



```
// C++ code
//
void setup()
{
Serial.begin(9600);
pinMode(13,OUTPUT);
pinMode(2,INPUT);
}
void loop()
{
int motion=digitalRead(2);
double data=analogRead(A2);
double n=data/1024;
Serial.print("Converted Analog data:");
Serial.println(n);
double volt=n*5;
Serial.print("Voltage data:");
Serial.println(volt);
double off=volt-0.5;
Serial.print("offset data:");
Serial.println(off);
double temp=off*100;
Serial.print("temp data:");
Serial.println(temp);
if(motion==1 && temp<60)
 tone(13,1020);
else if(motion==0 && temp>60)
```

```
tone(13,1500);
else if(motion==1 && temp>60)
tone(13,1700);
else if(motion==0 && temp<60)
noTone(13);
}
```