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# 1. algorithm

#include <algorithm> #include <numeric>

Algo	Params	Funcion
sort, stable_sort	f, l	ordena el intervalo
nth_element	f, nth, l	void ordena el n-esimo, y
		particiona el resto
fill, fill_n	f, l / n, elem	void llena [f, l) o [f,
		f+n) con elem
lower_bound, upper_bound	f, l, elem	it al primer / ultimo donde se
		puede insertar elem para que
		quede ordenada
binary_search	f, l, elem	bool esta elem en [f, l)
copy	f, l, resul	hace resul+ $i=f+i \ \forall i$
find, find_if, find_first_of	f, l, elem	$it$ encuentra i $\in$ [f,l) tq. i=elem,
	/ pred / f2, l2	$\operatorname{pred}(i), i \in [f2, l2)$
count, count_if	f, l, elem/pred	cuenta elem, pred(i)
search	f, l, f2, l2	busca $[f2,l2) \in [f,l)$
replace, replace_if	f, l, old	cambia old / pred(i) por new
	/ pred, new	
reverse	f, 1	da vuelta
partition, stable_partition	f, l, pred	pred(i) ad, !pred(i) atras
min_element, max_element	f, l, [comp]	$it \min, \max de [f,l]$
$lexicographical\_compare$	f1,l1,f2,l2	bool con [f1,l1];[f2,l2]
$next/prev\_permutation$	f,l	deja en [f,l) la perm sig, ant
set_intersection,	f1, l1, f2, l2, res	$[res, \ldots)$ la op. de conj
set_difference, set_union,		
set_symmetric_difference,		
push_heap, pop_heap,	f, l, e / e /	mete/saca e en heap [f,l),
make_heap		hace un heap de [f,l)
is_heap	f,l	bool es [f,l) un heap
accumulate	f,l,i,[op]	$T = \sum /\text{oper de [f,l)}$
$inner\_product$	f1, l1, f2, i	$T = i + [f1, 11) \cdot [f2, \dots)$
partial_sum	f, l, r, [op]	$r+i = \sum /oper de [f,f+i] \forall i \in [f,l)$
_builtin_ffs	unsigned int	Pos. del primer 1 desde la derecha
_builtin_clz	unsigned int	Cant. de ceros desde la izquierda.
_builtin_ctz	unsigned int	Cant. de ceros desde la derecha.
_builtin_popcount	unsigned int	Cant. de 1's en x.
builtin_parity	unsigned int	1 si x es par, 0 si es impar.
	ambiginea inte	I si ii se per, e si se iliper.

#### 2. Estructuras

#### 2.1. Prefix table

```
template<typename T>
class PTable {
    vec<T> pt;
    T opr (T a, T b) { return a + b; }
    T inv (T a, T b) { return a - b; }
    public:
    PTable (vec<T>& a) {
        pt.resize(a.size());
        rep(i,a.size()) pt[i] = !i ? a[i] : opr(pt[i-1], a[i]);
    }
    T q (int i, int j) { return (--i < 0) ? pt[j] : inv(pt[j], pt[i]); }
};</pre>
```

#### 2.2. Sparse table

Operacion asociativa idempotente.

```
template<typename T>
   class STable {
       vec<vec<T>> st;
3
       T op (T a, T b) { return min(a,b); }
4
       public:
       STable (vec<T>& a) {
6
           st.resize(20, vec<T>(a.size()));
7
           st[0] = a; scn(w,1,19) scn(i,0,a.size()-(1<< w))
8
                st[w][i] = op(st[w-1][i], st[w-1][i+(1<<(w-1))]);
9
       }
10
       Tq(int i, int j) {
11
           int w = log2fl(j - i + 1);
12
           return op(st[w][i], st[w][j - (1 << w) + 1]);
13
       }
14
<sub>15</sub> };
```

