ASSIGNMENT-4 DISTANCE DETECTION USING ULTRASONIC SENSOR

Date	20 October 2022
Team ID	PNT2022TMID11112
Name	Sneka.S
Student Roll Number	811519106137
Maximum Marks	2 Marks

Question1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

WOKWI LINK:

https://wokwi.com/projects/346666873885033042

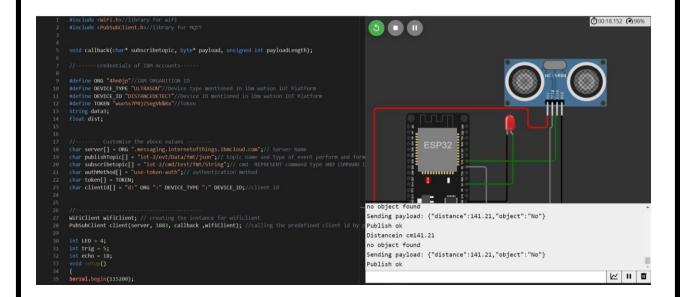
CODE:

```
pinMode(trig,OUTPUT);
pinMode(echo,INPUT);
pinMode(LED, OUTPUT);
delay(10);
wificonnect();
mqttconnect();
void loop()// Recursive Function
digitalWrite(trig,LOW);
 digitalWrite(trig,HIGH);
 delayMicroseconds(10);
  digitalWrite(trig,LOW);
  float dur = pulseIn(echo,HIGH);
 float dist = (dur * 0.0343)/2;
  Serial.print ("Distancein cm");
  Serial.println(dist);
 PublishData(dist);
  delay(1000);
  if (!client.loop()) {
 mqttconnect();
void PublishData(float dist) {
 mqttconnect();//function call for connecting to ibm
```

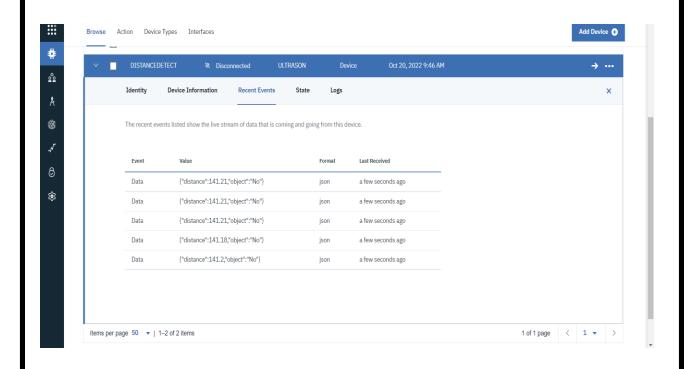
```
| creating the String in in form JSon to update the data to ibm cloud
| "/
| String object;
| if (dist cloe) {
| digitalWrite(LED,HIGH);
| Serial.println("object is near");
| object = "Near";
| }
| else {
| digitalWrite(LED,LOM);
| Serial.println("no object found");
| object = "No";
| }
| String payload = "{\"distance\":";
| payload += dist;
| payload += dist;
| payload += "," "\"object\":\"";
| payload += object;
| payload += "\")";
| Serial.println("Sending payload: ");
| Serial.println(payload);
```

```
WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
        while (WiFi.status() != WL_CONNECTED) {
          delay(500);
          Serial.print(".");
        Serial.println("");
Serial.println("WiFi connected");
        Serial.println("IP address: ");
        Serial.println(WiFi.localIP());
      void initManagedDevice() {
        if (client.subscribe(subscribetopic)) {
          Serial.println((subscribetopic));
          Serial.println("subscribe to cmd OK");
          Serial.println("subscribe to cmd FAILED");
      void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
        Serial.print("callback invoked for topic: ");
148
        Serial.println(subscribetopic);
        for (int i = 0; i < payloadLength; i++) {</pre>
          data3 += (char)payload[i];
```

OUTPUT:

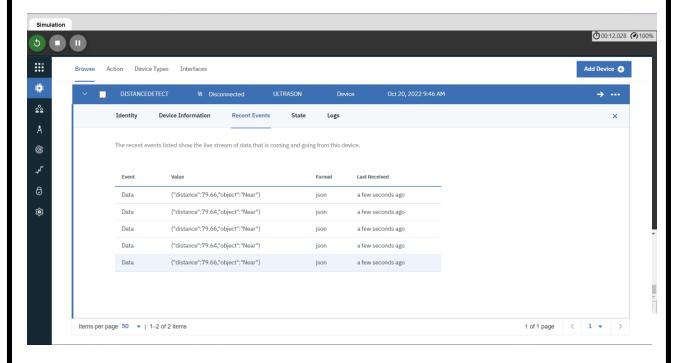


Data sent to the IBM cloud device when the object is far



when object is near to the ultrasonic sensor

Data sent to the IBM Cloud Device when the object is near



https://wokwi.com/projects/346666873885033042