

IoT Based Safety Gadget for Child Safety Monitoring & Notification

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Final Deliverables

MQTT location Sender

```
#include <WiFi.h>
#include <WiFiClient.h>
#include <PubSubClient.h>
#include <ArduinoJson.h>
#include<TinyGPS++.h>

#define RXD2 16
#define TXD2 17

HardwareSerial neogps(1);

TinyGPSPlus gps;
char arr[100];

const char* ssid = "GRACECOE-EEE";
const char* password = "Admin@Grace";

#define ID "q6wu16"
#define DEVICE_TYPE "GPS"
#define DEVICE_ID "Tracker"
#define TOKEN "childtracker1"
```

```
char server[] = ID ".messaging.internetofthings.ibmcloud.com";
char publish_Topic1[] = "iot-2/evt/Data1/fmt/json";
char publish_Topic2[] = "iot-2/evt/Data2/fmt/json";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ID ":" DEVICE_TYPE ":" DEVICE_ID;
```

```
WiFiClient wifiClient;
PubSubClient client(server, 1883, NULL, wifiClient);
```

```
void setup() {
    Serial.begin(115200);
    Serial.println();
    wifi_init();
}
```

```
long previous_message = 0;
void loop() {
    client.loop();
    String payload = getLocationPayload();
    if(payload==""){
        return;
    }
```

```
    Serial.print("Sending payload: ");
    Serial.println(payload);
    if (client.publish(publish_Topic1, arr)) {
        Serial.println("Published successfully");
    } else {
        Serial.println("Failed");
    }
```

```

    }
    delay(2000);
}

void wifi_init(){
    WiFi.begin(ssid, password);
    neogps.begin(9600,SERIAL_8N1,RXD2,TXD2);
    while (WiFi.status() != WL_CONNECTED) {
        delay(500);
        Serial.print(".");
    }
    Serial.println("");
    Serial.println(WiFi.localIP());

    if (!client.connected()) {
        Serial.print("Reconnecting client to ");
        Serial.println(server);
        while (!client.connect(clientId, authMethod, token)) {
            Serial.print(".");
            delay(500);
        }
        Serial.println("Connected TO IBM IoT cloud!");
    }
}

String getLocationPayload(){
    boolean newData = false;
    for(unsigned long start = millis();millis()-start<1000;){
        while(neogps.available()){
            if(gps.encode(neogps.read())){
                newData = true;
            }
        }
    }
}

```

```

    }
    String payload;
    if(newData == true){
        newData = false;
        payload = locationPayloadGenerator();
    }
    else{
        Serial.println("No data");
        payload = "{}";
    }
    return payload;
}

String locationPayloadGenerator(){
    String payload = "{}";
    if(gps.location.isValid()){
        float lat = gps.location.lat();
        float lon = gps.location.lng();
        payload = "{\"latitude\" : "+String(lat)+"\",\"longitude\" : "+String(lon)+"}";
        create_json(lat,lon);
    }
    return payload;
}

void create_json(float lat,float lon){
    StaticJsonDocument<100> doc;
    JsonObject root = doc.to<JsonObject>();
    root["lat"] = lat;
    root["lon"] = lon;
    serializeJsonPretty(doc,arr);
}

```