ASSIGNMENT 4

Ultrasonic sensor simulation in Wokwi

Question: Write a code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100cms send an "Alert" to IBM cloud and display in the device recent events.

Wokwi simulation link: https://wokwi.com/projects/347124503089775188

WOKWI OUTPUT SCREENSHOT:

```
sketch.ino diagram.json Library Manager 🔻
                                                                                                                                                                                                                               Ō00:30.796 (₹)99%
             roid setup() {
   Serial.begin(115200);
   pinMode(LED_BUILTIN, OUTPUT);
   pinMode(TRIG_PIN, OUTPUT);
   pinMode(ECHO_PIN, INPUT);
           float readDistanceCM() {
  digitalWrite(TRIG_PIN, LOW);
              delayMicroseconds(2);
digitalWrite(TRIG_PIN, HIGH);
             digitalWrite(IRLG_PIN, HIGH);
delayWicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
int duration = pulseIn(ECHO_PIN, HIGH);
return duration * 0.034 / 2;
                                                                                                                                                                              ES HOUSE PROPERTY (PWH -) X
                                                                                                                              Measured distance: 218.94
                                                                                                                              Measured distance: 239.84
           void loop() {
   float distance = readDistanceCM();
if(distance<=100)</pre>
                                                                                                                              Measured distance: 239.84
                                                                                                                             Measured distance: 113.56
                                                                                                                               person detected
                                                                                                                               person detected
                                                                                                                               person detected
            else{
Serial.print("Measured distance: ");
                                                                                                                                                                                                                                         ∠ II □
```

CODE:

```
#define ECHO_PIN 2
#define TRIG_PIN 3
#define organization = "md8rdq"
#define deviceType = "123"
#define deviceId = "123456"
#define authMethod = "token"
#define authToken = "Titik@2002"

void setup() {
    Serial.begin(115200);
    pinMode(LED_BUILTIN, OUTPUT);
    pinMode(TRIG_PIN, OUTPUT);
    pinMode(ECHO_PIN, INPUT);
}
```

```
float readDistanceCM() {
  digitalWrite(TRIG_PIN, LOW);
  delayMicroseconds(2);
  digitalWrite(TRIG_PIN, HIGH);
  delayMicroseconds(10);
  digitalWrite(TRIG_PIN, LOW);
  int duration = pulseIn(ECHO_PIN, HIGH);
  return duration * 0.034 / 2;
void loop() {
  float distance = readDistanceCM();
if(distance<=100)</pre>
  Serial.println(" person detected");
else{
  Serial.print("Measured distance: ");
  Serial.println(readDistanceCM());
  delay(1000);
```





