

Name: HARINI.N

REG NO: 19EC07

ASSIGNMENT 4-BUZZER FOR ULTRASONIC SENSOR

SOURCE CODE:

```
int t=2;

int e=3;

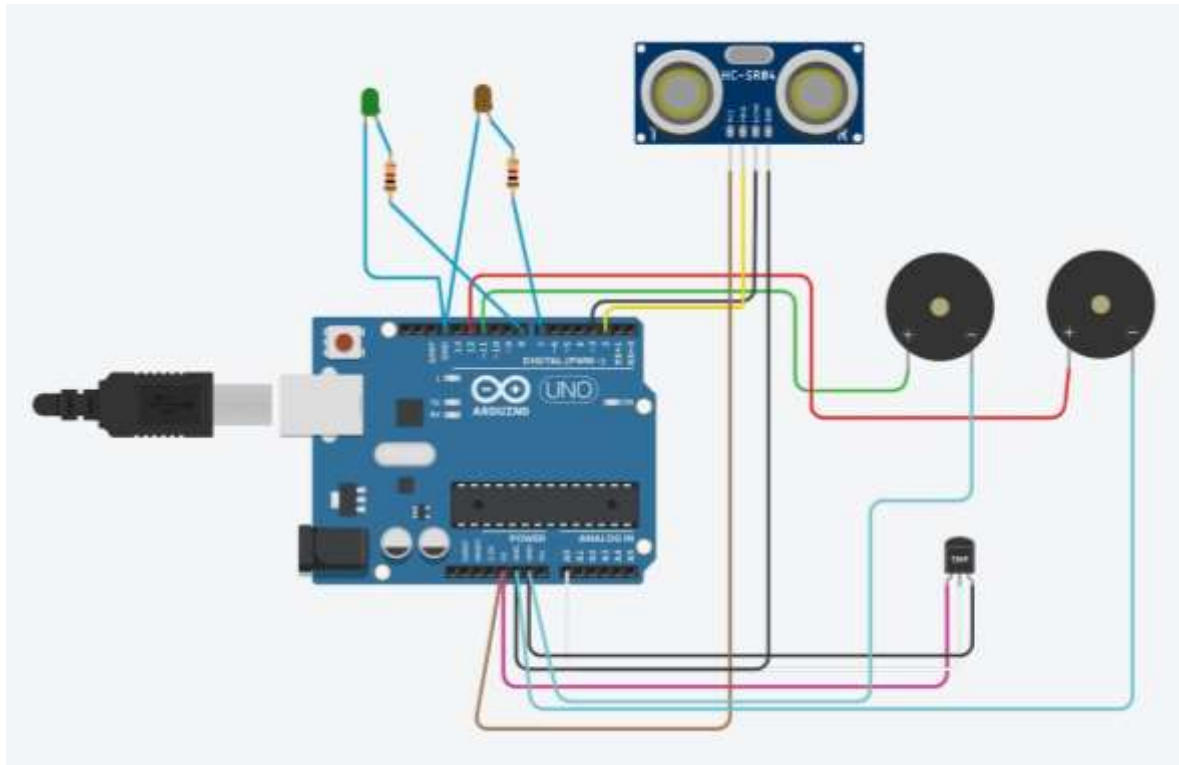
void setup()
{
  Serial.begin(9600);
  pinMode(t,OUTPUT
);
  pinMode(e,INPUT);
  pinMode(12,OUTPU
T);
}

void loop()
{
  //ultrasonic sensor
  digitalWrite(t,LOW);
  digitalWrite(t,HIGH);
  delayMicroseconds(1
0);
  digitalWrite(t,LOW);
```

```
float
dur=pulseIn(e,HIGH);
float dis=(dur*0.0343)/2;
Serial.print("Distance is:
");Serial.println(dis);

//LED ON
if(dis>=100)
{
digitalWrite(8,HIGH);
digitalWrite(7,HIGH);
}

//Buzzer For ultrasonic
Sensorif(dis>=100)
{
for(int i=0; i<=30000; i=i+10)
{
tone(12,i);
delay(1000);
noTone(12);
;
delay(1000);
}
}
```



