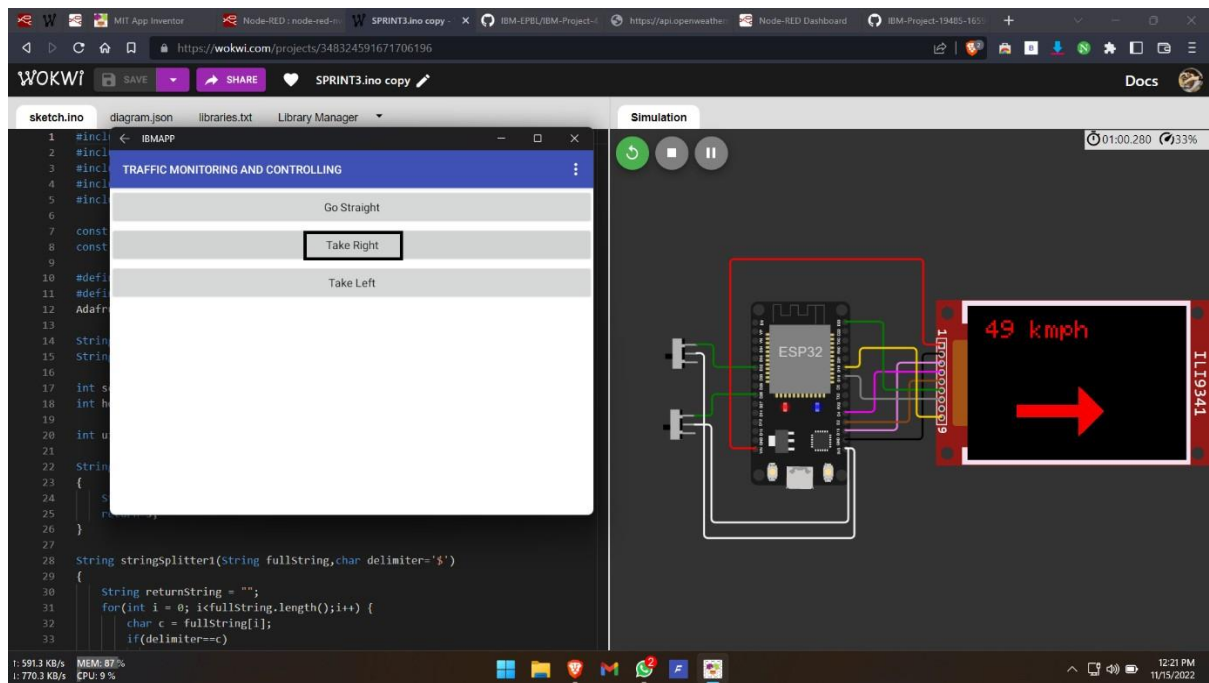
Output ESP32 CIRCUIT



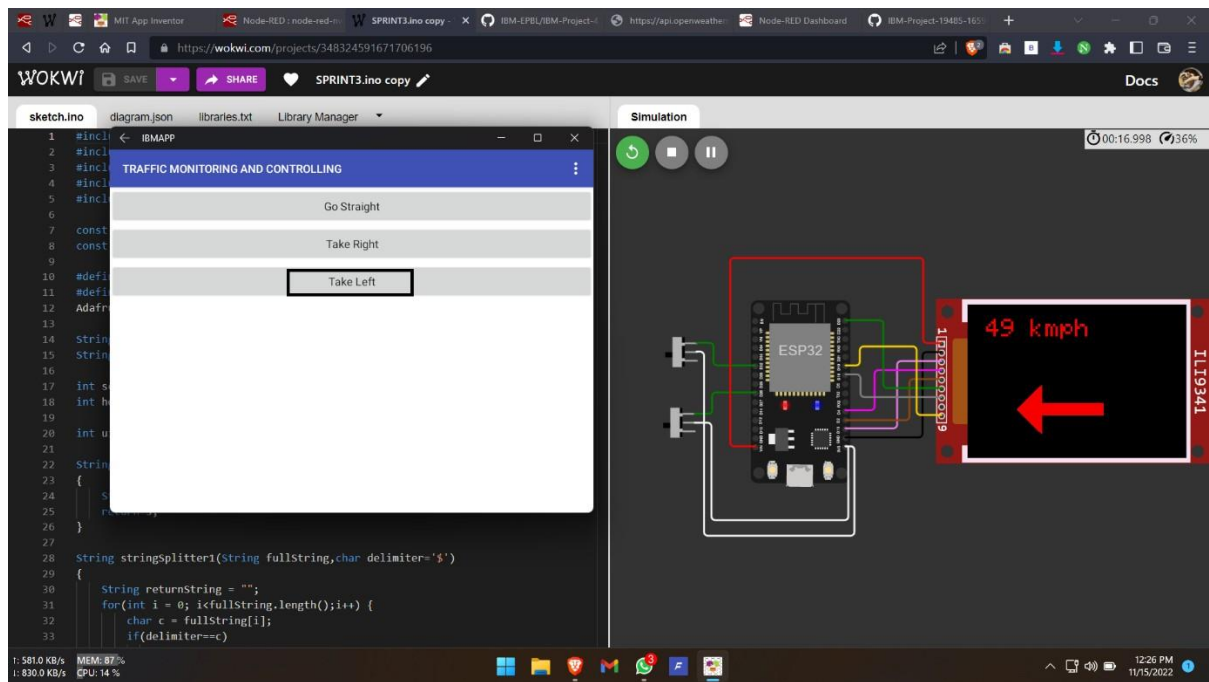
Output 2



Output 3



Output 4



Thank You