Assignment -4

Assignment Date	29 October 2022
Student Name	JAISHREE J
Student Roll Number	GCTC1914116
Maximum Marks	2 Marks

Question-1:
Write code and connections in wokwi for the ultrasonic sensor.
Whenever the distance is less than 100cms send an alert to the ibm cloud and display in the device recent events.

Code:

```
#define ECHO_PIN 2
#define TRIG_PIN 3

void setup() {
  Serial.begin(115200);
  pinMode(LED_BUILTIN, OUTPUT);
  pinMode(TRIG_PIN, OUTPUT);
  pinMode(ECHO_PIN, INPUT);
}

float readDistanceCM() {
  digitalWrite(TRIG_PIN, LOW);
  delayMicroseconds(2);
  digitalWrite(TRIG_PIN, HIGH);
  delayMicroseconds(10);
  digitalWrite(TRIG_PIN, LOW); int duration =
  pulseIn(ECHO_PIN, HIGH); return duration *
  0.034 / 2;
}

void loop() {
```

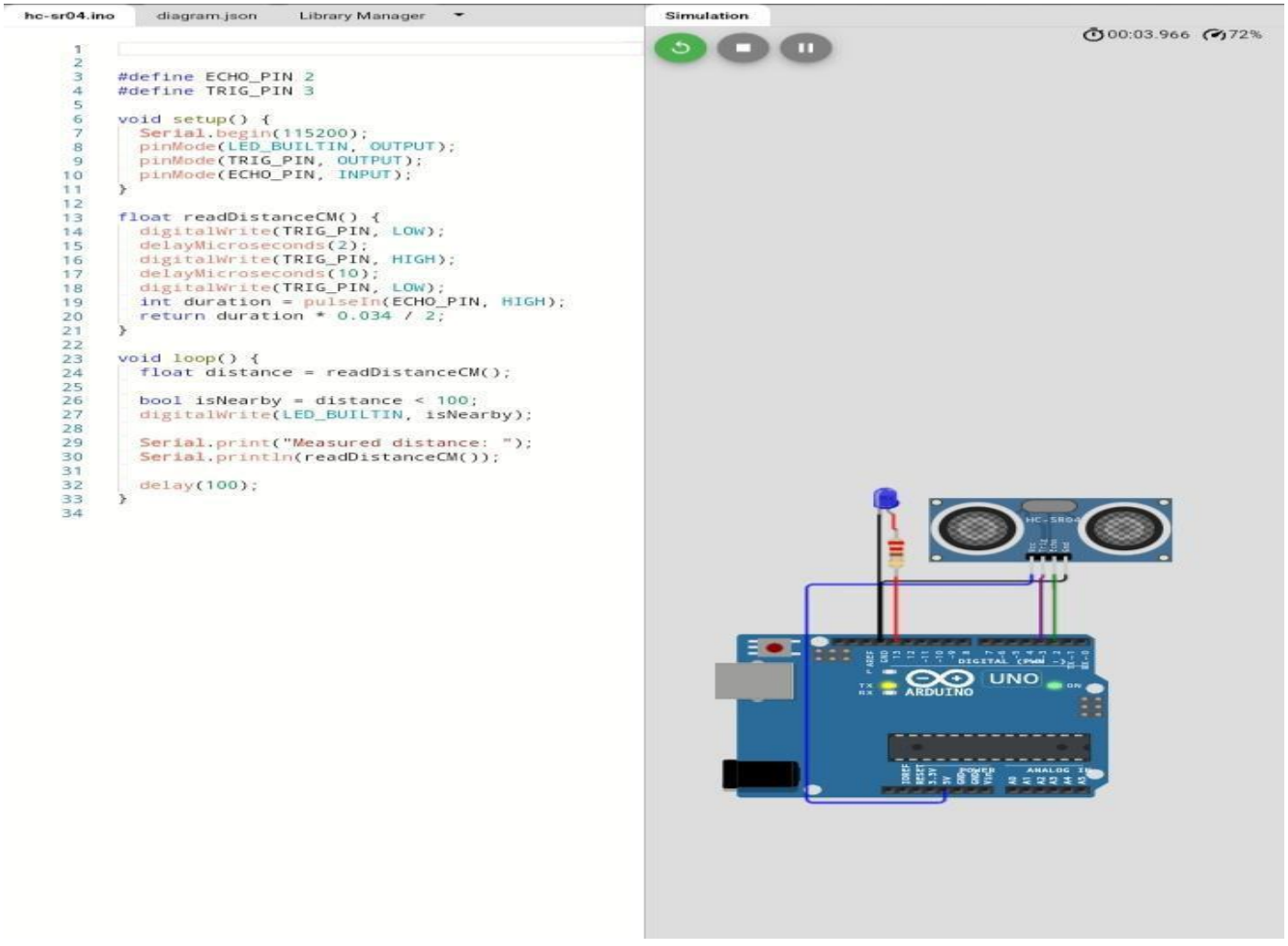
```
  float distance = readDistanceCM(); bool

  isNearby = distance < 100;

  digitalWrite(LED_BUILTIN, isNearby);


  Serial.print("Measured distance: ");
  Serial.println(readDistanceCM());

  delay(100);
}
```

