## **ASSIGNMENT 4**

## **BUZZER FOR ULTRASONIC SENSOR**

## **SOURCE CODE:**

```
int t=2;
int e=3;
void setup()
 Serial.begin(9600);
 pinMode(t,OUTPUT
 );
 pinMode(e,INPUT);
 pinMode(12,OUTPU
 T);
}
void loop()
 //ultrasonic sensor
 digitalWrite(t,LOW);
 digitalWrite(t,HIGH);
 delayMicroseconds(1
 0);
 digitalWrite(t,LOW);
```

```
float
dur=pulseIn(e,HIGH);
float dis=(dur*0.0343)/2;
Serial.print("Distance is:
");Serial.println(dis);
//LED ON
if(dis > = 100)
 digitalWrite(8,HIG
 H);
 digitalWrite(7,HIG
 H);
//Buzzer For ultrasonic
Sensorif(dis>=100)
for(int i=0; i<=30000; i=i+10)
tone(12,i);
delay(1000
);
noTone(12)
delay(1000
);
```

