## Assignment -4

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## QUESTION:

Write code and connections in wokwi for ultrasonic sensor. Whenever the distance is less than 100 cms send "alert" to IBM cloud and display in the device recent events.

## PROGRAM:

```
#include <WiFi.h>//library for wifi
#include <PubSubClient.h>//library for MQtt
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);
//----credentials of IBM Accounts-----
#define ORG "zlkemz"//IBM ORGANITION ID
#define DEVICE_TYPE "Nagarajan"//Device type mentioned in ibm watson IOT
Platform
#define DEVICE_ID "12345678"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "1234567890 " //Token String data3; float dist;
//----- Customise the above values ------
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name
char publishTopic[] = "iot-2/evt/event 1/fmt/json";// topic name and type of
event perform and format in which data to be send
char subscribetopic[] = "iot-2/cmd/test/fmt/String";// cmd REPRESENT command
type AND COMMAND IS TEST OF FORMAT STRING char authMethod[] = "use-token-
auth";// authentication method char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;//client id
WiFiClient wifiClient; // creating the instance for wificlient
PubSubClient client(server, 1883, callback , wifiClient); //calling the predefined
client id by passing parameter like server id, portand wificredential
int LED = 14;
int trig = 13;
int echo = 18;
void setup()
{
Serial.begin(115200);
pinMode(trig,OUTPUT);
pinMode(echo,INPUT);
pinMode(LED, OUTPUT);
```

```
delay(10); wificonnect();
mqttconnect();
} void loop()// Recursive
Function
{ digitalWrite(trig,LOW);
digitalWrite(trig,HIGH);
delayMicroseconds(10);
digitalWrite(trig,LOW);
                      float
dur = pulseIn(echo,HIGH);
                         float
dist = (dur * 0.0343)/2;
 Serial.print ("Distancein cm");
 Serial.println(dist);
 PublishData(dist);
delay(1000);
(!client.loop()) {
mqttconnect();
 }
}
/*....retrieving to
Cloud.....*/
void PublishData(float dist)
{
 mqttconnect();//function call for connecting to ibm
    creating the String in in form JSon to update the data to ibm cloud
 String object;
if (dist <100)
 {
   digitalWrite(LED,HIGH);
Serial.println("object is near");
object = "Near";
 }
else
   digitalWrite(LED,LOW);
   Serial.println("no object found");
object = "No";
 }
 String payload = "{\"distance\":";
payload += dist; payload += ","
"\"object\":\""; payload += object;
payload += "\"}";
 Serial.print("Sending payload: ");
 Serial.println(payload);
```

```
if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish ok");// if it sucessfully upload data on the cloud
then it will print publish ok in Serial monitor or else it will print publish
failed
  } else {
    Serial.println("Publish failed");
   } void mqttconnect() {
if (!client.connected()) {
                                                                 ");
    Serial.print("Reconnecting
                                       client
                                                      to
Serial.println(server);
    while (!!!client.connect(clientId, authMethod, token)) {
Serial.print("."); delay(500);
    }
    initManagedDevice();
    Serial.println();
  } } void wificonnect() //function defination for
wificonnect
 Serial.println();
 Serial.print("Connecting to ");
 WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish
the connection
 while (WiFi.status() != WL_CONNECTED) {
delay(500);
    Serial.print(".");
  }
 Serial.println("");
 Serial.println("WiFi connected");
 Serial.println("IP address: ");
 Serial.println(WiFi.localIP());
} void
initManagedDevice() {
 if (client.subscribe(subscribetopic)) {
Serial.println((subscribetopic));
Serial.println("subscribe to cmd
OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
 }
} void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength)
{
 Serial.print("callback
                                                                 ");
                              invoked
                                           for
                                                     topic:
Serial.println(subscribetopic);
  for (int i = 0; i < payloadLength; i++) {</pre>
//Serial.print((char)payload[i]);
+= (char)payload[i];
 }
 // Serial.println("data: "+ data3);
// if(data3=="Near")
```

```
// {
// Serial.println(data3);
// digitalWrite(LED,HIGH);

// }

// else
// Serial.println(data3);
// digitalWrite(LED,LOW);
// }
data3="";
}
```



