Assignment -3

Assignment Date	27 October 2022
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Maximum Marks	2 Marks

Question-1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to IBM cloud and display in device recent events.

Program:

```
i#include <WiFi.h>
#include < PubSubClient.h>
//---- credentials of IBM Accounts -----
#define ORG "qwErv"
#define DEVICE_TYPE "device_1"
#define DEVICE_ID "iot"
#define TOKEN "1234567"
#define speed 0.034
#define led 14
String data3;
int LED = 4;
//---- customise above values -----
char server[] = ORG
".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-
2/evt/sreedhar/fmt/json";
                                        //
topic name and type of event perform and
format in which data to be send
char topic[] = "iot-2/cmd/led/fmt/String";
// cmd Represent type and command is test
format of strings
char authMethod[] = "use-token-auth";
// authentication method
char token[] = TOKEN;
```

```
char clientId[] = "d:" ORG ":" DEVICE_TYPE
":" DEVICE ID;
//-----
WiFiClient wifiClient;
// creating instance for wificlient
PubSubClient client(server, 1883, wifiClient);
const int trigpin=5;
const int echopin=18;
String command;
String data="";
long duration;
float dist;
void setup()
{
 Serial.begin(115200);
 pinMode(led, OUTPUT);
 pinMode(trigpin, OUTPUT);
 pinMode(echopin, INPUT);
 wifiConnect();
 mqttConnect();
}
void loop() {
 bool isNearby = dist < 100;
 digitalWrite(led, isNearby);
 publishData();
 delay(500);
 if (!client.loop())
  mqttConnect();
// function call to connect to ibm
}
}
```

```
/* -----*/
void wifiConnect()
{
 Serial.print("Connecting to ");
 Serial.print("Wifi");
 WiFi.begin("Wokwi-GUEST", "", 6);
 while (WiFi.status() != WL_CONNECTED)
 {
  delay(500);
  Serial.print(".");
 }
 Serial.print("WiFi connected, IP address: ");
 Serial.println(WiFi.localIP());
}
void mqttConnect()
 if (!client.connected())
  Serial.print("Reconnecting MQTT client to
");
  Serial.println(server);
  while (!client.connect(clientId,
authMethod, token))
  {
   Serial.print(".");
   delay(500);
  }
  initManagedDevice();
  Serial.println();
 }
```

```
}
void initManagedDevice() {
 if (client.subscribe(topic))
 {
  Serial.println("IBM subscribe to cmd OK");
 }
 else
 {
  Serial.println("subscribe to cmd FAILED");
}
}
void publishData()
{
 digitalWrite(trigpin,LOW);
 digitalWrite(trigpin,HIGH);
 delayMicroseconds(10);
 digitalWrite(trigpin,LOW);
 duration=pulseIn(echopin,HIGH);
 dist=duration*speed/2;
 if(dist<100)
  digitalWrite(LED,HIGH);
  String payload = "{\"Alert Distance\":";
  payload += dist;
  payload += "}";
  Serial.print("\n");
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if (client.publish(publishTopic, (char*)
payload.c_str()))
  {
```

```
Serial.println("Publish OK");
  }
 }
  if(dist>100)
   {
    digitalWrite(LED,HIGH);
    String payload = "{\"Distance\":";
    payload += dist;
    payload += "}";
  Serial.print("\n");
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if(client.publish(publishTopic, (char*)
payload.c_str()))
   {
   Serial.println("Publish OK");
   }
  else
  {
   digitalWrite(LED,LOW);
   Serial.println("Publish FAILED");
  }
}
 }
```

