ASSIGNMENT-4

DISTANCE DETECTION USING ULTRASONIC SENSOR

Assignment Date	29.10. 2022
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Maximum Marks	2 Marks

Question-1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

WOWKI LINK:

https://wokwi.com/projects/346856352591643219

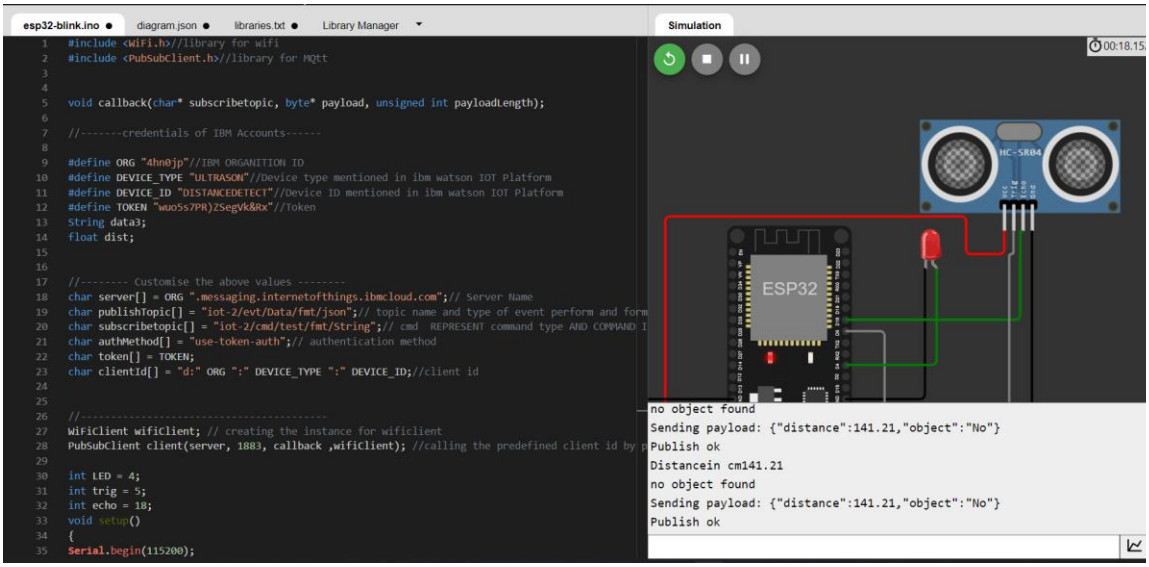
CODE:

```
#include <WiFi.h>
#include <PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "co65hn"
#define DEVICE_TYPE "ManiMD"
#define DEVICE_ID "manimd07"
#define TOKEN "0708012359"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/manimd/fmt/json";
char topic[] = "iot-2/cmd/led/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);



const int trigpin=5;
const int echopin=18;
String command;
String data="";

long duration;
float dist;
void setup()
{
  Serial.begin(115200);
  pinMode(led, OUTPUT);
  pinMode(trigpin, OUTPUT);
```

