ASSIGNMENT-4

DISTANCE DETECTION USING ULTRASONIC SENSOR

Date	24 October 2022
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Mark	2Marks

Question1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events

WOKWI LINK:

https://wokwi.com/projects/305566932847821378

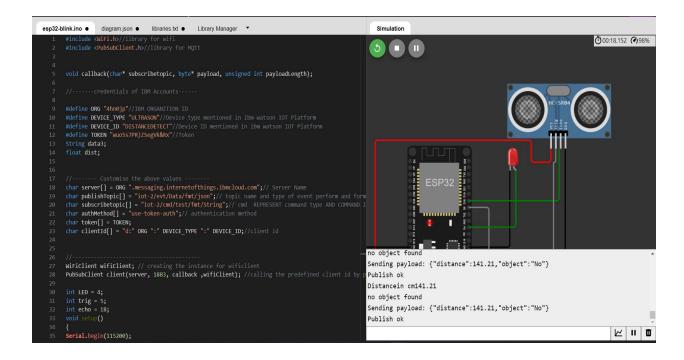
CODE:

```
esp32-blink.ino
                  diagram.json •
                                   libraries.txt •
                                                  Library Manager
       pinMode(trig,OUTPUT);
       pinMode(echo,INPUT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void loop()// Recursive Function
        digitalWrite(trig,LOW);
         digitalWrite(trig,HIGH);
         delayMicroseconds(10);
         digitalWrite(trig,LOW);
         float dur = pulseIn(echo,HIGH);
         float dist = (dur * 0.0343)/2;
         Serial.print ("Distancein cm");
         Serial.println(dist);
         PublishData(dist);
         delay(1000);
         if (!client.loop()) {
           mqttconnect();
       void PublishData(float dist) {
         mqttconnect();//function call for connecting to ibm
```

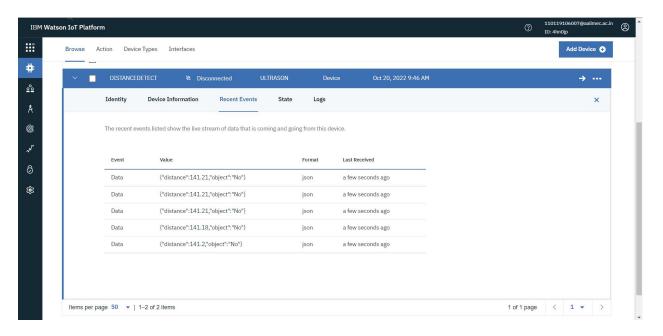
```
| Serial_println("Publish failed"); | Serial_println("Reconnect(clientid, autiMethod, token)) {
| Serial_println("Facility (Connecting client to "); | Serial_println("Connect(clientid, autiMethod, token)) {
| Serial_println("Connect(clientid, autiMethod, token) {
| Serial_println("Connect(clientid, autiMetho
```

```
esp32-blink.ino
                   diagram.json •
                                   libraries.txt ●
                                                  Library Manager
         WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
         while (WiFi.status() != WL_CONNECTED) {
           delay(500);
           Serial.print(".");
         Serial.println("WiFi connected");
         Serial.println("IP address: ");
         Serial.println(WiFi.localIP());
       void initManagedDevice() {
         if (client.subscribe(subscribetopic)) {
           Serial.println((subscribetopic));
           Serial.println("subscribe to cmd OK");
           Serial.println("subscribe to cmd FAILED");
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
         Serial.print("callback invoked for topic: ");
 148
         Serial.println(subscribetopic);
         for (int i = 0; i < payloadLength; i++) {</pre>
           data3 += (char)payload[i];
```

OUTPUT:

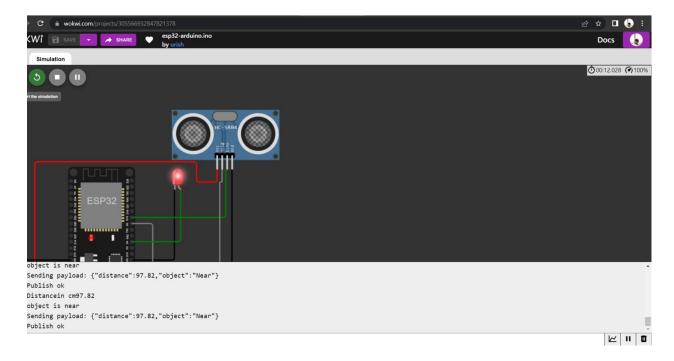


Data send to the IBM cloud device when the object is far



when object is near to the ultrasonic sensor

when object is near to the ultrasonic sensor



Data sent to the IBM Cloud Device when the object is near