#### 2.3. Segment tree

```
const int MAXN = 1<<20; // ~1e6
long long ST[2*MAXN];
</pre>
```

```
5 long long querie(int nodo, int left, int right, int a, int b) {
       if (left >= b || right <= a) return 0;
       if (left >= a && right <= b) return ST[nodo];</pre>
       int m = (left + right) / 2;
       long long q1 = querie(nodo*2,left,m,a,b);
       long long q2 = querie(nodo*2+1,m,right,a,b);
       return q1 + q2;
11
12
   void update(int p, long long val) {
       ST[p] = val;
       for (p = p/2; p > 0; p /= 2) ST[p] = op(ST[p*2], ST[p*2+1]);
15
16 }
      Disjiont Set Union
1 | struct DSU {
       vec<int> p, w; int nc;
2
       DSU (int n) { nc = n; p.resize(n); w.resize(n); rep(i,n) { p[i] = i,
            w[i] = 1: \}
       int get (int x) { return p[x] == x ? x : p[x] = get(p[x]); }
4
       void join (int x, int y) {
           x = get(x), y = get(y);
           if (x == y) return;
           if (w[x] > w[y]) swap(x,y);
           p[x] = y, w[y] += w[x];
9
10
       bool same (int x, int y) { return get(x) == get(y); }
11
<sub>12</sub> | };
      Algos
     Búsqueda Binaria (discreta)
void dbisect (i64& i, i64& j, bool (*pred)(i64)) {
       while (!(i + 1 == j)) {
2
           i64 m = i + (j - i) / 2;
3
           pred(m) ? j = m : i = m;
4
       }
5
6
  pair<bool, i64> dfirsttrue (i64 i, i64 j, bool (*pred)(i64)) {
       dbisect(i, j, pred);
       if (pred(i)) return mp(true, i);
9
```

if (pred(j)) return mp(true, j);

10

```
return mp(false, -1L);

pair<bool, i64> dlastfalse (i64 i, i64 j, bool (*pred)(i64)) {
    dbisect(i, j, pred);
    if (!pred(j)) return mp(true, j);
    if (!pred(i)) return mp(true, i);
    return mp(false, -1L);
}
```

# 4. Strings

### 5. Geometria

#### 6. Math

#### 6.1. Identidades

```
\begin{split} \sum_{i=0}^{n} \binom{n}{i} &= 2^n \\ \sum_{i=0}^{n} i \binom{n}{i} &= n * 2^{n-1} \\ \sum_{i=m}^{n} i &= \frac{n(n+1)}{2} - \frac{m(m-1)}{2} = \frac{(n+1-m)(n+m)}{2} \\ \sum_{i=0}^{n} i &= \sum_{i=1}^{n} i = \frac{n(n+1)}{2} \\ \sum_{i=0}^{n} i^2 &= \frac{n(n+1)(2n+1)}{6} &= \frac{n^3}{3} + \frac{n^2}{2} + \frac{n}{6} \\ \sum_{i=0}^{n} i(i-1) &= \frac{8}{6} (\frac{n}{2})(\frac{n}{2}+1)(n+1) \text{ (doubles)} \rightarrow \text{Sino ver caso impar y par} \\ \sum_{i=0}^{n} i^3 &= \left(\frac{n(n+1)}{2}\right)^2 &= \frac{n^4}{4} + \frac{n^3}{2} + \frac{n^2}{4} = \left[\sum_{i=1}^{n} i\right]^2 \\ \sum_{i=0}^{n} i^4 &= \frac{n(n+1)(2n+1)(3n^2+3n-1)}{30} &= \frac{n^5}{5} + \frac{n^4}{2} + \frac{n^3}{3} - \frac{n}{30} \\ \sum_{i=0}^{n} i^p &= \frac{(n+1)^{p+1}}{p+1} + \sum_{k=1}^{p} \frac{B_k}{p-k+1} \binom{p}{k}(n+1)^{p-k+1} \\ r &= e - v + k + 1 \end{split} Teorema de Pick: (Area, puntos interiores y puntos en el borde) A = I + \frac{B}{2} - 1
```

#### 6.2. Criba

#### 7. Grafos

#### 7.1. Toposort

```
1 // Metodo 1: Flood fill con un reverse al final
   // Facil
   int topovisit[maxn]; vector<int> topoorder;
   void topodfs (int u) {
       topovisit[u] = 1;
       for (int v : adj[u]) if (!topovisit[v]) {
           topodfs(v); topoorder.push_back(u);
8
9
   void toposort (void) {
       forf(u,0,n) if(!topovisit[u]) topodfs(u);
       reverse(topoorder.begin(), topoorder.end());
12
13
   // Metodo 2: Basado en BFS;
   // priority_queue permite priorizar entre vertices con mismo nivel
       topologico
   int indegree[maxn]; vector<int> kahnsorder; void kahns () {
       priority_queue<int, vector<int>, greater<int>> pq;
       forf(u,0,n) for (int v : adj[u]) indegree[v]++;
18
       forf(u,0,n) if (!indegree[u]) pq.push(u);
19
       while (!pq.empty()) {
20
           int u = pq.top(); pq.pop(); kahnsorder.push_back(u);
21
           for (int v : adj[u]) { indegree[v]--; if (!indegree[v]) pq.push(
22
               v); }
23
24 }
```

