

## Delivery of Sprint-2

|              |   |
|--------------|---|
| DATE         | 31 October 2022   |
| Team ID      | PNT2022TMID15172  |
| Project Name | Project : Smart Waste Management System For Metropolitan Cities |

### Work Done in Sprint-2:

#### Code for Sensors Data Transfer to IBM Cloud:

```
#include <WiFi.h> // library for wifi
#include <PubSubClient.h> // library for MQTT
#include <LiquidCrystal_I2C.h>
#include <mjson.h>
LiquidCrystal_I2C lcd(0x27, 20, 4);

//----- credentials of IBM Accounts -----
-----

#define ORG "ffw11q" // IBM organisation id
#define DEVICE_TYPE "Raspberry-pi" // Device type mentioned in
ibm watson iot platform
#define DEVICE_ID "12345" // Device ID mentioned in ibm watson
iot platform
#define TOKEN "12345678" // Token

//----- customise above values -----
-----

char server[] = ORG
".messaging.internetofthings.ibmcloud.com"; // server name
char publishTopic[] = "iot-
2/evt/data/fmt/json"; // topic name and type of
event perform and format in which data to be send
char topic[] = "iot-
2/cmd/led/fmt/String"; // cmd Represent
type and command is test format of strings
char authMethod[] = "use-token-
auth"; // authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":"
DEVICE_ID; //Client id

//-----
-----
```

```

WiFiClient wifiClient;
creating instance for wificlient
PubSubClient client(server, 1883, wifiClient);

#define ECHO_PIN 12
#define TRIG_PIN 13
float dist;
String data3;
bool SealBin = true;
void setup()
{
    Serial.begin(115200);
    pinMode(LED_BUILTIN, OUTPUT);
    pinMode(TRIG_PIN, OUTPUT);
    pinMode(ECHO_PIN, INPUT);
    //pir pin
    pinMode(34, INPUT);

    //ledpins
    pinMode(23, OUTPUT);
    pinMode(2, OUTPUT);
    pinMode(4, OUTPUT);
    pinMode(15, OUTPUT);

    lcd.init();
    lcd.backlight();
    lcd.setCursor(1, 0);
    lcd.print("");
    wifiConnect();
    mqttConnect();
}

float readcmCM()
{
    digitalWrite(TRIG_PIN, LOW);
    delayMicroseconds(2);
    digitalWrite(TRIG_PIN, HIGH);
    delayMicroseconds(10);
    digitalWrite(TRIG_PIN, LOW);
    int duration = pulseIn(ECHO_PIN, HIGH);
    return duration * 0.034 / 2;
}

void loop()
{

```

```

    lcd.clear();

    publishData();
    delay(500);
    if (!client.loop())
    {
        mqttConnect(); // function call to
connect to IBM
    }
}

/* -----retrieving to cloud-----
-----*/

void wifiConnect()
{
    Serial.print("Connecting to ");
    Serial.print("Wifi");
    WiFi.begin("Wokwi-GUEST", "", 6);
    while (WiFi.status() != WL_CONNECTED)
    {
        delay(500);
        Serial.print(".");
    }
    Serial.print("WiFi connected, IP address: ");
    Serial.println(WiFi.localIP());
}
void mqttConnect()
{
    if (!client.connected())
    {
        Serial.print("Reconnecting MQTT client to ");
        Serial.println(server);
        while (!client.connect(clientId, authMethod, token))
        {
            Serial.print(".");
            delay(500);
        }
        initManagedDevice();
        Serial.println();
    }
}
void initManagedDevice()
{
    if (client.subscribe(topic))
    {
        Serial.println("IBM subscribe to cmd OK");
    }
}

```

```

        else
        {
            Serial.println("subscribe to cmd FAILED");
        }
    }
}

void publishData()
{
    float cm = readcmCM();

    if(digitalRead(34)) //pir motion detection
    {
        Serial.println("Motion Detected");
        Serial.println("Lid Opened");
        digitalWrite(15, HIGH);

        if(digitalRead(34)== true)
        {
            if(cm <= 100) //Bin level
            detection
            {
                digitalWrite(2, HIGH);
                Serial.println("High Alert!!!,Trash bin is about to be full");
                Serial.println("Lid Closed");
                lcd.print("Full! Don't use");
                delay(2000);
                lcd.clear();
                digitalWrite(4, LOW);
                digitalWrite(23, LOW);
            }
            else if(cm > 100 && cm < 180)
            {
                digitalWrite(4, HIGH);
                Serial.println("Warning!!,Trash is about to cross 50% of bin level");
                digitalWrite(2, LOW);
                digitalWrite(23, LOW);
            }
        }
        else if(cm > 180)
        {
            digitalWrite(23, HIGH);
            Serial.println("Bin is available");
            digitalWrite(2,LOW);
            digitalWrite(4, LOW);
        }

        delay(10000);
    }
}

