



```
//Home automation
//buzzer
void setup()
{
  pinMode(12, OUTPUT); //for pir sensor o/p buzzer
  pinMode(8, OUTPUT); //for temp sensor o/p buzzer
  pinMode(4, INPUT); //feeding i/p to arduino from pir sensor
  Serial.begin(9600);
  pinMode(13, OUTPUT);
}

void loop()
{
  //pir sensor
  int p=digitalRead(4);
  delay(20);
  if(p)
```

```
{  
tone(12,800);//if motion detetcted the buzzer will rung  
    delay(500);  
    noTone(12);  
    delay(100);  
}  
//temp sensor  
double t=analogRead(A0);  
double e=((t/1024)*5)-0.5)*100;  
Serial.println(e);  
delay(200);  
if(e>25)  
{  
tone(8,9000);//if temperature greater than 50 deg the buzzer will rung  
    delay(500);  
    noTone(8);  
    delay(100);  
}  
}
```