

## Delivery of Sprint-2

### Code for Data Transfer from Sensors

```
#include <WiFi.h>                                // library for wifi
#include <PubSubClient.h>                        // library for MQTT
#include <LiquidCrystal_I2C.h>
LiquidCrystal_I2C lcd(0x27, 20, 4);

// .....credentials of IBM Accounts .....-

#define ORG "9gbe4w"                            // IBM organisation id
#define DEVICE_TYPE "SWMSMC"                   // Device type mentioned in ibm watson iot platform
#define DEVICE_ID "ibmproject"                 // Device ID mentioned in ibm watson iot platform
#define TOKEN "sUNA41tG6-Pq)0rk5X"            // Token

// .....customise above values ..... -

char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; // server name char
publishTopic[] = "iot-2/evt/data/fmt/json";
char topic[] = "iot-2/cmd/led/fmt/String"; // cmd Represent type and command is test format of strings
char authMethod[] = "use-token-auth"; // authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID; //Client id

// .....

WiFiClient wifiClient;                          // creating instance for wificlient
PubSubClient client(server, 1883, wifiClient);

#define ECHO_PIN 12
#define TRIG_PIN 13
float dist;

void setup()
{
  Serial.begin(115200);
  pinMode(LED_BUILTIN, OUTPUT);
  pinMode(TRIG_PIN, OUTPUT);
  pinMode(ECHO_PIN, INPUT);
  //pir pin
  pinMode(4, INPUT);

  //ledpins
  pinMode(23, OUTPUT);
  pinMode(2, OUTPUT);
  pinMode(4, OUTPUT);
  pinMode(15, OUTPUT);

  lcd.init();
  lcd.backlight();
  lcd.setCursor(1, 0);
  lcd.print("");
```

```

    wifiConnect();
    mqttConnect();
}

float readcmCM()
{
    digitalWrite(TRIG_PIN, LOW);
    delayMicroseconds(2);
    digitalWrite(TRIG_PIN, HIGH);
    delayMicroseconds(10);
    digitalWrite(TRIG_PIN, LOW); int
    duration = pulseIn(ECHO_PIN, HIGH);
    return duration * 0.034 / 2;
}

void loop()
{

    lcd.clear();

    publishData(); delay(500);
    if (!client.loop())
    {
        mqttConnect(); // function call to connect to IBM
    }
}

/* _____-retrieving to cloud_____ */

void wifiConnect()
{
    Serial.print("Connecting to ");
    Serial.print("Wifi");
    WiFi.begin("Wokwi-GUEST", "", 6);
    while (WiFi.status() != WL_CONNECTED)
    {
        delay(500);
        Serial.print(".");
    }
    Serial.print("WiFi connected, IP address: ");
    Serial.println(WiFi.localIP());
}
void mqttConnect()
{
    if (!client.connected())
    {
        Serial.print("Reconnecting MQTT client to ");
        Serial.println(server); while
        (!client.connect(clientId, authMethod, token))
        {
            Serial.print("."); delay(500);
        }
        initManagedDevice();
        Serial.println();
    }
}
void initManagedDevice()
{
    if (client.subscribe(topic))
    {
        Serial.println("IBM subscribe to cmd OK");
    }
}

```

```

    }
    else
    {
        Serial.println("subscribe to cmd FAILED");
    }
}
void publishData()
{
    float cm = readcmCM();

    if(digitalRead(34))                                //PIR motion detection
    {
        Serial.println("Motion
        Detected");    Serial.println("Lid
        Opened"); digitalWrite(15, HIGH);
    }
    else
    {
        digitalWrite(15, LOW);
    }

    if(digitalRead(34)== true)
    {
        if(cm <= 100)                                //Bin level detection
        {
            digitalWrite(2, HIGH);
            Serial.println("High Alert!!!,Trash bin is about to be full");
            Serial.println("Lid Closed"); lcd.print("Full! Don't use");
            delay(2000); lcd.clear(); digitalWrite(4, LOW);
            digitalWrite(23, LOW);
        }
        else if(cm > 150 && cm < 250)
        {
            digitalWrite(4, HIGH);
            Serial.println("Warning!!,Trash is about to cross 50% of bin level"); digitalWrite(2,
            LOW);
            digitalWrite(23, LOW);
        }
        else if(cm > 250 && cm <=400)
        {
            digitalWrite(23, HIGH);
            Serial.println("Bin is
            available");
            digitalWrite(2,LOW);
            digitalWrite(4, LOW);
        }
        delay(10000); Serial.println("Lid
        Closed");
    }
    else
    {
        Serial.println("No motion detected");
    }

    if(cm <= 100)
    {
        digitalWrite(21,HIGH);
        String payload = "{\"High Alert!!\":\":";
    }

