

PNT2022TMID11025:

The screenshot shows a Visual Studio Code editor with a Python script named 'main.py' open. The script is a ROS2 node that publishes a 'localityInfo' message. The message is defined as a dictionary with the following fields:

- `school`: A dictionary containing `schoolName` (set to 'Chengdu, CN') and `activeTime` (set to '18:00-21:00').
- `transportMode`: A string set to 'Bicycle'.
- `mealSpeedLimit`: A float set to 10.

The script uses the 'rclpy' library and the 'std_msgs/msg/LocalityInfo' message type. The bottom status bar indicates the file is named 'main.py' and is located in the directory '/home/casper/documents/main.py'.