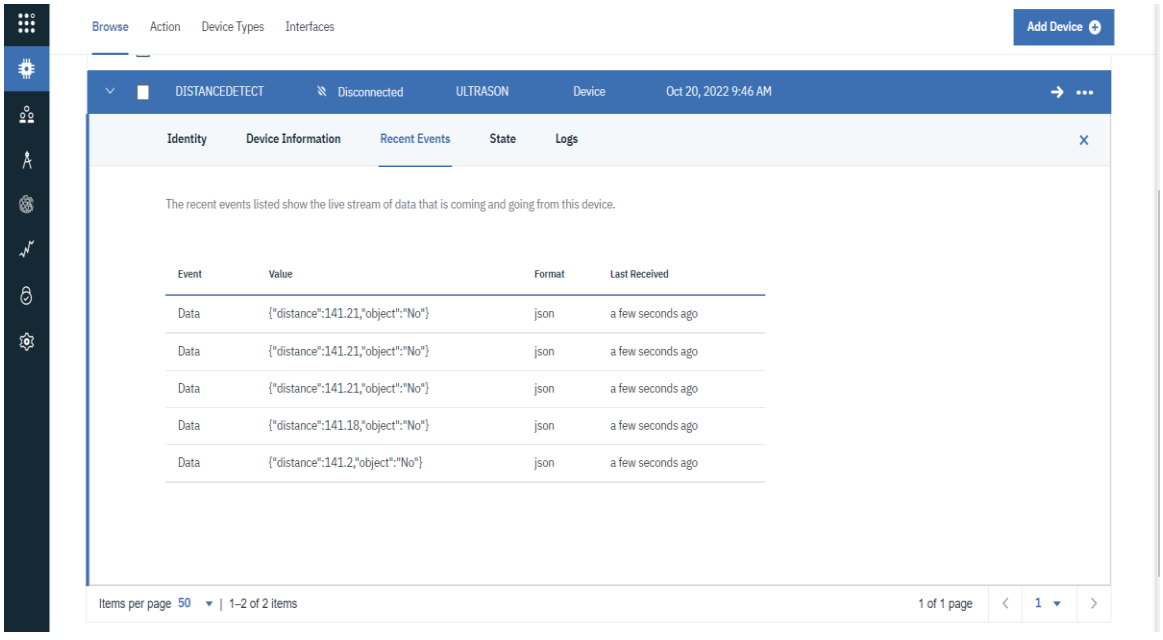
```
  pinMode(echopin, INPUT);
  wifiConnect();
  mqttConnect();
}

void loop() {
  bool isNearby = dist < 100;
  digitalWrite(led, isNearby);

  publishData();
  delay(500);

  if (!client.loop()) {
    mqttConnect();
  }
}

void wifiConnect() {
  Serial.print("Connecting to "); Serial.print("Wifi");
  WiFi.begin("Wokwi-GUEST", "", 6);
  while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
  }
      Serial.print("WiFi      connected,      IP      address:      ");
Serial.println(WiFi.localIP());
}

void mqttConnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting MQTT client to "); Serial.println(server);
    while (!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);
    }
    initManagedDevice();
    Serial.println();
  }
}

void initManagedDevice() {
  if (client.subscribe(topic)) {
    // Serial.println(client.subscribe(topic));
    Serial.println("IBM subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
}
```

```
void publishData()
{
  digitalWrite(trigpin,LOW);
  digitalWrite(trigpin,HIGH);
  delayMicroseconds(10);
  digitalWrite(trigpin,LOW);
  duration=pulseIn(echopin,HIGH);
  dist=duration*speed/2;
  if(dist<100){
    String payload = "{\"Alert Distance\":";
    payload += dist;
    payload += "}";

    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);
    if (client.publish(publishTopic, (char*) payload.c_str())) {
      Serial.println("Publish OK");
    }

  }
    if(dist>100){
    String payload = "{\"Distance\":";
    payload += dist;
    payload += "}";
    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);
     if(client.publish(publishTopic, (char*) payload.c_str())) {
      Serial.println("Publish OK");
    }else {
      Serial.println("Publish FAILED");
    }

  }
    }
```

