# **Assignment-4**

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Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events. Upload document with wokwi share link and images of IBM cloud.

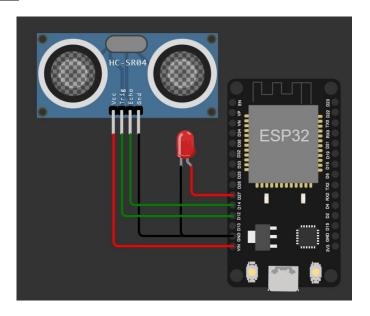
## CODE:

```
#include <WiFi.h>
#include <PubSubClient.h>
void callback(char* subscribetopic,byte* payload, unsigned int payloadLength);
#define ORG "k0ly3z"
#define DEVICE TYPE "ESPALPHA"
#define DEVICE ID "ESP251"
#define TOKEN "dR8tqDUTxABgzQ?Fim"
String data3;
char server[]= ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[]="iot-2/evt/distance/fmt/json";
char subscribeTopic[]="iot-2/cmd/test/fmt/String";
char authMethod[]="use-token-auth";
char token[]=TOKEN;
char clientID[]="d:"ORG":"DEVICE TYPE":"DEVICE ID;
WiFiClient wifiClient;
PubSubClient client(server,1883,callback,wifiClient);
#define ECHO PIN 14
#define TRIG PIN 12
#define led 27
void setup() {
  // put your setup code here, to run once:
 Serial.begin(115200);
 pinMode(led, OUTPUT);
 pinMode(TRIG_PIN, OUTPUT);
 pinMode(ECHO PIN, INPUT);
 wificonnect();
 mqttconnect();
float readDistanceCM() {
 digitalWrite(TRIG_PIN, LOW);
 delayMicroseconds(2);
 digitalWrite(TRIG PIN, HIGH);
 delayMicroseconds(10);
 digitalWrite(TRIG_PIN, LOW);
  int duration=random(1,200);
```

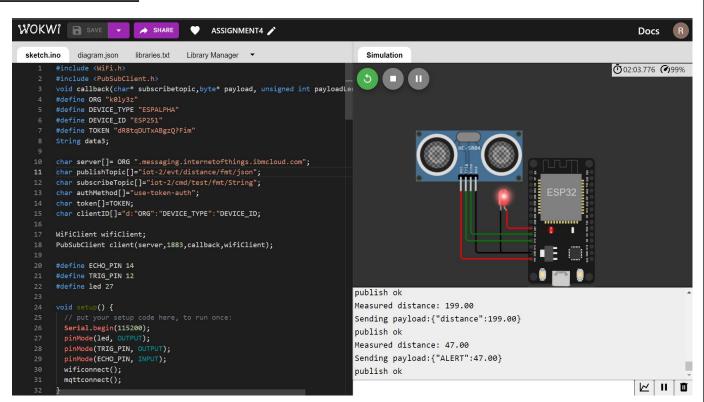
```
//Serial.println(duration);
  //duration = pulseIn(ECHO PIN, HIGH);
  return duration ;
  //Serial.println(duration);
void loop() {
 float distance = readDistanceCM();
  //Serial.println(distance);
  bool isNearby = distance < 100;</pre>
  digitalWrite(led, isNearby);
  Serial.print("Measured distance: ");
  Serial.println(distance);
  if(distance<100){</pre>
    PublishData2(distance);
  }else{
    PublishData1(distance);
  //PublishData(distance);
 delay(1000);
  if(!client.loop()){
    mqttconnect();
  //delay(2000);
void PublishData1(float dist){
 mqttconnect();
  String payload= "{\"distance\":";
  payload += dist;
  payload+="}";
  Serial.print("Sending payload:");
  Serial.println(payload);
  if(client.publish(publishTopic,(char*)payload.c str())){
    Serial.println("publish ok");
  } else{
    Serial.println("publish failed");
  }
void PublishData2(float dist){
  mqttconnect();
  String payload= "{\"ALERT\":";
  payload += dist;
  payload+="}";
  Serial.print("Sending payload:");
  Serial.println(payload);
  if(client.publish(publishTopic,(char*)payload.c_str())){
    Serial.println("publish ok");
  } else{
    Serial.println("publish failed");
  }
void mqttconnect(){
  if(!client.connected()){
    Serial.print("Reconnecting to ");
```

```
Serial.println(server);
    while(!!!client.connect(clientID, authMethod, token)){
      Serial.print(".");
      delay(500);
    initManagedDevice();
    Serial.println();
  }
void wificonnect(){
  Serial.println();
  Serial.print("Connecting to");
 WiFi.begin("Wokwi-GUEST","",6);
 while(WiFi.status()!=WL CONNECTED){
    delay(500);
    Serial.print(".");
  Serial.println("");
  Serial.println("WIFI CONNECTED");
  Serial.println("IP address:");
  Serial.println(WiFi.localIP());
void initManagedDevice(){
  if(client.subscribe(subscribeTopic)){
    Serial.println((subscribeTopic));
    Serial.println("subscribe to cmd ok");
  }else{
    Serial.println("subscribe to cmd failed");
  }
void callback(char* subscribeTopic, byte* payload, unsigned int payloadLength){
  Serial.print("callback invoked for topic:");
  Serial.println(subscribeTopic);
  for(int i=0; i<payloadLength; i++){</pre>
    data3 += (char)payload[i];
  Serial.println("data:"+ data3);
  if(data3=="lighton"){
    Serial.println(data3);
    digitalWrite(led,HIGH);
  }else{
    Serial.println(data3);
    digitalWrite(led,LOW);
  data3="";
```

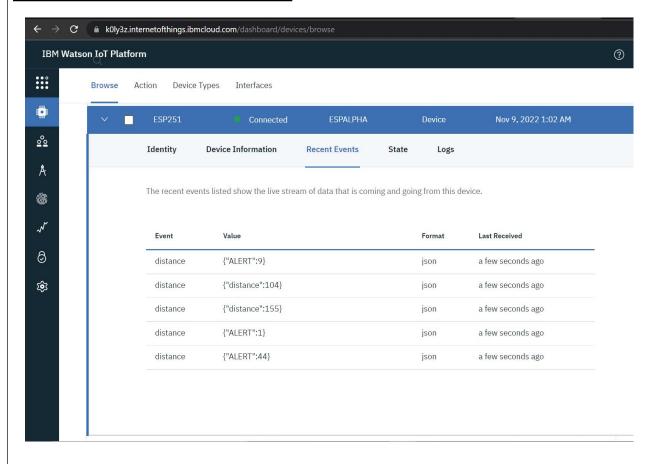
## **CIRCUIT CONNECTION:**



#### **WOKWI OUTPUT:**



### **LIVE DATA FEED SEEN ON IBM IoT:**



## **INFERENCES:**

- The schematics are designed in wokwi website and the code is written to interface the ESP32 connected ultrasonic sensor to IBM IoT platform.
- ➤ The simulated distance readings measured using ultrasonic sensor is displayed on the output terminal.
- The sensor readings are sent to and displayed in the IBM IoT platform.