



```
#include <LiquidCrystal.h> //LCD library
```

```
#define echo 2
```

```
#define trig 3
```

```
float duration; // time taken by the pulse to return back
```

```
float distance;
```

```
int sensor_Input;
```

```
float temp;// oneway distance travelled by the pulse
```

```
LiquidCrystal lcd(13, 12, 11, 10, 9, 8);//lcd(RS,EN,D4,D5,D6,D7)
```

```
void setup() {
```

```
    pinMode(trig, OUTPUT);
```

```
    pinMode(echo, INPUT);
```

```
    Serial.begin(9600);
```

```
    lcd.begin(16, 2);
```

```
}
```

```
void loop() {
```

```
    time_Measurement();
```

```
    distance = duration * (0.0343) / 2;// calculate the oneway distance travelled by the pulse
```

```
    display_distance();
```

```
    measure_Temp();
```

```
}
```

```
void time_Measurement()
```

```

{ //function to measure the time taken by the pulse to return back

digitalWrite(trig, LOW);

delayMicroseconds(2);

digitalWrite(trig, HIGH);

delayMicroseconds(10);

digitalWrite(trig, LOW);

duration = pulseIn(echo, HIGH);

}

void measure_Temp()

{

sensor_Input = analogRead(A0);

temp = (float)sensor_Input / 1024;

temp = temp * 5;

temp = temp - 0.5;

temp = temp * 100;

    Serial.print("Temp in C: ");

Serial.print(temp);

Serial.println();

}

void display_distance()

{

Serial.print("Distance in Cm: ");

Serial.print(distance);

Serial.println();

delay(1000);

}

```