ASSIGNMENT 4

Ultrasonic sensor simulation in Wokwi

Question: Write a code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100cms send an "Alert" to IBM cloud and display in the device recent events.

Wokwi simulation link: https://wokwi.com/projects/347124503089775188

WOKWI OUTPUT SCREENSHOT:

```
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                                                                                                                           Simulation
                                                                                                                                                                                                                   Ō00:30.796 (⁴)99%
                oid setup() {
Serial.begin(115200);
pinMode(LED_BUILTIN, OUTPUT);
pinMode(TRIG_PIN, OUTPUT);
pinMode(ECHO_PIN, INPUT);
                                                                                                                                                                       -111
                                                                                                                                                                                                   M
             float readDistanceCM() {
   digitalWrite(TRIG_PIN, LOW);
   delayMicroseconds(2);
   digitalWrite(TRIG_PIN, HIGH);
                digitatwrite(IRIG_FIM, INCOMP);
delayMicroseconds(10);
digitatWrite(TRIG_FIM, LOW);
int duration = pulseIn(ECHO_FIM, HIGH);
return duration * 0.034 / 2;
                                                                                                                        Measured distance: 218.94
                                                                                                                        Measured distance: 239.84
                roid loop() {
  float distance = readDistanceCM();
                                                                                                                        Measured distance: 239.84
                                                                                                                        Measured distance: 113.56
              if(distance<=100)
                                                                                                                         person detected
                                                                                                                         person detected
                                                                                                                         person detected
              else{
Serial.print("Measured distance: ");
                                                                                                                                                                                                                            <u>⊬</u> II 1
```

CODE:

```
#define ECHO_PIN 2
#define TRIG_PIN 3
#define organization = "md8rdq"
#define deviceType = "123"
#define deviceId = "123456"
#define authMethod = "token"
#define authToken = "Titik@2002"

void setup() {
    Serial.begin(115200);
    pinMode(LED_BUILTIN, OUTPUT);
    pinMode(TRIG_PIN, OUTPUT);
    pinMode(ECHO_PIN, INPUT);
}
```

```
float readDistanceCM() {
  digitalWrite(TRIG_PIN, LOW);
  delayMicroseconds(2);
  digitalWrite(TRIG PIN, HIGH);
  delayMicroseconds(10);
  digitalWrite(TRIG_PIN, LOW);
  int duration = pulseIn(ECHO_PIN, HIGH);
  return duration * 0.034 / 2;
void loop() {
  float distance = readDistanceCM();
if(distance<=100)</pre>
  Serial.println(" person detected");
else{
  Serial.print("Measured distance: ");
  Serial.println(readDistanceCM());
  delay(1000);
```