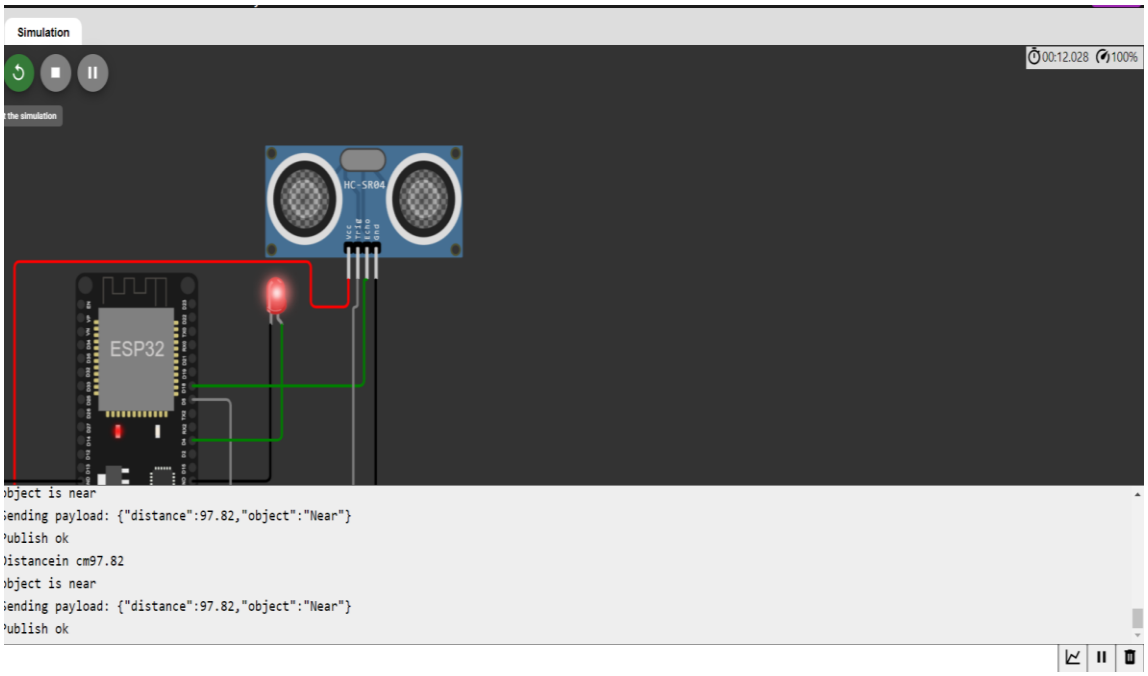
OUTPUT:



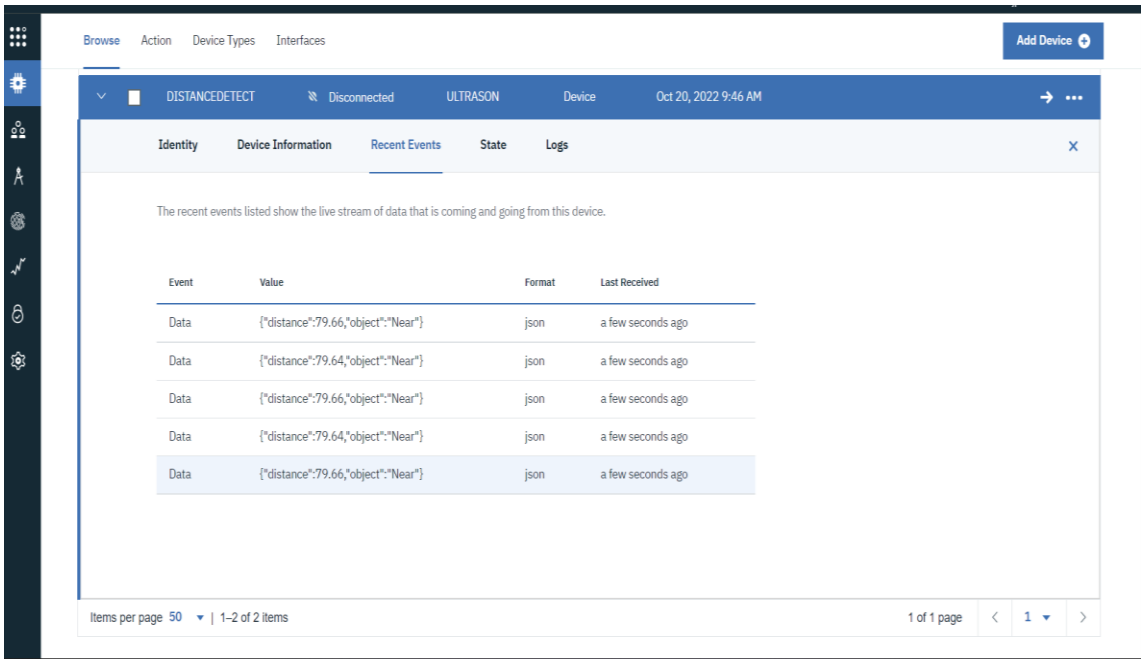
DATA SEND TO THE IBM CLOUD DEVICE WHEN THE OBJECT IS FAR



when object is near to the ultrasonic sensor



Data sent to the IBM Cloud Device when the object is near



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