# **ASSIGNMENT - 4**

1.Write Code and connections in wokwi for ultrasonic sensor. whatever distance is less than 100 cms send "Alert" to ibm cloud and display in device recent events.

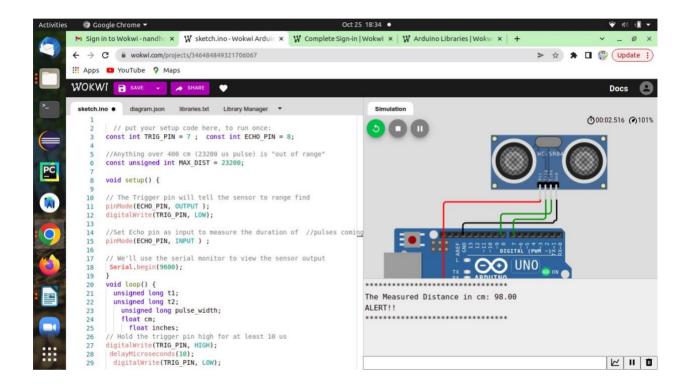
#### CODE:

```
// put your setup code here, to run
once: const int TRIG_PIN = 7; const
int ECHO_PIN = 8;
//Anything over 400 cm (23200 us pulse) is "out of range"
const unsigned int MAX_DIST = 23200;
void setup() {
// The Trigger pin will tell the sensor to range find
pinMode(ECHO_PIN, OUTPUT );
digitalWrite(TRIG_PIN, LOW);
//Set Echo pin as input to measure the duration of //pulses coming back from the distance
sensor pinMode(ECHO_PIN, INPUT);
// We'll use the serial monitor to view the sensor output
Serial.begin(9600);
}
void loop() {
 unsigned long t1;
 unsigned long t2;
  unsigned long pulse_width;
  float cm;
```

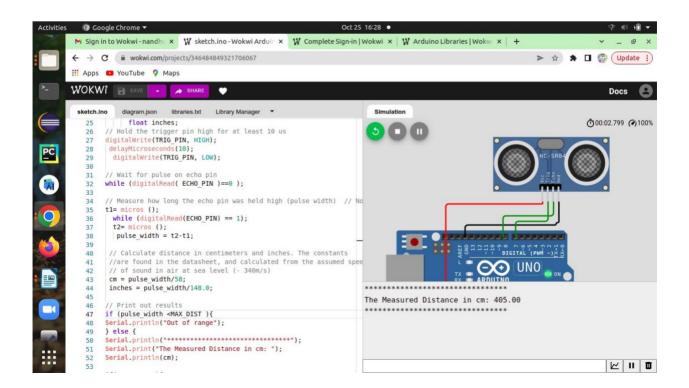
```
float inches:
// Hold the trigger pin high for at least 10 us
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
 digitalWrite(TRIG_PIN, LOW);
// Wait for pulse on echo pin
while (digitalRead( ECHO_PIN
)==0);
// Measure how long the echo pin was held high (pulse width) // Note: the micros()
counter will overflow after-70 min t1= micros ();
 while (digitalRead(ECHO_PIN) == 1);
 t2= micros ();
 pulse_width = t2-t1;
// Calculate distance in centimeters and inches. The constants
//are found in the datasheet, and calculated from the assumed speed
// of sound in air at sea level (- 340m/s)
cm = pulse_width/238;
inches = pulse_width/34;
if (pulse_width <MAX_DIST ){</pre>
Serial.println("Out of range");
} else {
Serial.println("****************************);
Serial.print("The Measured Distance in cm: ");
Serial.println(cm);
if(cm < 100){
Serial.println("ALERT!!");
}
Serial.print("*****************************);
```

```
}
//wait at least 1000ms before next measurement
delay(1000);
}
```

# If the distance is less than 100 cm, it Alerts.



### If the distance is more than 100 cm, it won't Alert



#### **CONNECTION:**

