ASSIGNMENT-4 DISTANCE DETECTION USING ULTRASONIC SENSOR

Date	22 October 2022
Team ID	
	PNT2022TMID110 52
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Maximum Marks	2 Marks

Question1:

Write code and connections in work for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

WOKWI LINK:

https://wokwi.com/projects/305566932847821378

CODE:

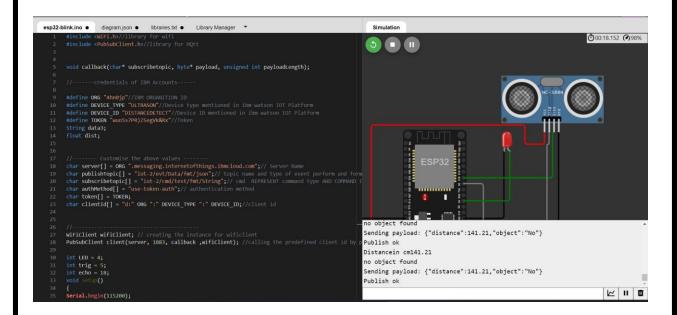
```
#include #i
```

```
esp32-blink.ino
                  diagram.json •
                                   libraries.txt ●
                                                  Library Manager *
       pinMode(trig,OUTPUT);
       pinMode(echo,INPUT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void loop()// Recursive Function
        digitalWrite(trig,LOW);
         digitalWrite(trig,HIGH);
         delayMicroseconds(10);
         digitalWrite(trig,LOW);
         float dur = pulseIn(echo,HIGH);
         float dist = (dur * 0.0343)/2;
         Serial.print ("Distancein cm");
         Serial.println(dist);
         PublishData(dist);
         delay(1000);
         if (!client.loop()) {
         mqttconnect();
       void PublishData(float dist) {
         mqttconnect();//function call for connecting to ibm
```

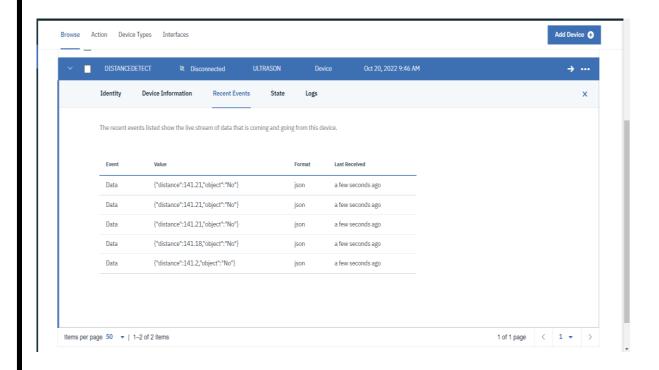
```
| creating the String in in form JSon to update the data to ibm cloud
| "/
| String object;
| if (dist cloe) {
| digitalWrite(LED,HIGH);
| Serial.println("object is near");
| object = "Near";
| }
| else {
| digitalWrite(LED,LOM);
| Serial.println("no object found");
| object = "No";
| }
| String payload = "{\"distance\":";
| payload += dist;
| payload += dist;
| payload += "," "\"object\":\"";
| payload += object;
| payload += "\")";
| Serial.println("Sending payload: ");
| Serial.println(payload);
```

```
esp32-blink.ino •
                   diagram.json •
                                   libraries.txt ●
                                                  Library Manager
         WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
         while (WiFi.status() != WL_CONNECTED) {
           delay(500);
           Serial.print(".");
         Serial.println("");
         Serial.println("WiFi connected");
         Serial.println("IP address: ");
         Serial.println(WiFi.localIP());
       void initManagedDevice() {
         if (client.subscribe(subscribetopic)) {
           Serial.println((subscribetopic));
           Serial.println("subscribe to cmd OK");
           Serial.println("subscribe to cmd FAILED");
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
         Serial.print("callback invoked for topic: ");
 148
         Serial.println(subscribetopic);
         for (int i = 0; i < payloadLength; i++) {</pre>
           data3 += (char)payload[i];
```

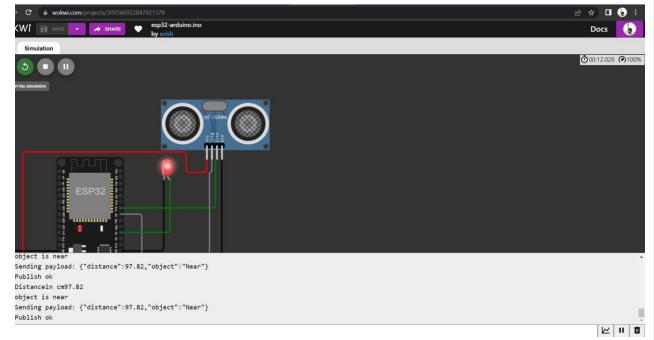
OUTPUT:



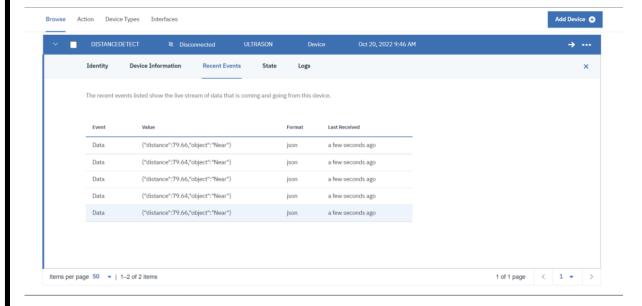
Data send to the IBM cloud device when the object is far



when object is near to the ultrasonic sensor



Data sent to the IBM Cloud Device when the object is near



https://wokwi.com/projects/305566932847821378