```

```

        Serial.println("Lid Closed");
    }
    else
    {
        Serial.println("No motion detected");
        digitalWrite(2, LOW);
        digitalWrite(15, LOW);
        digitalWrite(4, LOW);
        digitalWrite(23, LOW);
    }

}

else
{
    digitalWrite(15, LOW);

}

    if(cm <= 100)
    {
        digitalWrite(21,HIGH);
        String payload = "{\"High_Alert\":";
        payload += cm;
        payload += " }";
        Serial.print("\n");
        Serial.print("Sending payload: ");
        Serial.println(payload);

        if (client.publish(publishTopic, (char*) payload.c_str()))           // if data
        is uploaded to cloud successfully,prints publish ok else prints publish failed
        {
            Serial.println("Publish OK");
        }
    }
    else if(cm <= 180)
    {
        digitalWrite(22,HIGH);
        String payload = "{\"Warning\":";
        payload += cm ;
        payload += " }";
        Serial.print("\n");
        Serial.print("Sending payload: ");
        Serial.println(payload);
        if(client.publish(publishTopic, (char*) payload.c_str()))
        {
            Serial.println("Publish OK");
        }
    }

```

```

else
{
  Serial.println("Publish FAILED");
}
}
else if(cm > 180)
{
  digitalWrite(23,HIGH);
  String payload = "{";
  payload += cm;
  payload += " }";
  Serial.print("\n");
  Serial.print("Sending payload: ");
  Serial.println(payload);

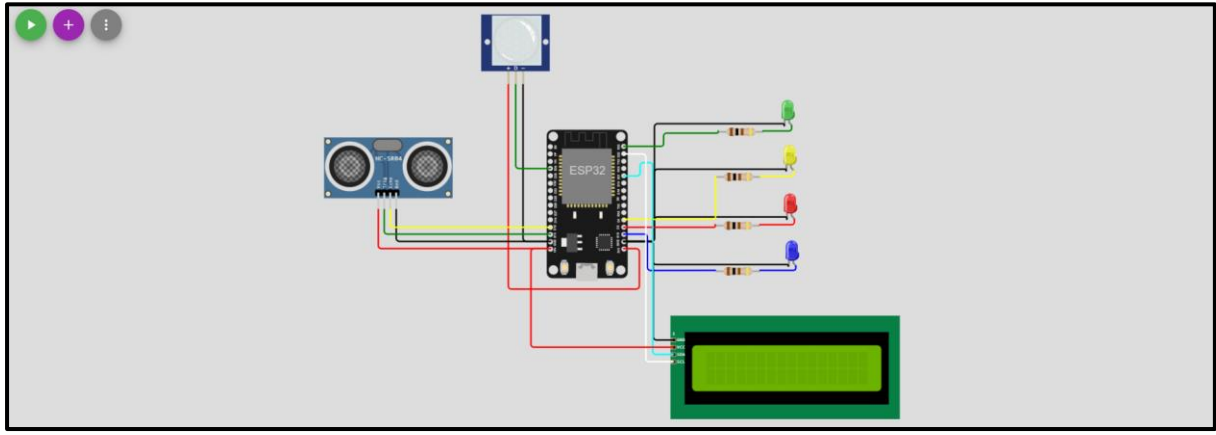
  if (client.publish(publishTopic, (char*) payload.c_str())) // if data
  is uploaded to cloud successfully,prints publish ok else prints publish failed
  {
    Serial.println("Publish OK");
  }

}

float inches = (cm / 2.54); //print on
lcd
  lcd.setCursor(0,0);
  lcd.print("Inches");
  lcd.setCursor(4,0);
  lcd.setCursor(12,0);
  lcd.print("cm");
  lcd.setCursor(1,1);
  lcd.print(inches, 1);
  lcd.setCursor(11,1);
  lcd.print(cm, 1);
  lcd.setCursor(14,1);
  delay(1000);
  lcd.clear();
}

