Team ID	PNT2022TMID05219
Project Name	Smart Waste Management System For Metropolitan Cities

Write code and connections in wokwi for ultrasonic sensor. Whenever the distance is less than 100 cm, send "alert" to IBM cloud and display in device recent events.

# WOKWI LINK: https://wokwi.com/projects/347136221699375700

### CODE:

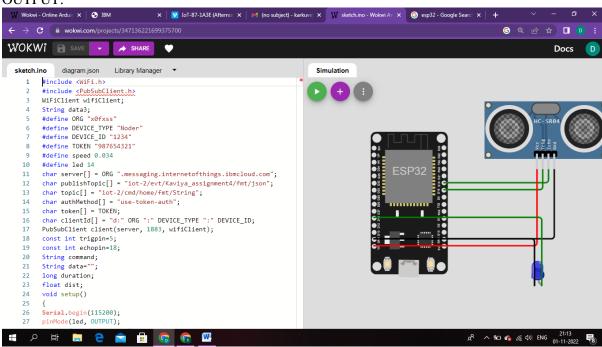
#include <WiFi.h> #include < PubSubClient.h> WiFiClient wifiClient; String data3; #define ORG "x0fxss" #define DEVICE\_TYPE "Noder" #define DEVICE\_ID "1234" #define TOKEN "987654321" #define speed 0.034 #define led 14 char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; char publishTopic[] = "iot-2/evt/Kaviya\_assignment4/fmt/json"; char topic[] = "iot-2/cmd/home/fmt/String"; char authMethod[] = "use-token-auth"; char token[] = TOKEN; char clientId[] = "d:" ORG ":" DEVICE\_TYPE ":" DEVICE\_ID; PubSubClient client(server, 1883, wifiClient);

```
const int trigpin=5;
const int echopin=18;
String command;
String data="";
long duration;
float dist;
void setup()
Serial.begin(115200);
pinMode(led, OUTPUT);
pinMode(trigpin, OUTPUT);
pinMode(echopin, INPUT);
wifiConnect();
mqttConnect();
}
void loop() {
bool is Nearby = dist < 100;
digitalWrite(led, isNearby);
publishData();
delay(500);
if (!client.loop()) {
mqttConnect();
}
}
void wifiConnect() {
Serial.print("Connecting to "); Serial.print("Wifi");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL_CONNECTED) {
delay(500);
Serial.print(".");
```

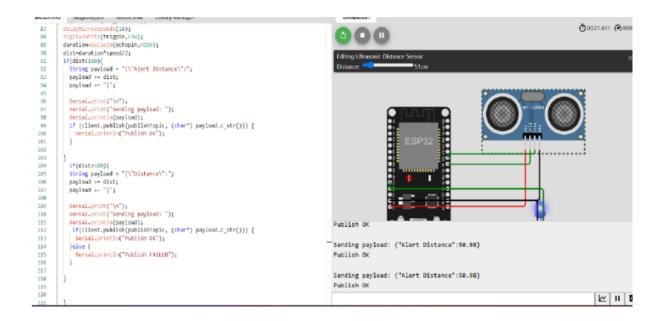
```
Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
void mqttConnect() {
if (!client.connected()) {
Serial.print("Reconnecting MQTT client to "); Serial.println(server);
while (!client.connect(clientId, authMethod, token)) {
Serial.print(".");
delay(500);
initManagedDevice();
Serial.println();
void initManagedDevice() {
if (client.subscribe(topic)) {
// Serial.println(client.subscribe(topic));
Serial.println("IBM subscribe to cmd OK");
} else {
Serial.println("subscribe to cmd FAILED");
void publishData()
digitalWrite(trigpin,LOW);
digitalWrite(trigpin,HIGH);
delayMicroseconds(10);
digitalWrite(trigpin,LOW);
duration=pulseIn(echopin,HIGH);
dist=duration*speed/2;
if(dist<100){
String payload = "{\"Alert Distance\":";
```

```
payload += dist;
payload += "}";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish OK");
if(dist>100){
String payload = "{\"Distance\":";
payload += dist;
payload += "}";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if(client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish OK");
Serial.println("Publish FAILED");
}
}
}
```

## **OUTPUT:**



# A) When distance greater than 100,



# B) When distance less than 100,

