ASSIGNMENT – 4

Assignment date	**29 October 2022**
Project name	**Iot Based Smart Crop Protection System for Agriculture**
Team ID	**PNT2022TMID08774**
Maximum mark	**2 Marks**

QUESTION 1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100cms send "alert" to ibm cloud and display in device recent events.

WOKWI LINK: https://wokwi.com/projects/347127533902234196

CODE:

```
#include <WiFi.h>
#include <PubSubClient.h>

void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);

#define ORG "akptwo"
#define DEVICE_TYPE "ESP32_Controller"
#define DEVICE_ID "BME280_Sensor"
#define TOKEN "pySeb&4Lc@4tEHID(n"
String data3;
float dist;

char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char subscribetopic[] = "iot-2/cmd/test/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;


WiFiClient wifiClient;
```

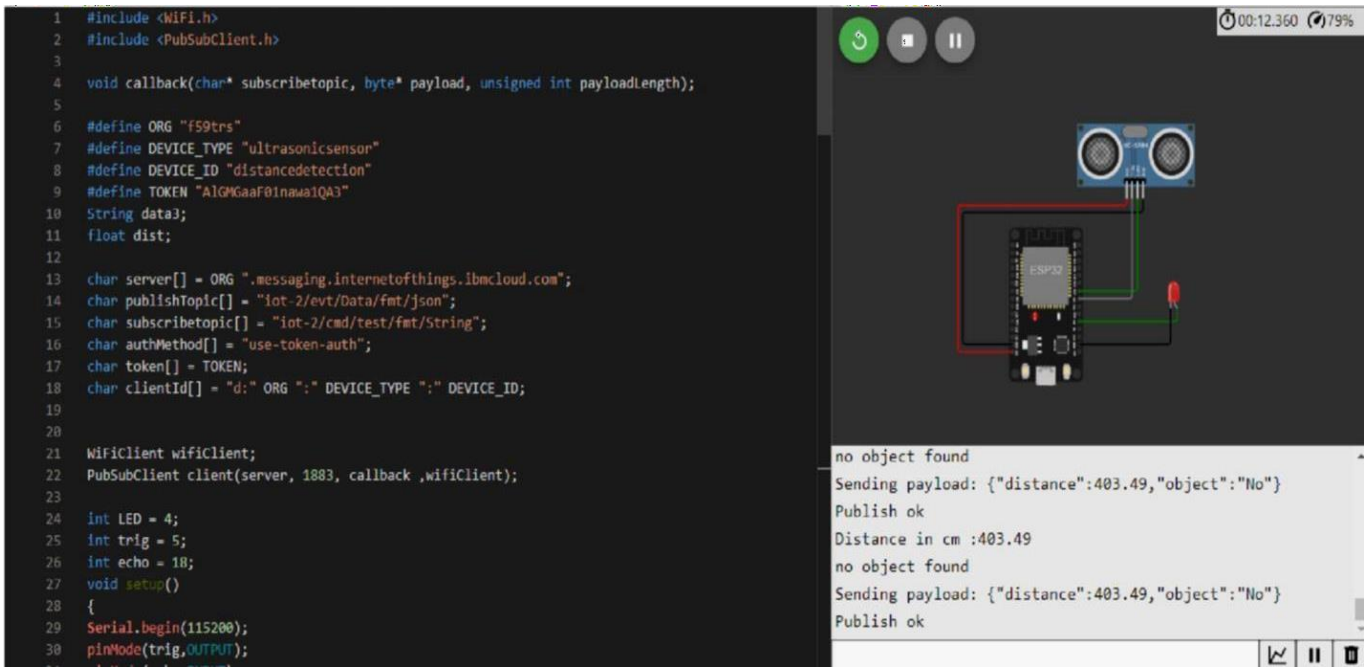
```
PubSubClient client(server, 1883, callback ,wifiClient);

int LED = 4;
int trig = 5;
int echo = 18;
void setup()
{
Serial.begin(115200);
pinMode(trig,OUTPUT);
pinMode(echo,INPUT);
pinMode(LED, OUTPUT);
delay(10);
wificonnect();
mqttconnect();
}
void loop()
{

 digitalWrite(trig,LOW);
  digitalWrite(trig,HIGH);
  delayMicroseconds(10);
  digitalWrite(trig,LOW);
  float dur = pulseIn(echo,HIGH);
  float dist = (dur * 0.0343)/2;
  Serial.print ("Distance in cm :");
  Serial.println(dist);

  PublishData(dist);
  delay(1000);
  if (!client.loop()) {
    mqttconnect();
  }
}

void PublishData(float dist) {
  mqttconnect();
  String object;
  if (dist <100)
  {
    digitalWrite(LED,HIGH);
    Serial.println("object is near");
    object = "Near";
  }
  else
  {
```

```
    digitalWrite(LED,LOW);
    Serial.println("no object found");
    object = "No";
  }

  String payload = "{\"distance\":";
  payload += dist;
  payload += "," "\"object\":\"";
  payload += object;
  payload += "\"}";

    Serial.print("Sending payload: ");
  Serial.println(payload);

  if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish ok");
  } else {
    Serial.println("Publish failed");
  }
}
void mqttconnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting client to ");
    Serial.println(server);
    while (!!!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);
    }
     initManagedDevice();
     Serial.println();
  }
}
void wificonnect()
{
  Serial.println();
  Serial.print("Connecting to ");
  WiFi.begin("Wokwi-GUEST", "", 6);
  while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
  }
  Serial.println("");
  Serial.println("WiFi connected");
  Serial.println("IP address: ");
  Serial.println(WiFi.localIP());
```

```
}
void initManagedDevice() {
  if (client.subscribe(subscribetopic)) {
    Serial.println((subscribetopic));
    Serial.println("subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
}
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
  {
  Serial.print("callback invoked for topic: ");
  Serial.println(subscribetopic);
  for (int i = 0; i < payloadLength; i++) {
    data3 += (char)payload[i];
  }
data3="";
  }
```

OUTPUT:

When object is nearer to Ultrasonic sensor



Data sent to the ibm cloud when the object is near