

Assignment Date	22 October2022
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Student Roll Number	2019504053
Maximum Marks	2 Marks

ASSIGNMENT-4

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to IBM cloud and display in device recent events.

Source Code:

```
#include <WiFi.h>
#include <PubSubClient.h>
void callback(char* subscribtopic,byte* payload, unsigned int payloadLength);
#define ORG "w1e0ay"
#define DEVICE_TYPE "nodeMCU"
#define DEVICE_ID "1004"
#define TOKEN "95245848"
String data3;
char server[]= ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[]="iot-2/evt/distance/fmt/json";
char subscribeTopic[]="iot-2/cmd/test/fmt/String";
char authMethod[]="use-token-auth";
char token[]=TOKEN;
char clientID[]="d:"ORG":DEVICE_TYPE:DEVICE_ID;
WiFiClient wifiClient;
PubSubClient client(server,1883,callback,wifiClient);
#define ECHO_PIN 12
#define TRIG_PIN 13
#define led 14
void setup() {
// put your setup code here, to run once:
Serial.begin(115200);
pinMode(led, OUTPUT);
pinMode(TRIG_PIN, OUTPUT);
pinMode(ECHO_PIN, INPUT);
wificonnect();
mqttconnect();
}
float readDistanceCM() {
digitalWrite(TRIG_PIN, LOW);// Clear the trigger
delayMicroseconds(2);
digitalWrite(TRIG_PIN, HIGH);// Sets the trigger pin to HIGH state for 10
microseconds
delayMicroseconds(10);
```

```

digitalWrite(TRIG_PIN, LOW);
int duration=pulseIn(ECHO_PIN, HIGH);
//Serial.println(duration);
//duration = pulseIn(ECHO_PIN, HIGH);
return duration*0.017;
//Serial.println(duration);
}
void loop() {
float distance = readDistanceCM();
//Serial.println(distance);
bool isNearby = distance < 100;
digitalWrite(led, isNearby);
Serial.print("Measured distance: ");
Serial.println(distance);
if(distance<100){
PublishData2(distance);
}else{
PublishData1(distance);
}
//PublishData(distance);
delay(1000);
if(!client.loop()){
mqttconnect();
}
//delay(2000);
}
void PublishData1(float dist){
mqttconnect();
String payload= "{\"distance\":\"";
payload += dist;
payload+="}";
Serial.print("Sending payload:");
Serial.println(payload);
if(client.publish(publishTopic,(char*)payload.c_str())){
Serial.println("publish ok");
} else{
Serial.println("publish failed");
}
}
void PublishData2(float dist){
mqttconnect();
String payload= "{\"ALERT\":\"";
payload += dist;
payload+="}";
Serial.print("Sending payload:");
Serial.println(payload);
if(client.publish(publishTopic,(char*)payload.c_str())){
Serial.println("publish ok");
} else{
Serial.println("publish failed");
}
}
}

