Assignment 4

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Question

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events.

Upload document with wokwi share link and images of IBM cloud.

Code:

```
#include <WiFi.h>
#include < PubSubClient.h>
void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength);
#define ORG "Ajay"//IBM ORGANITION ID
#define DEVICE_TYPE "ESP32"//Device type mentioned in ibm watson IOT Platform
#define DEVICE ID "1802"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "12341802" //Token
String data3;
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char subscribetopic[] = "iot-2/cmd/test/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
WiFiClient wifiClient;
PubSubClient client(server, 1883, callback, wifiClient);
const int trigPin = 5;
const int echoPin = 18;
#define SOUND_SPEED 0.034
long duration;
float distance;
void setup() {
Serial.begin(115200);
pinMode(trigPin, OUTPUT);
pinMode(echoPin, INPUT);
wificonnect();
mqttconnect();
void loop()
digitalWrite(trigPin, LOW);
delayMicroseconds(2);
digitalWrite(trigPin, HIGH);
delayMicroseconds(10);
```

```
digitalWrite(trigPin, LOW);
duration = pulseIn(echoPin, HIGH);
distance = duration * SOUND_SPEED/2;
Serial.print("Distance (cm): ");
Serial.println(distance);
if(distance<100)
Serial.println("ALERT!!");
delay(1000);
PublishData(distance);
delay(1000);
if (!client.loop()) {
mqttconnect();
delay(1000);
void PublishData(float dist) {
mqttconnect();
String payload = "{\"Distance\":";
payload += dist;
payload += ",\"ALERT!!\":""\"Distance less than 100cms\"";
payload += "}";
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish ok");
} else {
Serial.println("Publish failed");
void mqttconnect() {
if (!client.connected()) {
Serial.print("Reconnecting client to ");
Serial.println(server);
while (!!!client.connect(clientId, authMethod, token)) {
Serial.print(".");
delay(500);
initManagedDevice();
Serial.println();
void wificonnect()
Serial.println();
Serial.print("Connecting to ");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL_CONNECTED) {
delay(500);
Serial.print(".");
Serial.println("");
```

```
Serial.println("WiFi connected");
Serial.println("IP address: ");
Serial.println(WiFi.localIP());
void initManagedDevice() {
if (client.subscribe(subscribetopic)) {
Serial.println((subscribetopic));
Serial.println("subscribe to cmd OK");
} else {
Serial.println("subscribe to cmd FAILED");
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
Serial.print("callback invoked for topic: ");
Serial.println(subscribetopic);
for (int i = 0; i < payloadLength; i++) {
data3 += (char)payload[i];
Serial.println("data: "+ data3);
data3="";
```

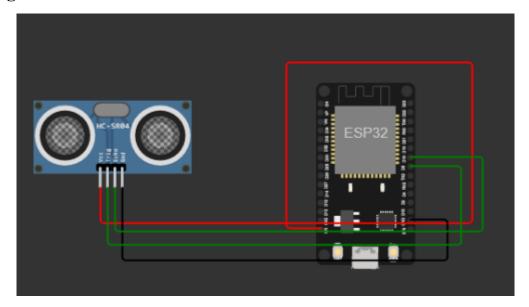
Diagram

```
"version": 1,
"author": "sweetysharon",
"editor": "wokwi",
"parts": [
 { "type": "wokwi-esp32-devkit-v1", "id": "esp", "top": 0.35, "left": -50.9, "attrs": {} },
 { "type": "wokwi-hc-sr04", "id": "ultrasonic1", "top": 20.5, "left": -355.25, "attrs": {} }
],
"connections": [
 [ "esp:TXO", "$serialMonitor:RX", "", [] ],
 [ "esp:RX0", "$serialMonitor:TX", "", [] ],
  "esp:VIN",
  "ultrasonic1:VCC",
  "red",
  ["h-37.16", "v-178.79", "h200", "v173.33", "h100.67"]
 [ "esp:GND.1", "ultrasonic1:GND", "black", [ "h39.87", "v44.04", "h170" ] ],
 [ "esp:D5", "ultrasonic1:TRIG", "green", [ "h54.54", "v85.07", "h130.67" ] ],
 [ "esp:D18", "ultrasonic1:ECHO", "green", [ "h77.87", "v80.01", "h110" ] ]
```

Wokwi simulation link:

https://wokwi.com/projects/346508314441417298

Circuit Diagram:



Output:

Wokwi output:

```
Connecting to ....
WiFi connected
IP address:
10.10.0.2
Reconnecting client to ytluse.messaging.internetofthings.ibmcloud.com
iot-2/cmd/test/fmt/String
subscribe to cmd OK

Distance (cm): 399.92
Distance (cm): 399.96
Distance (cm): 399.94
Distance (cm): 399.98
Distance (cm): 399.98
Distance (cm): 399.94
Distance (cm): 399.92
Distance (cm): 399.94
```

IBM cloud output:

