Prince Dr. K. Vasudevan College of Engineering and Technology

ASSIGNMENT-4

PROJECT TITTLE: Personal assistance for seniors who are self reliant.

| TEAM ID | PNT2022TMID38119 |
|--------------|------------------|
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| MAXIMUM MARK | 2 MARKS |

Assignment Question:

Write code and connections in wokwi for ultrasonic sensor.

Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

Wokowi Link: https://wokwi.com/projects/347327129936986708

```
#include <WiFi.h>//library for wifi
#include <PubSubClient.h>//library for MQtt

#define ECHO_GPIO 12
#define TRIGGER_GPIO 13
#define MAX_DISTANCE_CM 100 // Maximum of 5 meters
#include "Ultrasonic.h"

Ultrasonic ultrasonic(13, 12);
int distance;

void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);

//------credentials of IBM Accounts-----

#define ORG "kizp10"/IBM ORGANITION ID
#define DEVICE_TYPE "IOTdevice"//Device type mentioned in ibm watson IOT Platform
#define DEVICE_ID "1234567890" //Device ID mentioned in ibm watson IOT Platform
#define TOKEN "1234567890" //Token

String data3;
```

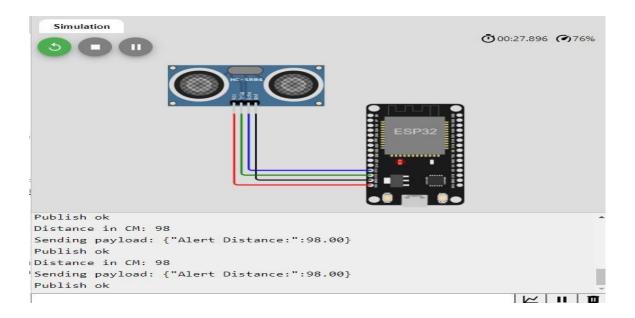
```
//----- Customise the above values ------
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of event
perform and format in which data to be send
char subscribetopic[] = "iot-2/cmd/command/fmt/String";// cmd REPRESENT command
type AND COMMAND IS TEST OF FORMAT STRING
char authMethod[] = "use-token-auth";// authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;//client id
//--
WiFiClient wifiClient; // creating the instance for wificlient
PubSubClient client(server, 1883, callback, wifiClient); //calling the predefined client id
by passing parameter like server id, portand wificredential
void setup()// configureing the ESP32
 Serial.begin(115200);
 delay(10);
 Serial.println();
 wificonnect();
 mqttconnect();
void loop()// Recursive Function
{
 distance = ultrasonic.read(CM);
 if (distance < 100) {
 Serial.print("Distance in CM: ");
 Serial.println(distance);
 PublishData(distance);
 delay(1000);
  if (!client.loop()) {
   mqttconnect();
 }
 delay(1000);
```

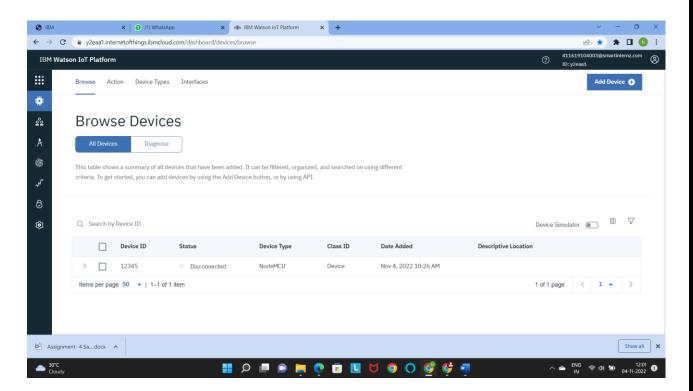
```
}
/*.....*/
void PublishData(float temp) {
 mqttconnect();//function call for connecting to ibm
  creating the String in in form JSon to update the data to ibm cloud
 String payload = "{\"Alert Distance:\":";
 payload += temp;
 payload += "}";
 Serial.print("Sending payload: ");
 Serial.println(payload);
 if (client.publish(publishTopic, (char*) payload.c_str())) {
  Serial.println("Publish ok");// if it sucessfully upload data on the cloud then it will
print publish ok in Serial monitor or else it will print publish failed
} else {
  Serial.println("Publish failed");
 }
}
void mqttconnect() {
if (!client.connected()) {
  Serial.print("Reconnecting client to ");
  Serial.println(server);
  while (!!!client.connect(clientId, authMethod, token)) {
   Serial.print(".");
   delay(500);
  initManagedDevice();
 }
```

```
void wificonnect() //function defination for wificonnect
 Serial.println();
 Serial.print("Connecting to ");
 WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the
connection
 while (WiFi.status() != WL_CONNECTED) {
  delay(500);
  Serial.print(".");
 }
 Serial.println("");
 Serial.println("WiFi connected");
 Serial.println("IP address: ");
 Serial.println(WiFi.localIP());
}
void initManagedDevice() {
if (client.subscribe(subscribetopic)) {
  Serial.println((subscribetopic));
  Serial.println("subscribe to cmd OK");
} else {
  Serial.println("subscribe to cmd FAILED");
}
}
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{
 Serial.print("callback invoked for topic: ");
 Serial.println(subscribetopic);
 for (int i = 0; i < payloadLength; i++) {</pre>
 //Serial.print((char)payload[i]);
  data3 += (char)payload[i];
 Serial.println("data: " + data3);
 if (data3 == "lighton")
 }
```

```
else
{
    Serial.println(data3);
}
data3 = "";
}
```

When the distance is less than 100cm the alert is not sent to the IBM cloud





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