```

```

void mqttconnect(){
if(!client.connected()){
Serial.print("Reconnecting to ");
Serial.println(server);
while(!client.connect(clientID, authMethod, token)){
Serial.print(".");
delay(500);
}
initManagedDevice();
Serial.println();
}
}

void wificonnect(){
Serial.println();
Serial.print("Connecting to");
WiFi.begin("Wokwi-GUEST", "", 6);
while(WiFi.status() != WL_CONNECTED){
delay(500);
Serial.print(".");
}
Serial.println("");
Serial.println("WIFI CONNECTED");
Serial.println("IP address:");
Serial.println(WiFi.localIP());
}

void initManagedDevice(){
if(client.subscribe(subscribeTopic)){
Serial.println((subscribeTopic));
Serial.println("subscribe to cmd ok");
}else{
Serial.println("subscribe to cmd failed");}}
void callback(char* subscribeTopic, byte* payload, unsigned int
payloadLength){
Serial.print("callback invoked for topic:");
Serial.println(subscribeTopic);
for(int i=0; i<payloadLength; i++){
data3 += (char)payload[i];}
Serial.println("data:" + data3);
if(data3=="lighton"){
Serial.println(data3);
digitalWrite(led, HIGH);
}else{
Serial.println(data3);
digitalWrite(led, LOW);}
data3="";
}

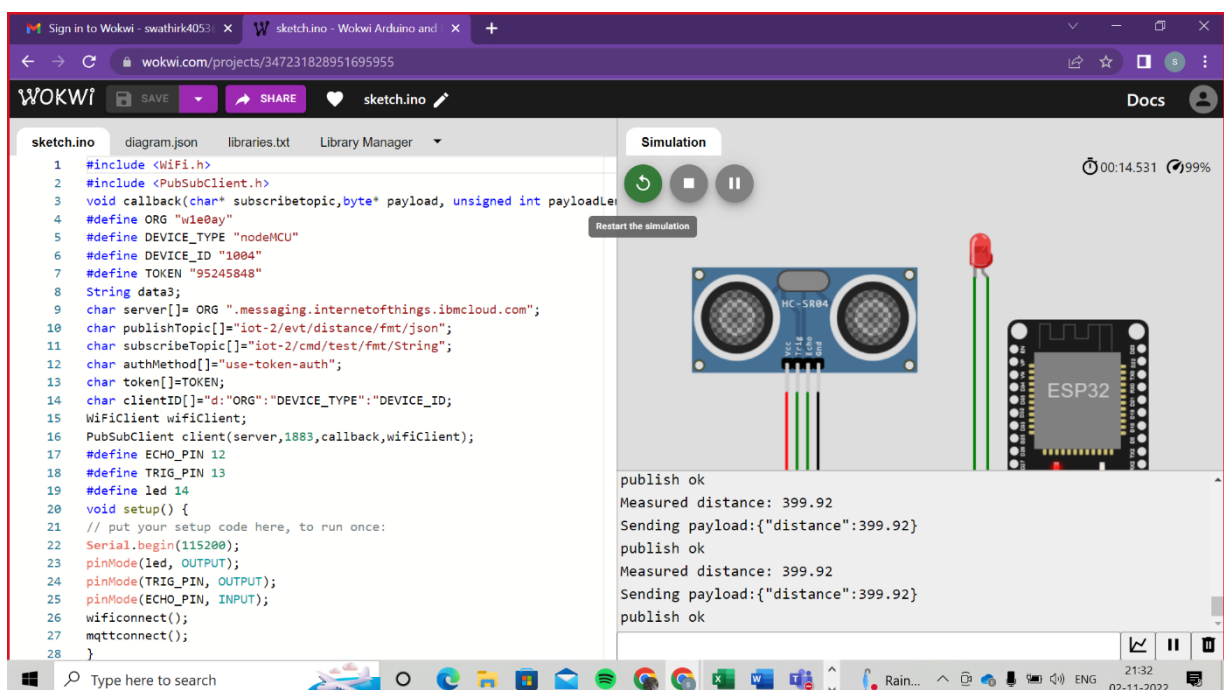
```

WOKWI LINK:

<https://wokwi.com/projects/347231828951695955>

OUTPUT:

NORMAL CASE:



ALERT CASE:

```
1 #include <WiFi.h>
2 #include <PubSubClient.h>
3 void callback(char* subscribtopic,byte* payload,unsigned int payloadLen)
4 #define ORG "w1e0ay"
5 #define DEVICE_TYPE "nodeMCU"
6 #define DEVICE_ID "1004"
7 #define TOKEN "95245848"
8 String data3;
9 char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
10 char publishTopic[] = "iot-2/evt/distance/fmt/json";
11 char subscribeTopic[] = "iot-2/cmd/test/fmt/String";
12 char authMethod[] = "use-token-auth";
13 char token[] = TOKEN;
14 char clientId[] = "d:ORG:DEVICE_TYPE:DEVICE_ID";
15 WiFiClient wifiClient;
16 PubSubClient client(server,1883,callback,wifiClient);
17 #define ECHO_PIN 12
18 #define TRIG_PIN 13
19 #define led 14
20 void setup() {
21 // put your setup code here, to run once:
22 Serial.begin(115200);
23 pinMode(led, OUTPUT);
24 pinMode(TRIG_PIN, OUTPUT);
25 pinMode(ECHO_PIN, INPUT);
26 wificonnect();
27 mqttconnect();
28 }
```

publish ok
Measured distance: 68.97
Sending payload:{"ALERT":68.97}
publish ok
Measured distance: 68.97
Sending payload:{"ALERT":68.97}
publish ok

IBM CLOUD STORAGE:

Device Drilldown - 1004

Connection Information

Recent Events

State

This table shows a list of data points that are reported by this device.

Showing Raw Data | No Interfaces Available

Property	Value	Type	Event	Last Received
ALERT	68.97	Number	distance	a few seconds ago

Device Information

View basic device information including location and manufacturer.

Edit Device Information

Service Details - IBMWatson IoT PlatformIBM TermsIBM SkillsBuild SoftwareWokwi - Online Arduino IDENew Tab

w1e0ay.internetofthings.ibmcloud.com/dashboard/devices/drilldown/nodeMCU:1004?returnTo=/devices/browse

GmailYouTubeMapsOnline C++ CompilerJava Programs | Java

IBM Watson IoT Platform2019504053@student.annauniv.eduID: w1e0ay

Back

Device Drilldown - 1004

Connection Information

Recent Events

State

Device Information

Metadata

Diagnostics

Connection Logs

Device Actions

State

This table shows a list of data points that are reported by this device.

Showing Raw Data

 | No Interfaces Available

Property	Value	Type	Event	Last Received
distance	399.92	Number	distance	a few seconds ago

Device Information

View basic device information including location and manufacturer.

Edit Device Information

Type here to search

Rain...

21:3002-11-2022