

Assignment -4

Wokwi and IBM cloud connection

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Maximum Marks	2 Marks

Question-1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100cms send "alert" to IBM cloud and display in device recent events (Upload document with wokwi share link and images of IBM cloud).

Solution:

Wokwi link: <https://wokwi.com/projects/347391182142177875>

Code:

```
#include <WiFi.h>//library for wifi
#include <PubSubClient.h>//library for MQTT

void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);

#define ORG "b59mry"//IBM ORGANITION ID

#define DEVICE_TYPE "Board"//Device type mentioned in ibm watson IOT Platform
#define DEVICE_ID "1111"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "12345678" //Token
String data3;

//----- Customise the above values -----
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of event perform and format in
which data to be send
char subscribetopic[] = "iot-2/cmd/command/fmt/String";// cmd REPRESENT command type AND
COMMAND IS TEST OF FORMAT STRING
char authMethod[] = "use-token-auth";// authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;//client id
```

```

//-----
WiFiClient wifiClient; // creating the instance for wificlient
PubSubClient client(server, 1883, callback ,wifiClient); //calling the predefined client id by passing
parameter like server id,portand wificredential

#define echoPin 10
#define trigPin 11
float duration;
float distance;

void setup() {
  pinMode(trigPin, OUTPUT);
  pinMode(echoPin, INPUT);
  Serial.begin(9600);
}

void loop() {
  // Clears the trigPin condition
  digitalWrite(trigPin, LOW);
  delayMicroseconds(2);
  // Sets the trigPin HIGH (ACTIVE) for 10 microseconds
  digitalWrite(trigPin, HIGH);
  delayMicroseconds(10);
  digitalWrite(trigPin, LOW);
  // Reads the echoPin, returns the sound wave travel time in microseconds
  duration = pulseIn(echoPin, HIGH);
  // Calculating the distance
  distance = duration * 0.034/2; // Speed of sound wave divided by 2 (go and back)
  // Displays the distance on the Serial Monitor
  Serial.print("Distance: ");
  Serial.print(distance);
  Serial.println(" cm");
  if(distance<100)
  {
    Serial.println("Alert:Object is between 100cm");
  }
}

/*.....retrieving to Cloud.....*/

void PublishData(float distance) {

```

```

mqttconnect();//function call for connecting to ibm
/*
    creating the String in in form JSon to update the data to ibm cloud
*/
String payload = "{\"distance\":";
payload += distance;
payload += "}";

Serial.print("Sending payload: ");
Serial.println(payload);

if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish ok");// if it sucessfully upload data on the cloud then it will print publish ok in
    Serial monitor or else it will print publish failed
} else {
    Serial.println("Publish failed");
}

}

void mqttconnect() {
    if (!client.connected()) {
        Serial.print("Reconnecting client to ");
        Serial.println(server);
        while (!client.connect(clientId, authMethod, token)) {
            Serial.print(".");
            delay(500);
        }

        initManagedDevice();
        Serial.println();
    }
}

void wificonnect() //function defination for wificonnect
{
    Serial.println();
    Serial.print("Connecting to ");

    WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
    while (WiFi.status() != WL_CONNECTED) {
        delay(500);
        Serial.print(".");
    }
}

```

```

}
Serial.println("");
Serial.println("WiFi connected");
Serial.println("IP address: ");
Serial.println(WiFi.localIP());
}

void initManagedDevice() {
  if (client.subscribe(subscribetopic)) {
    Serial.println((subscribetopic));
    Serial.println("subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
}

void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{

  Serial.print("callback invoked for topic: ");
  Serial.println(subscribetopic);
  for (int i = 0; i < payloadLength; i++) {
    //Serial.print((char)payload[i]);
    data3 += (char)payload[i];
  }
  Serial.println("data: "+ data3);
  data3="";
}

```

The screenshot shows the IBM Watson IoT Platform interface. The top navigation bar includes the IBM logo and the text 'IBM Watson IoT Platform'. The main content area is divided into several tabs: 'Identity', 'Device Information', 'Recent Events', 'State', and 'Logs'. The 'Recent Events' tab is currently selected, displaying a table of recent events. The table has four columns: 'Event', 'Value', 'Format', and 'Last Received'. The events listed are 'event_1' with 'distance' values of 34, 94, 93, 48, and 79, all in 'json' format, and received 'a few seconds ago'. A status bar at the bottom of the dashboard shows the device ID '1234', its status 'Disconnected', and a note '1 Simulation running'.

Event	Value	Format	Last Received
event_1	{"distance":34}	json	a few seconds ago
event_1	{"distance":94}	json	a few seconds ago
event_1	{"distance":93}	json	a few seconds ago
event_1	{"distance":48}	json	a few seconds ago
event_1	{"distance":79}	json	a few seconds ago

1234 Disconnected 1 Simulation running