DIAGRAM.JSON:

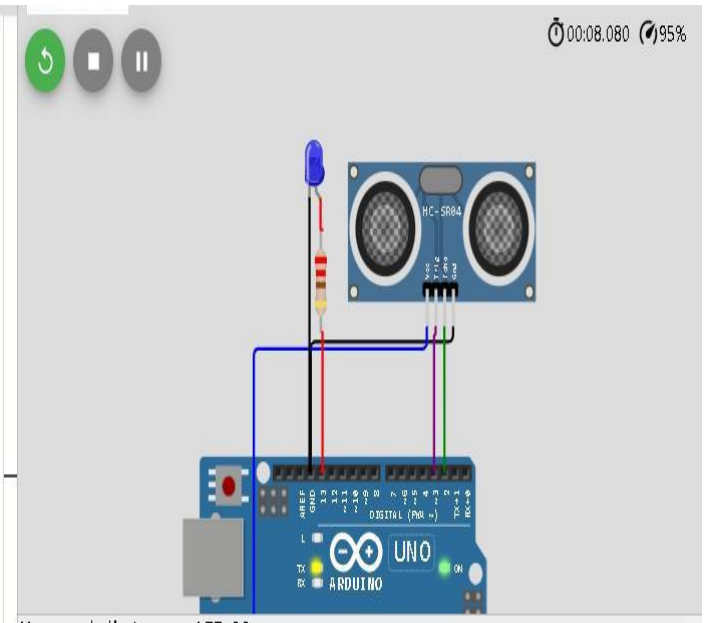
```
{
  "version": 1,
  "author": "sindhuja",
  "editor": "wokwi",
  "parts": [
    {
      "type": "wokwi-arduino-uno",
      "id": "uno",
      "top": 275.99,
      "left": 47.73, "rotate": 0,
      "hide": false,
      "attrs": {}
    },
    {
      "type": "wokwi-resistor",
      "id": "r1",
      "top": 165.87,
      "left": 142.81,
      "rotate": 90,
      "hide": false,
      "attrs": { "value": "220" }
    },
    {
      "type": "wokwi-led",
      "id": "led",
      "top": 87.29,
```

```
      "left": 147.05,
      "rotate": 0,
      "hide": false,
      "attrs": { "color": "blue" }
    },
    {
      "type": "wokwi-hc-sr04",
      "id": "ultrasonic",
      "top": 108.43,
      "left": 196.5, "rotate": 0,
      "hide": false,
      "attrs": { "distance": "180" }
    }
  ],
  "connections": [
    [ "uno:GND.1", "ultrasonic:GND", "black", [ "v-8", "*", "v8" ] ],
    [ "uno:2", "ultrasonic:ECHO", "green", [] ],
    [ "uno:3", "ultrasonic:TRIG", "purple", [ "*", "v4" ] ],
    [ "uno:5V", "ultrasonic:VCC", "blue", [ "v16", "h-96", "*", "v12" ] ],
    [ "uno:GND.1", "led:C", "black", [] ],
    [ "r1:1", "led:A", "red", [] ],
    [ "uno:13", "r1:2", "red", [] ]
  ]
}
```

OUTPUT:


hc-sr04.ino
diagram.json
Library Manager
Simulation
00:03.966
72%
#define ECHO_PIN 2
#define TRIG_PIN 3
void setup() {
Serial.begin(115200);
pinMode(LED_BUILTIN, OUTPUT);
pinMode(TRIG_PIN, OUTPUT);
pinMode(ECHO_PIN, INPUT);
}
float readDistanceCM() {
digitalWrite(TRIG_PIN, LOW);
delayMicroseconds(2);
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
int duration = pulseIn(ECHO_PIN, HIGH);
return duration * 0.034 / 2;
}
void loop() {
float distance = readDistanceCM();
bool isNearby = distance < 100;
digitalWrite(LED_BUILTIN, isNearby);
Serial.print("Measured distance: ");
Serial.println(readDistanceCM());
delay(100);
}
HC-SR04
UNO
ARDUINO

```
void setup() {
  Serial.begin(115200);
  pinMode(LED_BUILTIN, OUTPUT);
  pinMode(TRIG_PIN, OUTPUT);
  pinMode(ECHO_PIN, INPUT);
}

float readDistanceCM() {
  digitalWrite(TRIG_PIN, LOW);
  delayMicroseconds(2);
  digitalWrite(TRIG_PIN, HIGH);
  delayMicroseconds(10);
  digitalWrite(TRIG_PIN, LOW);
  int duration = pulseIn(ECHO_PIN, HIGH);
  return duration * 0.034 / 2;
}

void loop() {
  float distance = readDistanceCM();

  bool isNearby = distance < 100;
  digitalWrite(LED_BUILTIN, isNearby);

  Serial.print("Measured distance: ");
  Serial.println(readDistanceCM());

  delay(100);
}

```




```
Measured distance: 177.26
Measured distance: 177.24
Measured distance: 177.26
Measured distance: 177.24
Measured distance: 177.16
Measured distance: 177.24
Measured distance: 177.16
```