Name: KANIMOZHILM

REG NO: 19EC09

ASSIGNMENT 4-BUZZER FOR ULTRASONIC SENSOR

SOURCE CODE:

```
int t=2;

int e=3;

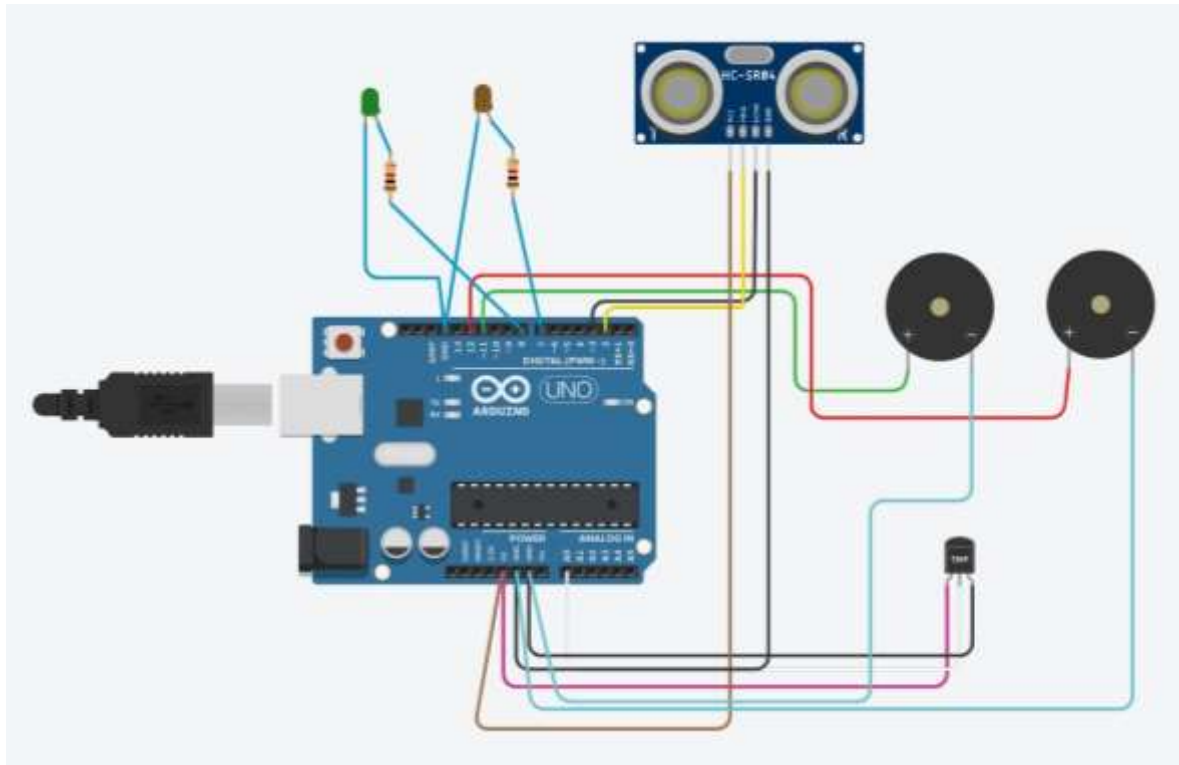

void setup()
{
  Serial.begin(9600);
  pinMode(t,OUTPUT
);
  pinMode(e,INPUT);
  pinMode(12,OUTPU
T);
}


void loop()
{
  //ultrasonic sensor
  digitalWrite(t,LOW);
  digitalWrite(t,HIGH);
  delayMicroseconds(1
0);
  digitalWrite(t,LOW);
```

```
float
dur=pulseIn(e,HIGH);
float dis=(dur*0.0343)/2;
Serial.print("Distance is:
");Serial.println(dis);

//LED ON
if(dis>=100)
{
digitalWrite(8,HIGH);
digitalWrite(7,HIGH);
}

//Buzzer For ultrasonic
Sensorif(dis>=100)
{
for(int i=0; i<=30000; i=i+10)
{
tone(12,i);
delay(1000);
noTone(12);
;
delay(1000);
}
}
```