#### 7.2. Componentes fuertemente conexas

```
const int maxn = int(5e5+1);
int n, m; vector<int> adj[maxn];

deque<int> kosaorder; int kosavisit[maxn];
void kosajaru1 (int u) { kosavisit[u] = 1; for (int v : adj[u]) if (! kosavisit[v]) kosajaru1(v); kosaorder.push_front(u); }
vector<int> tadj[maxn]; void kosajaru2 (void) { forf(u,0,n) for (int v : adj[u]) tadj[v].push_back(u); }
int kosaroot[maxn]; vector<vector<int>> kosacomp;
void kosajaru3 (int u, int r) { kosavisit[u] = 1; kosacomp.back().
```

```
push_back(u); kosaroot[u] = r; for (int v : tadj[u]) if (!kosavisit[
       v]) kosajaru3(v, r); }
  vector<int> adjscc[maxn]; int aristas[maxn]; void kosajaru (void) {
       forf(u,0,n) if (!kosavisit[u]) kosajaru1(u);
      kosajaru2(); memset(kosavisit, 0, maxn*sizeof(int));
11
      for (int u : kosaorder) if(!kosavisit[u]) { kosacomp.push_back({});
12
           kosajaru3(u, u); }
       memset(aristas, -1, sizeof(aristas));
13
       for (auto comp : kosacomp) for (int u : comp) for (int v : adj[u]) {
14
           int ru = kosaroot[u], rv = kosaroot[v];
15
           if (ru != rv && aristas[rv] != ru) aristas[rv] = ru, adjscc[ru].
16
               push_back(rv);
       }
17
18
```

#### 7.3. Puentes y puntos de articulación

```
const int maxn = int(1e5+1);
  int n, m; vector<int> adj[maxn];
   vector<pair<int, int>> bridges; vector<int> arts;
  int dfsdt[maxn], dfslow[maxn], dfsparent[maxn], dfstime, dfsroot,
       rootchildren, isart[maxn];
  void artdfs (int u) { dfslow[u] = dfsdt[u] = ++dfstime; for (int v :
       adj[u]) {
           if (!dfsdt[v]) {
7
               dfsparent[v] = u; if (u == dfsroot) ++rootchildren; artdfs(v
8
                   );
               if (dfslow[v] >= dfsdt[u]) isart[u] = 1;
9
               if (dfslow[v] > dfsdt[u]) bridges.push_back({u,v});
10
               dfslow[u] = min(dfslow[u], dfslow[v]);
11
           } else if (v != dfsparent[u]) dfslow[u] = min(dfslow[u], dfsdt[v
12
               ]);
       }
13
14
   void getarts (void) { forf(u,0,n) dfsparent[u] = -1;
15
       forf(u,0,n) { if (!dfsdt[u]) { dfsroot = u; rootchildren = 0; artdfs
16
           (u); isart[dfsroot] = (rootchildren > 1); } }
      forf(u,0,n) if (isart[u]) arts.push_back(u);
17
18 }
```

#### 8. Network Flow

# 9. Template

```
#include <bits/stdc++.h>
   using namespace std;
3 using i64 = int64_t;
   const int MAXN = 5e5;
   const i64 INF = LLONG_MAX;
   #define endl '\n'
   #define rep(i,N) for (int i = 0; i < int(N); i++)</pre>
   #define scn(k,i,j) for (int k = int(i); k \le int(j); k++)
   #define forall(it,v) for(auto it = v.begin(); it != v.end(); it++)
   #define printall(v) forall(x,v){cout << *x << " ";} cout << endl</pre>
   #define vec vector
   #define pb push_back
#define mp make_pair
   #define printpair(p) cout << "(" << p.fst << ", " << p.snd << ")" <<
       endl
   #define fst first
   #define snd second
   #define log2fl(x) (x ? 63 - _builtin_clzll(x) : -1)
   typedef vec<vec<int>> adj;
   typedef vec<vec<pair<int,i64> > wadj;
20
   int main (void) {
       ios::sync_with_stdio(0); cin.tie(0);
22
23
       // :)
24
25
       return 0;
26
27 }
```

## 10. Ayudamemoria

#### Compilar y correr

```
// Makefile
CPPFLAGS = -std=c++20 -00 -Wall -g
CC = g++
// comp.sh: compilar $1 y mostrar primeras $2 lineas de error
rm -f $1
```

```
clear
make $1 2>&1 | head -$2

// run.sh: correr $1 con $2 como input
rm -f $1
clear
make $1 && ./$1 < $2</pre>
```