```

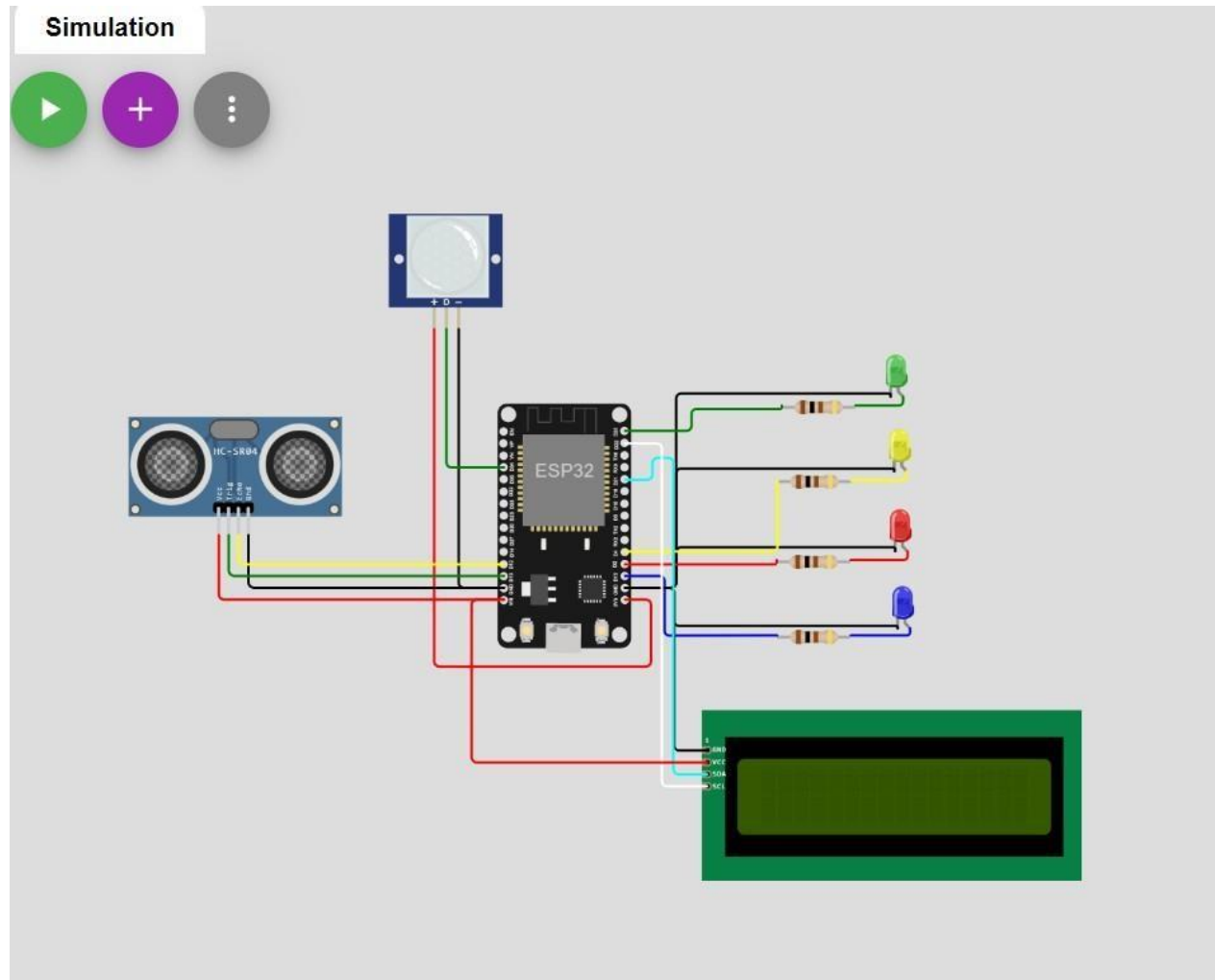
```

payload += cm; payload
+= "left\ " };
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str()))    // if data is uploaded to cloud successfully,prints publish ok or prints publish failed
{
Serial.println("Publish OK");
}
}
if(cm <= 250)
{
digitalWrite(22,HIGH);
String payload = "{\nWarning!!\":\":"";
payload += dist; payload += "left\ " };
Serial.print("\n");
Serial.print("Sending distance: "); Serial.println(cm);
if(client.publish(publishTopic, (char*) payload.c_str()))
{
Serial.println("Publish OK");
}
else
{
Serial.println("Publish FAILED");
}
}

float inches = (cm / 2.54);    //print on LCD lcd.setCursor(0,0); lcd.print("Inches");
lcd.setCursor(4,0); lcd.setCursor(12,0); lcd.print("cm"); lcd.setCursor(1,1); lcd.print(inches, 1);
lcd.setCursor(11,1); lcd.print(cm, 1); lcd.setCursor(14,1); delay(1000); lcd.clear();
}

```

### Connection Diagram



Link : <https://wokwi.com/projects/347376419979919956>