## IBM ASSIGNMENT 1

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## **SOURCE CODE:**

```
int t=2;
int e=3;
void setup()
  Serial.begin(9600);
  pinMode(t,OUTPUT);
  pinMode(e,INPUT);
  pinMode(12,OUTPUT);
void loop()
  //ultrasonic sensor
  digitalWrite(t,LOW);
  digitalWrite(t,HIGH);
  delayMicroseconds(10);
  digitalWrite(t,LOW);
  float dur=pulseIn(e,HIGH);
  float dis=(dur*0.0343)/2;
  Serial.print("Distance is: ");
  Serial.println(dis);
    //LED ON
  if(dis>=100)
    digitalWrite(8,HIGH);
    digitalWrite(7,HIGH);
  }
  //Buzzer For ultrasonic Sensor
```

```
if(dis>=100)
for(int i=0; i<=30000; i=i+10)
tone(12,i);
delay(1000);
noTone(12);
delay(1000);
}
}
  //Temperate Sensor
double a= analogRead(A0);
double t=(((a/1024)*5)-0.5)*100;
Serial.print("Temp Value: ");
Serial.println(t);
delay(1000);
//LED ON
if(t>=100)
  digitalWrite(8,HIGH);
  digitalWrite(7,HIGH);
}
//Buzzer for Temperature Sensor
if(t>=100)
{
for(int i=0; i<=30000; i=i+10)
tone(12,i);
delay(1000);
noTone(12);
delay(1000);
}
}
//LED OFF
if(t<100)
  digitalWrite(8,LOW);
  digitalWrite(7,LOW);
}
```

## **CIRCUIT DIAGRAM:**

