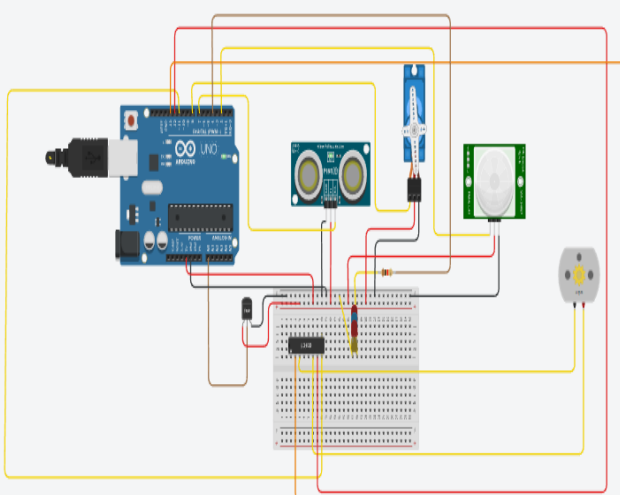


Simulator time: 00:00:09.007

Code Stop Simulation Send To

1 (Arduino Uno R3)



```
1 #include<Servo.h>
2 const int pingPin = 7;
3 int servoPin = 8;
4
5 Servo servol;
6
7 void setup() {
8   // initialize serial communication:
9   Serial.begin(9600);
10  servol.attach(servoPin);
11  pinMode(2,INPUT);
12  pinMode(4,OUTPUT);
13  pinMode(11,OUTPUT);
14  pinMode(12,OUTPUT);
15  pinMode(13,OUTPUT);
16  pinMode(A0,INPUT);
17  digitalWrite(2,LOW);
18  digitalWrite(11,HIGH);
19
20 }
21
22 void loop() {
23
24   long duration, inches, cm;
```

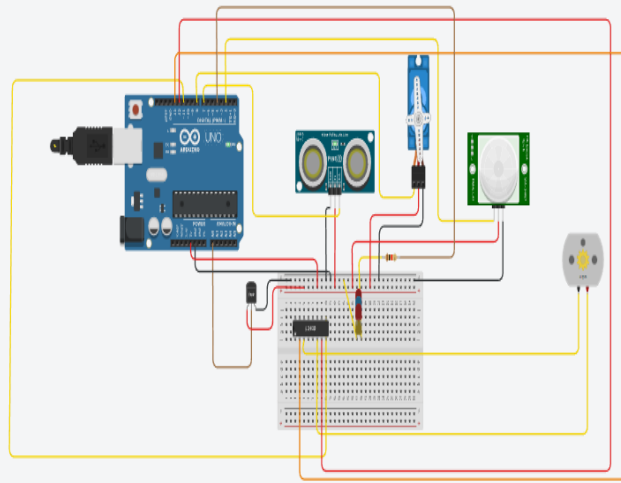


Simulator time: 00:00:10.600

Code Stop Simulation Send To



1 (Arduino Uno R3)



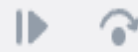
Serial Monitor

```
temperature
73.44
43in, 111cm
temperature
73.44
43in, 111cm
temperature
73.44
43in, 111cm
temperature
73.44
43in, 111cm
temperature
73.44
43in, 111cm
temperature
73.44
43in, 111cm
temperature
73.44
43in, 111cm
temperature
73.44
43in, 111cm
temperature
73.44
43in, 111cm
temperature
73.44
43in, 111cm
```

Send

Clear





1 (Arduino Uno R3) ▾

```
1 #include<Servo.h>
2 const int pingPin = 7;
3 int servoPin = 8;
4
5 Servo servo1;
6
7 void setup() {
8   // initialize serial communication:
9   Serial.begin(9600);
10  servo1.attach(servoPin);
11 }
```



Serial Monitor ▾

43in, 110cm
temperature
73.44
43in, 111cm
temperature
73.44
43in, 110cm
temperature
73.44
43in, 111cm
temperature
73.44
43in, 110cm

Send

Clear

