# Assignment - 4 WOKWI CONNECTION

Assignment Date	8 November 2022
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Maximum Marks	2 Marks

# **QUESTION:**

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events.

# CODE:

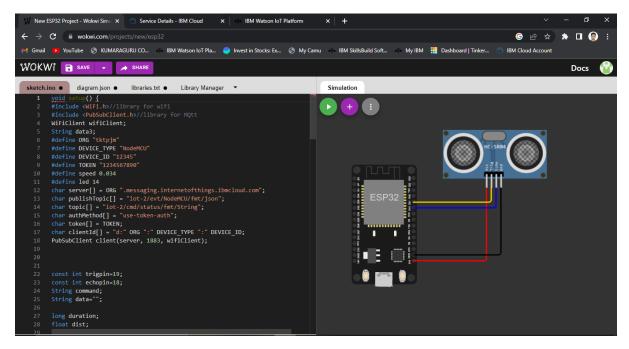
#include <wifi.h>//library for wifi</wifi.h>
#include <pubsubclient.h>//library for MQtt</pubsubclient.h>
WiFiClient wifiClient;
String data3;
#define ORG "tktpjm"
#define DEVICE_TYPE ''NodeMCU''
#define DEVICE_ID "12345"
#define TOKEN ''1234567890''
#define speed 0.034
#define led 14
$char\ server[] = ORG\ ".messaging.internet of things.ibmcloud.com";$
<pre>char publishTopic[] = "iot-2/evt/NodeMCU/fmt/json";</pre>
<pre>char topic[] = "iot-2/cmd/status/fmt/String";</pre>
<pre>char authMethod[] = "use-token-auth";</pre>
<pre>char token[] = TOKEN;</pre>
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
const int trigpin=19;
const int echopin=18;
String command;
String data="";
long duration;
float dist;

```
{
Serial.begin(115200);
 pinMode(led, OUTPUT);
 pinMode(trigpin, OUTPUT);
 pinMode(echopin, INPUT);
 wifiConnect();
 mqttConnect();
}
void loop() {
bool is Nearby = dist < 100;
digitalWrite(led, isNearby);
 publishData();
delay(500);
if (!client.loop()) {
  mqttConnect();
}
void wifiConnect() {
Serial.print("Connecting to "); Serial.print("Wifi");
 WiFi.begin("Wokwi-GUEST", "", 6);
 while (WiFi.status() != WL_CONNECTED) {
  delay(500);
  Serial.print(".");
Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}
void mqttConnect() {
if \ (!client.connected()) \ \{\\
  Serial.print("Reconnecting MQTT client to "); Serial.println(server);
  while \ (!client.connect(clientId, authMethod, token)) \ \{
   Serial.print(".");
   delay(500);
  init Managed Device ();\\
  Serial.println();
```

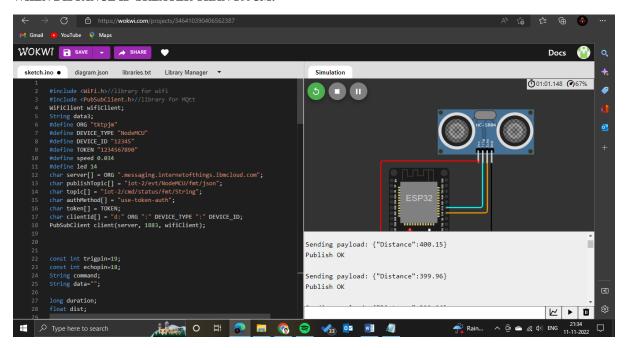
```
}
}
void\ initManagedDevice()\ \{
 if (client.subscribe(topic)) {
  // Serial.println(client.subscribe(topic));
  Serial.println("IBM subscribe to cmd OK");
 } else {
  Serial.println("subscribe to cmd FAILED");
 }
}
void publishData()
{
 digitalWrite(trigpin,LOW);
 {\bf digital Write (trigpin, HIGH);}
 delayMicroseconds(10);
 digitalWrite(trigpin,LOW);
 duration=pulseIn(echopin,HIGH);
 dist=duration*speed/2;
 if(dist{<}100)\{
  String payload = "{\"Alert Distance\":";
  payload += dist;
  payload += "}";
  Serial.print("\n");
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if \ (client.publish(publishTopic, (char*) \ payload.c\_str())) \ \{\\
   Serial.println("Publish OK");
  }
 }
  if(dist>100){}
  String payload = "{\"Distance\":";
  payload += dist;
  payload += "}";
  Serial.print("\n");
  Serial.print("Sending payload: ");
  Serial.println(payload);
```

```
if(client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish OK");
}else {
    Serial.println("Publish FAILED");
}
```

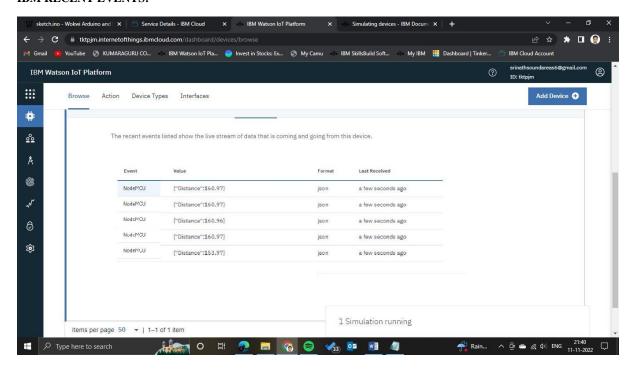
#### **OUTPUT:**



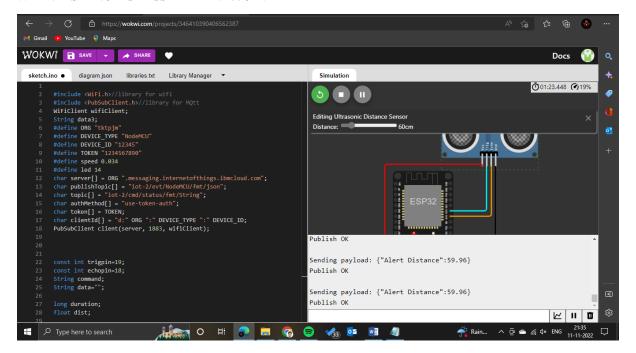
### WHEN DISTANCE IS GREATER THAN 100CM:



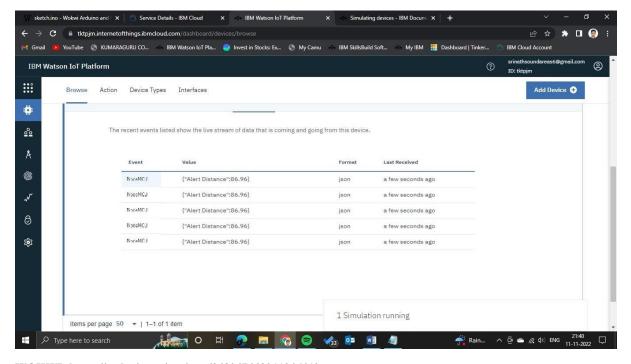
#### **IBM RECENT EVENTS:**



#### WHEN DISTANCE IS LESSER THAN 100CM:



## **IBM RECENT EVENTS:**



WOKWI: https://wokwi.com/projects/348047443911246419