

ASSIGNMENT – 4

Ultrasonic sensor simulation in Wokwi

Date	10 NOVEMBER 2022
Team ID	PNT2022TMID08766
Project Name	Real Time Water Quality Monitoring and Control System
Maximum Marks	4 Marks

QUESTION:

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events.

```
#include <WiFi.h>
#include <PubSubClient.h>
void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength);
//-----credentials of IBM Accounts-----
#define ORG "ksus4d"//IBM ORGANITION ID
#define DEVICE_TYPE "Sensordata"//Device type mentioned in ibm watson IOT
Platform
#define DEVICE_ID "0001"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "Raja prakash" //Token
String data3;
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char subscribetopic[] = "iot-2/cmd/test/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
WiFiClient wifiClient;
PubSubClient client(server, 1883, callback, wifiClient);
const int trigPin = 5;
const int echoPin = 18;
#define SOUND_SPEED 0.034
long duration;
float distance;
void setup() {
  Serial.begin(115200);
  pinMode(trigPin, OUTPUT);
```

```

pinMode(echoPin, INPUT);
wificonnect();
mqttconnect();
}
void loop()
{
digitalWrite(trigPin, LOW);
delayMicroseconds(2);
digitalWrite(trigPin, HIGH);
delayMicroseconds(10);
digitalWrite(trigPin, LOW);
duration = pulseIn(echoPin, HIGH);
distance = duration * SOUND_SPEED / 2;
Serial.print("Distance (cm): ");
Serial.println(distance);
if (distance < 100)
{
Serial.println("ALERT!!");
delay(1000);
PublishData(distance);
delay(1000);
if (!client.loop()) {
mqttconnect();
}
}
delay(1000);
}
void PublishData(float dist) {
mqttconnect();
String payload = "{\"Distance\": ";
payload += dist;
payload += ", \"ALERT!!\": \"\" \"Distance less than 100cms\"";
payload += "}";
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish ok");
} else {
Serial.println("Publish failed");
}
}
void mqttconnect() {
if (!client.connected()) {
Serial.print("Reconnecting client to ");
Serial.println(server);
while (!client.connect(clientId, authMethod, token)) {
Serial.print(".");
delay(500);
}
initManagedDevice();
Serial.println();
}
}

```

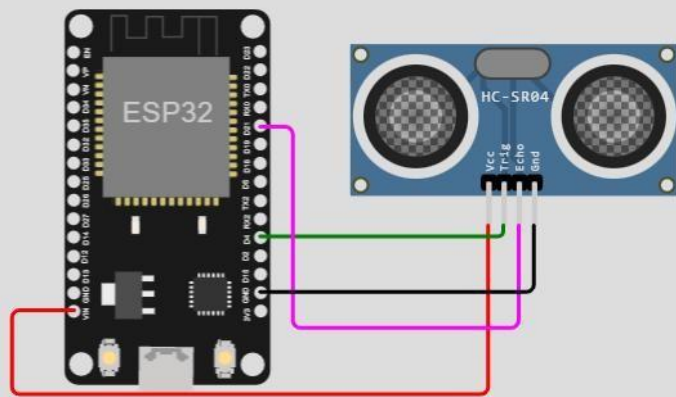
```

}
void wificonnect()
{
  Serial.println();
  Serial.print("Connecting to ");
  WiFi.begin("Wokwi-GUEST", "", 6);
  while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
  }
  Serial.println("");
  Serial.println("WiFi connected");
  Serial.println("IP address: ");
  Serial.println(WiFi.localIP());
}
void initManagedDevice() {
  if (client.subscribe(subscribetopic)) {
    Serial.println((subscribetopic));
    Serial.println("subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
}
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{
  Serial.print("callback invoked for topic: ");
  Serial.println(subscribetopic);
  for (int i = 0; i < payloadLength; i++) {
    //Serial.print((char)payload[i]);
    data3 += (char)payload[i];
  }
  Serial.println("data: " + data3);
  data3 = "";
}

```



```
{
  "version": 1,
  "author": "RAJA PRAKASH R",
  "editor": "wokwi",
  "parts": [
    { "type": "wokwi-esp32-devkit-v1", "id": "esp", "top": -56, "left": -120,
      "attrs": { } },
    { "type": "wokwi-hc-sr04", "id": "ultrasonic1", "top": -36.04, "left": 27.5,
      "attrs": { } }
  ],
  "connections": [
    [ "esp:TX0", "$serialMonitor:RX", "", [ ] ],
    [ "esp:RX0", "$serialMonitor:TX", "", [ ] ],
    [ "ultrasonic1:VCC", "esp:VIN", "red", [ "v87.91", "h-246.45", "v-36" ] ],
    [ "ultrasonic1:TRIG", "esp:D4", "green", [ "v0" ] ],
    [ "ultrasonic1:ECHO", "esp:D21", "magenta", [ "v53.24", "h-116.89", "v-88.67" ] ],
    [ "ultrasonic1:GND", "esp:GND.1", "black", [ "v0" ] ]
  ]
}
```

```
Measured distance: 177.24  
Measured distance: 177.16  
Measured distance: 177.26  
Measured distance: 177.16  
Measured distance: 177.24  
Measured distance: 177.16  
Measured distance: 177.26
```