```

## Simulation Circuit Diagram:



## Simulation Output:

W ESP32-IBMconnection[original] x +

wokwi.com/projects/348707873452196436

WOKWI SAVE SHARE Sprint-2-ESP32-IBM-Connection-Koliyar Nikhil Durairaj Docs

esp32-blink.ino • diagram.json libraries.txt Library Manager

```
1 #include <WiFi.h> // library for wifi
2 #include <PubSubClient.h> // library for MQTT
3 #include <LiquidCrystal_I2C.h>
4 #include <json.h>
5 LiquidCrystal_I2C lcd(0x27, 20, 4);
6
7 //----- credentials of IBM Accounts -----
8
9 #define ORG "ffw11q" // IBM organisation id
10 #define DEVICE_TYPE "Raspberry-pi" // Device type mentioned in ibm watson
11 #define DEVICE_ID "12345" // Device ID mentioned in ibm watson iot platform
12 #define TOKEN "12345678" // Token
13
14 //----- customise above values -----
15
16 char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; // server name
17 char publishTopic[] = "iot-2/evt/data/fmt/json"; // topic name
18 char topic[] = "iot-2/cmd/led/fmt/String"; // cmd representation
19 char authMethod[] = "use-token-auth"; // authentication method
20 char token[] = TOKEN;
21 char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID; //client id
22
23 //-----
24
25 WiFiClient wificlient; // creating client
26 PubSubClient client(server, 1883, wificlient);
27
28 #define ECHO_PIN 12
29 #define TRIG_PIN 13
30 float dist;
31 String data3;
32 bool SealBin = true;
33 void setup()
34 {
35   Serial.begin(115200);
```

Simulation

00:29.096 84%

Publish OK

Sending payload: {"Warning":169.97 }

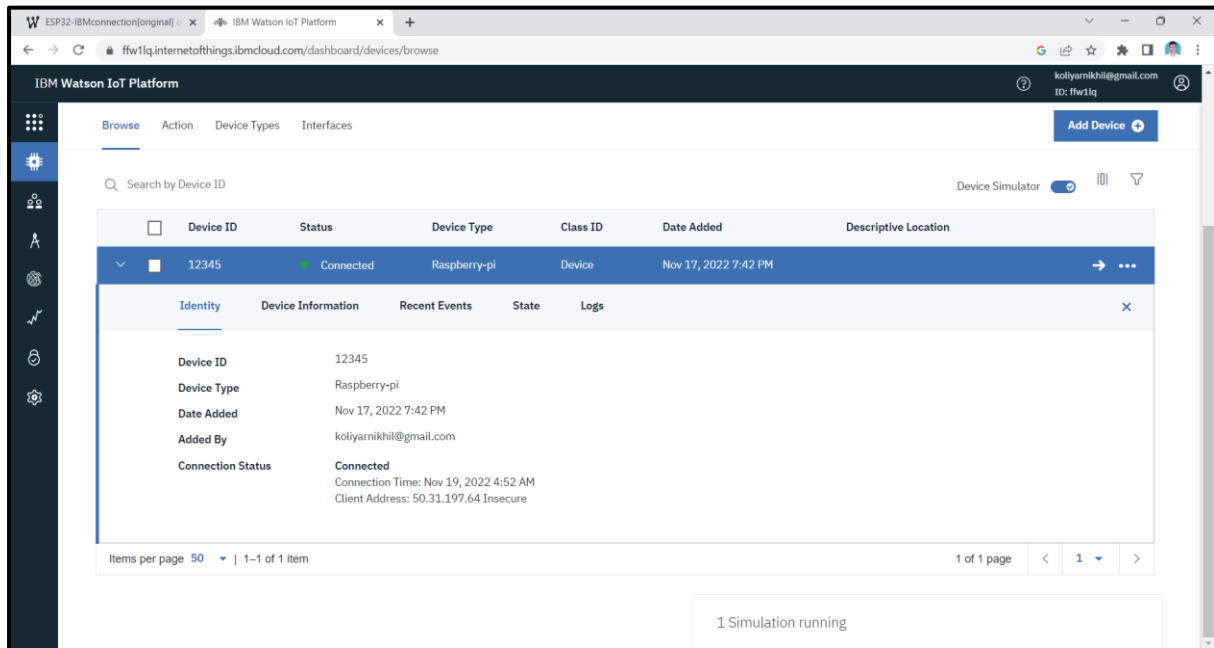
Publish OK

Sending payload: {"Warning":169.97 }

Publish OK

Inches 66.9 cm 170.0

## Connected with IBM Watson IoT Platform:



The screenshot shows the IBM Watson IoT Platform dashboard. The top navigation bar includes 'Browse', 'Action', 'Device Types', and 'Interfaces'. A search bar is present with the text 'Search by Device ID'. The main content area displays a table of devices. The first device is highlighted with a blue row and a dropdown menu open, showing details for Device ID 12345.

