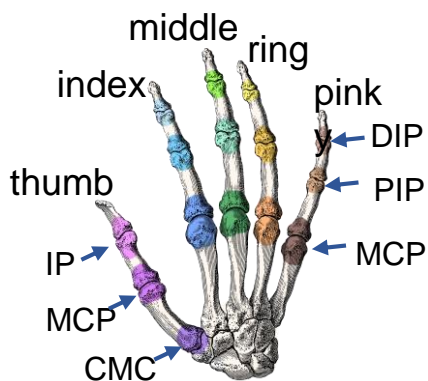
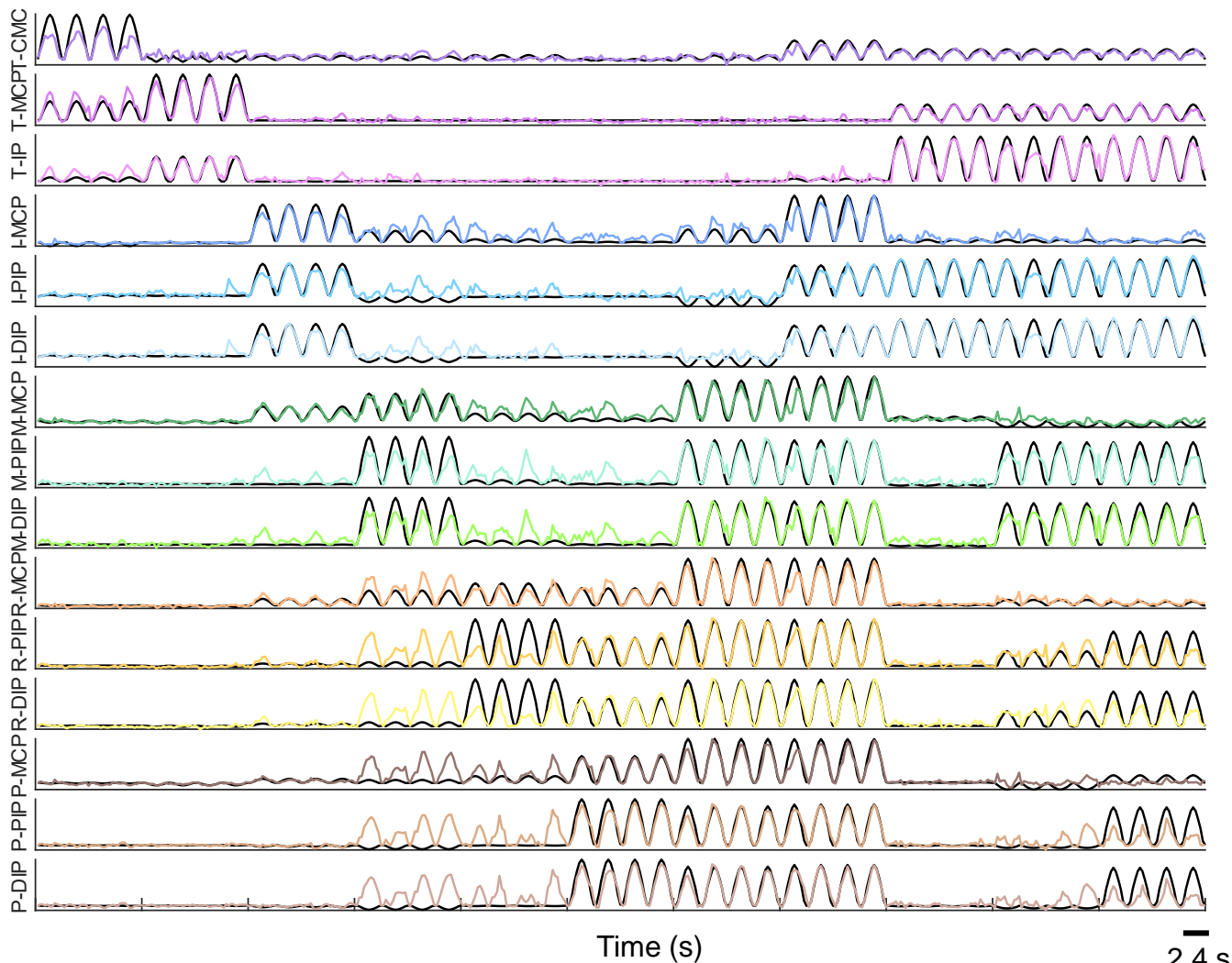


Joint angles (sd)



— Real joint trajectory