Name: KANAGA.E

REG NO: 19EC08

ASSIGNMENT 4-BUZZER FOR ULTRASONIC SENSOR

SOURCE CODE:

```
int t=2;

int e=3;

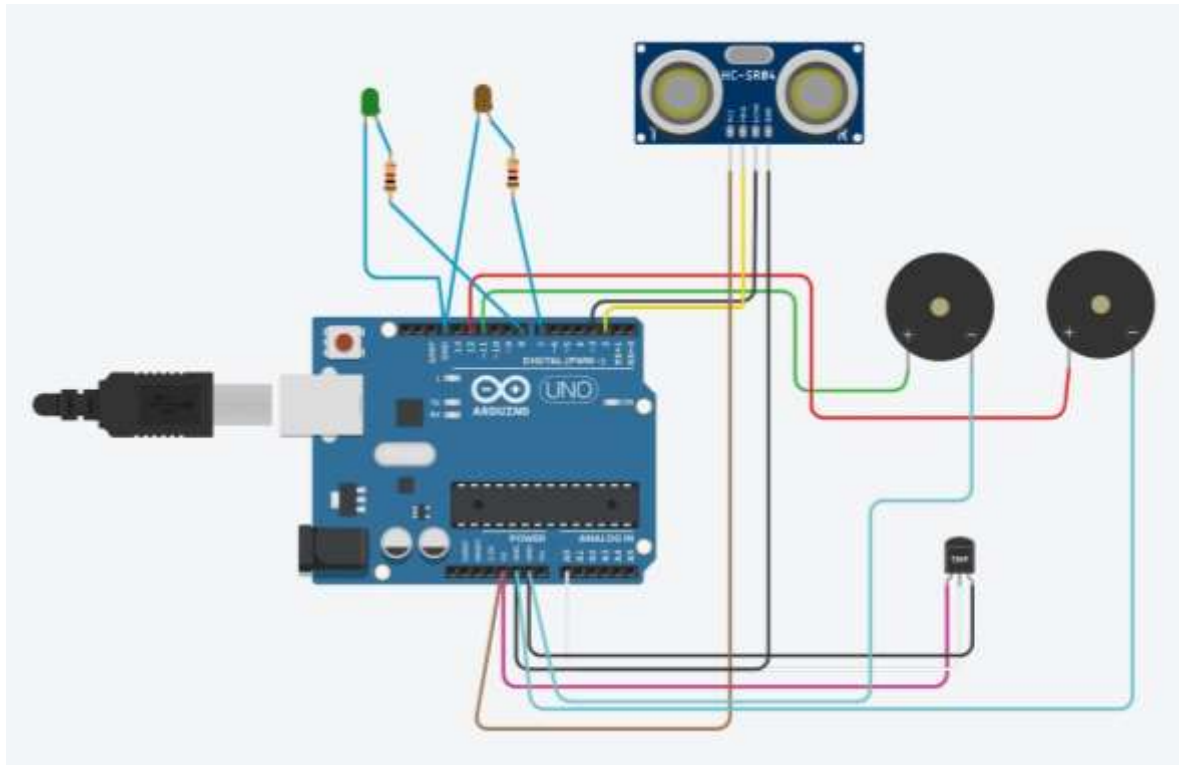

void setup()
{
  Serial.begin(9600);
  pinMode(t,OUTPUT
);
  pinMode(e,INPUT);
  pinMode(12,OUTPU
T);
}


void loop()
{
  //ultrasonic sensor
  digitalWrite(t,LOW);
  digitalWrite(t,HIGH);
  delayMicroseconds(1
0);
  digitalWrite(t,LOW);
```

```
float
dur=pulseIn(e,HIGH);
float dis=(dur*0.0343)/2;
Serial.print("Distance is:
");Serial.println(dis);

//LED ON
if(dis>=100)
{
    digitalWrite(8,HIGH);
    digitalWrite(7,HIGH);
}

//Buzzer For ultrasonic
Sensorif(dis>=100)
{
    for(int i=0; i<=30000; i=i+10)
    {
        tone(12,i);
        delay(1000);
    }
    noTone(12);
    delay(1000);
}
```

Name: PREETHIKA.S

REG NO: 19EC14

ASSIGNMENT 4-BUZZER FOR ULTRASONIC SENSOR

SOURCE CODE:

```
int t=2;

int e=3;

void setup()
{
  Serial.begin(9600);
  pinMode(t,OUTPUT
);
  pinMode(e,INPUT);
  pinMode(12,OUTPU
T);
}

void loop()
{
  //ultrasonic sensor
  digitalWrite(t,LOW);
  digitalWrite(t,HIGH);
  delayMicroseconds(1
0);
  digitalWrite(t,LOW);
```

```
float
dur=pulseIn(e,HIGH);
float dis=(dur*0.0343)/2;
Serial.print("Distance is:
");Serial.println(dis);

//LED ON
if(dis>=100)
{
digitalWrite(8,HIGH);
digitalWrite(7,HIGH);
}

//Buzzer For ultrasonic
Sensorif(dis>=100)
{
for(int i=0; i<=30000; i=i+10)
{
tone(12,i);
delay(1000);
noTone(12);
;
delay(1000);
}
}
```