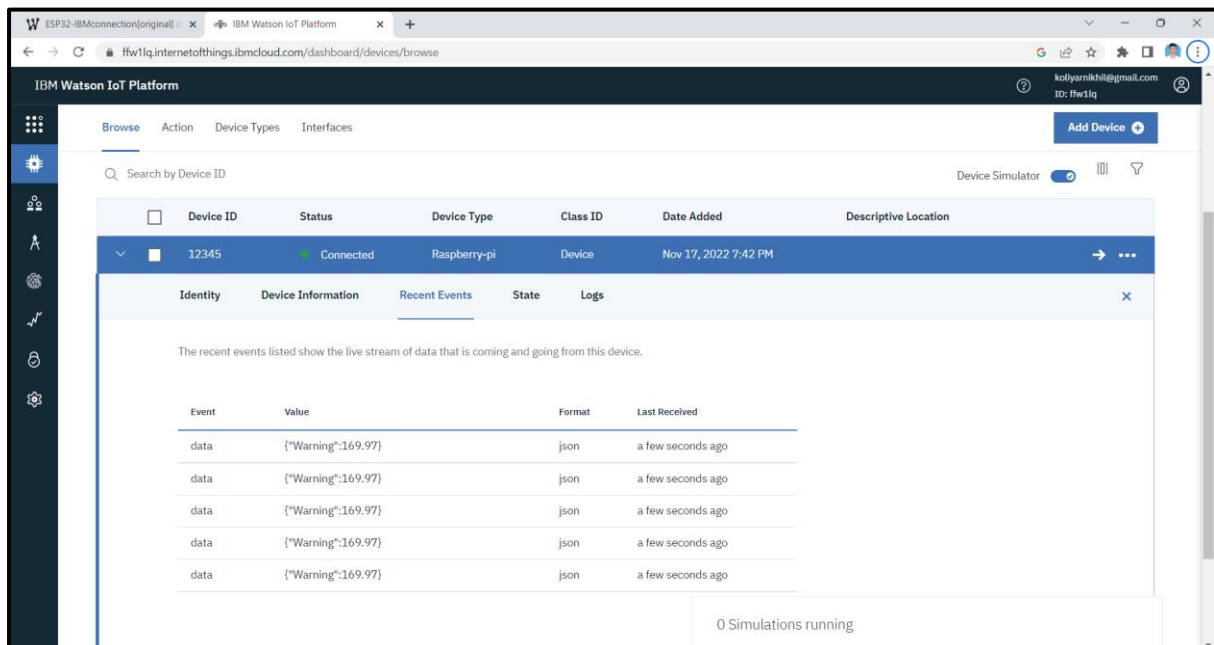
| Device ID | Status    | Device Type  | Class ID | Date Added           | Descriptive Location |
|-----------|-----------|--------------|----------|----------------------|----------------------|
| 12345     | Connected | Raspberry-pi | Device   | Nov 17, 2022 7:42 PM |                      |

Below the table, the 'Identity' tab is selected, showing the following information:

- Device ID: 12345
- Device Type: Raspberry-pi
- Date Added: Nov 17, 2022 7:42 PM
- Added By: kolyamikhil@gmail.com
- Connection Status: Connected
- Connection Time: Nov 19, 2022 4:52 AM
- Client Address: 50.31.197.64 Insecure

At the bottom right, a status bar indicates '1 Simulation running'.

## Sensor Data Received at IBM Watson IoT Platform:



The screenshot shows the IBM Watson IoT Platform dashboard, similar to the previous one, but with the 'Recent Events' tab selected for the device with ID 12345. The tab shows a live stream of data events.

The recent events listed show the live stream of data that is coming and going from this device.

| Event | Value              | Format | Last Received     |
|-------|--------------------|--------|-------------------|
| data  | {"Warning":169.97} | json   | a few seconds ago |
| data  | {"Warning":169.97} | json   | a few seconds ago |
| data  | {"Warning":169.97} | json   | a few seconds ago |
| data  | {"Warning":169.97} | json   | a few seconds ago |
| data  | {"Warning":169.97} | json   | a few seconds ago |

At the bottom right, a status bar indicates '0 Simulations running'.

## Wokwi Link:

<https://wokwi.com/projects/348707873452196436>